

# Geometric models for noncommutative algebras

Fall 2025, week 1

## Introduction

Two main directions in this course:

(I)

### Symmetries

| geometry  | algebra   |
|---|---|
| Lie group $G$<br>left invariant<br><u>vector fields on <math>G</math></u><br>or $T_e G$ <small>first-order differential operators</small> | ↪ Lie algebra $\mathfrak{g}$<br>vec. sp. with bilinear map<br>$[\cdot, \cdot] : \mathfrak{g} \times \mathfrak{g} \rightarrow \mathfrak{g}$<br>s.t. .... |
| left invariant differential operators on $G$  | universal enveloping algebra $U(\mathfrak{g})$  |

We also can weaker symmetries:

Lie groupoid  $\mathcal{G}$  | ↪ Lie algebroid  $A$

left invariant vector fields on  $\mathfrak{g}$

left invariant differential operators on  $\mathfrak{g}$

vector bundle  $A$  with a Lie bracket on  $\Gamma(A)$  s.t. ...  
global sections

universal enveloping algebra  $\mathcal{U}(A)$  of  $A$

(II)

spaces and algebra

geometry

algebra

manifold  $M$

smooth map  $N \rightarrow M$

vector field on  $M$

vector bundle over  $M$

Lie algebroid  $A$

In particular,

Lie alg  $\mathfrak{g}$

differential graded manifold  $(M, \mathfrak{g})$

function alg  $C^\infty(M)$

alg morphism  $C^\infty(M) \rightarrow C^\infty(N)$

derivation of  $C^\infty(M)$

$X: A \rightarrow A$  ,  $X(ab) = X(a)b + aX(b)$

projective  $C^\infty(M)$ -module

Chevalley-Eilenberg dg alg.

$(\Gamma(\wedge^* A^*), d_{CE})$

ref:  $(\wedge^* \mathfrak{g}^*, d_{CE})$

search for Lie alg cohomology

dg alg.  $(C^\infty(M), Q)$

# Lie algebras and universal enveloping alg

## Preliminaries: tensor product

Let  $V, W$  be vector spaces over a field  $k$ . The tensor product is the vector space

$$V \otimes W = k^{(V \times W)} / R$$

where

$k^{(V \times W)}$  = the vector space freely generated by the set

$$V \times W$$

$$= \left\{ \sum_{(x,y) \in V \times W} a_{(x,y)} \cdot (x,y) \mid \begin{array}{l} a_{(x,y)} \in k \\ a_{(x,y)} = 0 \\ \text{except finite} \\ (x,y) \in V \times W \end{array} \right\}$$

and  $R$  is the subspace of  $k^{(V \times W)}$

spanned by

$$(v_1 + v_2, w) - (v_1, w) - (v_2, w) \quad (v, w_1 + w_2) - (v, w_1) - (v, w_2) \quad (v, w) + (v, w) - (v, w)$$

$$(x_1 + x_2, y) = (x_1, y) + (x_2, y),$$

$$(x, y_1 + y_2) = (x, y_1) + (x, y_2),$$

$$(c \cdot x, y) = c \cdot (x, y)$$

$$(x, c \cdot y) = c \cdot (x, y)$$

$$\begin{aligned} & \text{... } x_1, x_2 \in V \\ & y_1, y_2 \in W \\ & c \in K \end{aligned}$$

## Remark

① An arbitrary element in  $V \otimes W$  is of the form  
$$\sum_{i=1}^k \underbrace{x_i \otimes y_i}_{\text{...}} = [x_i, y_i] \in K^{(k \times m)} / R$$

② Furthermore,

$$(ax_1 + bx_2) \otimes y = a \cdot x_1 \otimes y + b \cdot x_2 \otimes y$$

$$x \otimes (ay_1 + by_2) = a \cdot x \otimes y_1 + b \cdot x \otimes y_2$$

$$(a \cdot x) \otimes y = a \cdot (x \otimes y) = x \otimes (a \cdot y)$$

③ If  $v_1, \dots, v_n$  form a basis for  $V$   
 $w_1, \dots, w_m$  " basis for  $W$ ,

then

$$v_1 \otimes w_1, v_1 \otimes w_2, \dots, v_1 \otimes w_m,$$

$$v_2 \otimes w_1, \dots, v_2 \otimes w_m$$

$\vdots$

$\vdots$

$$v_1 \otimes w_1, \dots, \dots, v_n \otimes w_m$$

form a basis  $V \otimes W$ .

$$\textcircled{+} \left\{ \begin{array}{l} \text{finite-dimensional} \\ \text{vector spaces} \end{array} \right\} \longleftrightarrow \mathbb{Z}_{\geq 0}$$

isomorphism

$$V \longleftrightarrow \dim V$$

For  $m, n \in \mathbb{Z}_{\geq 0}$ ,

$$V \oplus W \longleftrightarrow \begin{array}{l} n+m \\ \dim(V \oplus W) = \\ \dim(V) + \dim(W) \end{array}$$

$$V \otimes W \longleftrightarrow \begin{array}{l} n \cdot m \\ \dim(V \otimes W) \\ = \dim(V) \cdot \dim(W) \end{array}$$

Def

Let  $V_1, \dots, V_n$  be vector spaces over  $K$ .

$$V_1 \otimes V_2 \otimes \dots \otimes V_n$$

$$\stackrel{\text{def.}}{=} \frac{K(V_1 \times V_2 \times \dots \times V_n)}{R}$$

where

$$R = \text{span} \left\{ \begin{array}{l} (V_1, V_2, \dots, V_i + V_i', \dots, V_n) \\ - (V_1, \dots, V_i, \dots, V_n) - (V_1, \dots, V_i', \dots, V_n) \\ (cV_1, \dots, cV_i, \dots, V_n) \\ - c \cdot (V_1, \dots, V_i, \dots, V_n) \end{array} \right\}$$

$V_i \in V_i, \quad i=1, \dots, n$

The tensor algebra generated by a vector space  $V$  is

$$\mathbb{T}V = \bigoplus_{n=0}^{\infty} \overbrace{V \otimes V \otimes \dots \otimes V}^{n \text{ times}}$$

$\uparrow$   
 vector space

$\Rightarrow$  we have scalar product

and addition

which is equipped with the multiplication

$$(v_1 \otimes \dots \otimes v_i) \cdot (v_{i+1} \otimes \dots \otimes v_{i+j})$$

$$= v_1 \otimes \dots \otimes v_i \otimes v_{i+1} \otimes \dots \otimes v_{i+j}$$

$$\uparrow \\ v^{(i+j)} \in \mathbb{I}V$$

## Lie algebra

Suppose  $k = \mathbb{R}$  or  $\mathbb{C}$  for convenience.

Def.

A Lie algebra is a vector space  $\mathfrak{g}$  together with bilinear map

$$[ , ] : \mathfrak{g} \times \mathfrak{g} \rightarrow \mathfrak{g}$$

called the Lie bracket, satisfying

(i) anticommutativity:

$$[x, y] = -[y, x]$$

ii) Jacobi identity:

$$[x, [y, z]] + [y, [z, x]] + [z, [x, y]] = 0$$

$$\forall x, y, z \in \mathfrak{g}$$

Remark

① The binary operation  $[\cdot, \cdot]$  is almost never associative

$$[x, [y, z]] = [x \cdot (y \cdot z)] \neq [(x \cdot y) \cdot z]$$

② Jacobi identity  $\Leftrightarrow$

$[x, -]$  is a derivation  $\forall x \in \mathfrak{g}$ ,

i.e.

$$[x, [y, z]] = [x, y] \cdot z + \overbrace{[y, [x, z]]}^{\text{deriv}}$$

Example Let  $A$  be an associative algebra.

①  $(A, [\cdot, \cdot])$ ,  $[a, b] := a \cdot b - b \cdot a$ , <sup>Commutator</sup>  
is a Lie algebra (exercise)

(1.5) Since  $\text{End}_k A = \{f: A \rightarrow A, f \text{ is linear}\}$   
is an alg. w.r.t. composition  $\circ$ ,  
it can be regarded as a Lie alg. by ①

②  $\text{Der}(A) := \{\text{derivations of } A\}$   
 $= \left\{ f \in \text{End}(A) \mid f(ab) = f(a)b + a f(b) \right\}$   
is a Lie subalgebra of  $\text{End}(A)$ .

To show this claim, check:

$\forall f, g \in \text{Der}(A)$ ,

$$[f, g] = f \circ g - g \circ f$$

is still in  $\text{Der}(A)$ , i.e.

$$[f, g](ab) \stackrel{\text{check}}{=} [f, g](a) \cdot b \quad \underline{\text{exer}}$$

$$+ a \cdot [f, g](cb)$$

$$\textcircled{3} \quad \mathfrak{sl}_2(\mathbb{C}) = \{ X \in M_2(\mathbb{C}) \mid \text{tr}(X) = 0 \}$$

$\nwarrow$   $\dim \mathfrak{sl}_2(\mathbb{C}) = 3$

In fact,

$$E = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, \quad F = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix},$$

$$H = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

form a basis for  $\mathfrak{sl}_2(\mathbb{C})$ .

The Lie bracket is determined by

$$[E, F] = E \cdot F - F \cdot E$$

$$= \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} - \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$$

$$= \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = H$$

$$[H, F] = -2F$$

$$[H, E] = 2E$$

exer

Prove or disprove:

$$\dim \mathfrak{g} \Rightarrow [X, Y] = 0$$

"

$$\forall X, Y \in \mathfrak{g}$$

$LH, E, J = \dots$

Def

Let  $\mathfrak{g}$  be a Lie alg.

The universal enveloping algebra  $U(\mathfrak{g})$  of  $\mathfrak{g}$  is the associative algebra

$$U(\mathfrak{g}) = \frac{\mathbb{T}\mathfrak{g}}{\langle \underbrace{x \otimes y - y \otimes x - [x, y]}_{x, y \in \mathfrak{g}} \rangle}$$

the ideal generated by all the elements of the form

$$x \otimes y - y \otimes x - [x, y] \\ x, y \in \mathfrak{g}$$

Remark

$\mathfrak{g}$  can be considered as a subspace

$$\text{of } U(\mathfrak{g}) : \mathfrak{g} = \mathfrak{g}^{\otimes 1} \hookrightarrow \mathbb{T}\mathfrak{g} \rightarrow U(\mathfrak{g})$$

Furthermore,

$$[u, v] = u \cdot v - v \cdot u$$

$$(\mathfrak{g}, [\cdot, \cdot]) \quad \wedge \quad (\mathcal{U}(\mathfrak{g}), \underbrace{[\cdot, \cdot]}_{\downarrow})$$

is a Lie subalgebra of

since, by the construction of  $\mathcal{U}(\mathfrak{g})$ ,

$$\begin{array}{c} \mathfrak{g} \\ \hookrightarrow \\ x \end{array} \cdot \begin{array}{c} \mathfrak{g} \\ \hookrightarrow \\ y \end{array} - y \cdot x = [x, y] \leftarrow \text{in } \mathcal{U}(\mathfrak{g})$$

Prop (Universal property for  $\mathcal{U}(\mathfrak{g})$ )  
(over  $\mathbb{k}$ )

Let  $\mathfrak{g}$  be a Lie alg,  $A$  be an associative alg (over  $\mathbb{k}$ ).

If  $f: \mathfrak{g} \rightarrow A$  is a linear map s.t.

$$f([x, y]) = \underbrace{f(x) \cdot f(y) - f(y) \cdot f(x)}_{[f(x), f(y)] \text{ in } A}$$

then  $\exists!$  algebra morphism

$$\tilde{f}: \mathcal{U}(\mathfrak{g}) \rightarrow A$$

s.t.  $\tilde{f} \circ \varphi = f$ , where  $\varphi$  is the map

$$\mathfrak{g} \hookrightarrow \mathbb{T}\mathfrak{g} \xrightarrow{\varphi} \mathcal{U}(\mathfrak{g})$$

$$\begin{array}{ccc} \mathfrak{g} & \xrightarrow{\varphi} & \mathcal{U}(\mathfrak{g}) \\ & \searrow \cong & \downarrow \exists! \tilde{f} \\ & \text{Lie alg mor} & \text{Alg mor} \end{array}$$

exer: prove the proposition

## Remarks

① A representation of a Lie alg  $\mathfrak{g}$  is a vector space  $V$  together with a Lie alg mor

$$\phi: \mathfrak{g} \rightarrow \text{Commutator} \downarrow \text{End}(V)$$

e.g. For  $\mathfrak{sl}_2(\mathbb{C})$ , consider  $V = \mathbb{C}^2$

$$\phi: \mathfrak{sl}_2(\mathbb{C}) \rightarrow \text{End}(\mathbb{C}^2)$$

$\begin{matrix} \mathfrak{e} \\ \times \end{matrix}$

$$\phi(X)(\vec{v}) = X \cdot \vec{v}$$

idea:  $V$  has a  $\mathfrak{g}$ -symmetry

② A representation of an associative alg.  $A$

is a vector space  $V$  together with  
 an alg mor

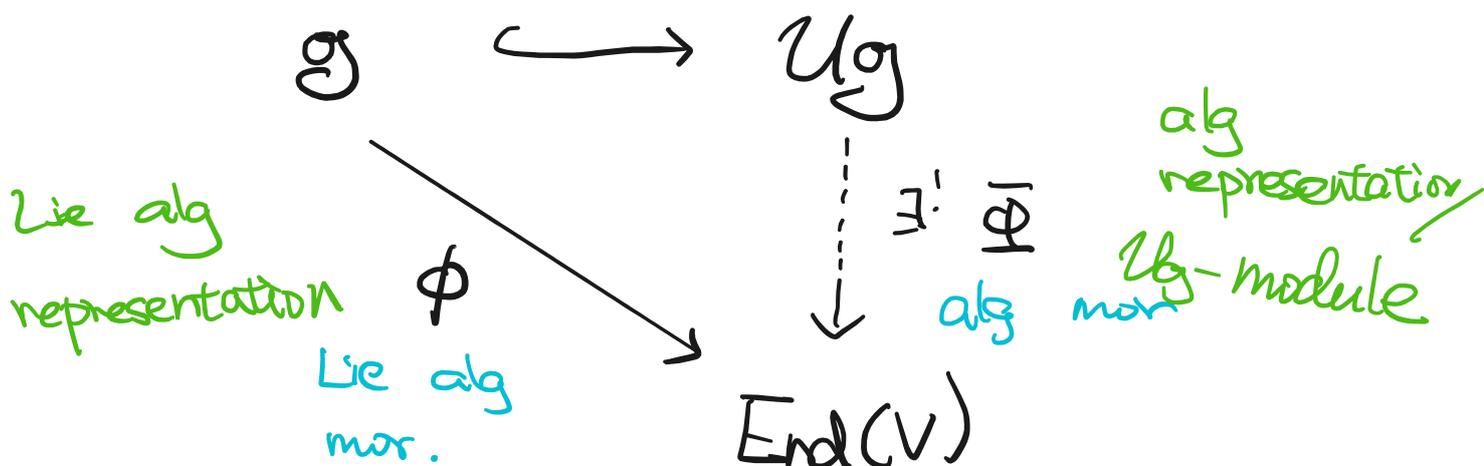
$$\Phi: A \longrightarrow \text{End}(V)$$

Composition

$\Leftrightarrow V$  is a module over  $A$ .

③ By the universal property,  
 a representation of  $\mathfrak{g}$  (as a Lie alg.)

$\Leftrightarrow$   
 a " of  $U(\mathfrak{g})$  (as an alg.)



Matrix groups and their Lie algebras  
 (and actions)

In general, we use <sup>commutative</sup> groups to study symmetries.

### Example

Consider  $\mathbb{Z}_2 = \{\pm 1\} \subseteq \mathbb{R}$

A function  $f: \mathbb{R} \rightarrow \mathbb{R}$  is even iff  $f$  is " $\mathbb{Z}_2$ -invariant", i.e.

$$f(g \cdot x) = f(x) \quad \forall g \in \mathbb{Z}_2$$

$f$  is odd  $\Leftrightarrow f$  is " $\mathbb{Z}_2$ -equivariant"  
i.e.

$$f(g \cdot x) = g \cdot f(x) \quad \forall g \in \mathbb{Z}_2$$

So evenness and oddness of functions

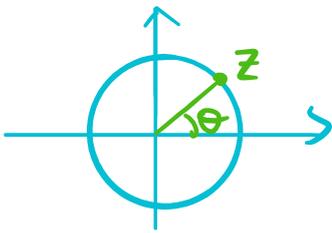
can be understood by the  $\mathbb{Z}_2$ -action on  $\mathbb{R}$

$\mathbb{Z}_2$  (or finite groups)  $\leftrightarrow$  study of discrete

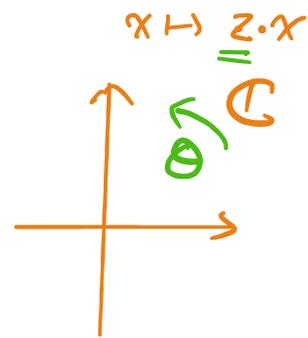
discrete  
symmetries

Lie group  $\leftrightarrow$  study of  
smooth symmetries

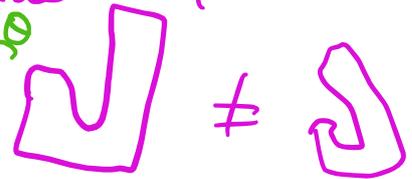
$$U(1) = \{z \in \mathbb{C} \mid |z| = 1\}$$



act  
 $\curvearrowright$



NOTE: The space



doesn't have a "nice"

$U(1)$ -action

A big success in Lie theory is:

Lie groups  $\leftrightarrow$  Lie algebras  
NOT 1-1 but almost  
 $\uparrow$  very difficult  $\uparrow$  linear algebra much easier

To avoid differential geometry,  
let's consider "matrix groups".

Here a matrix group is a closed  
subgroup of  $GL_n(\mathbb{C})$ .

$$\{A \in M_n(\mathbb{C}) \mid \det(A) \neq 0\}$$

"

$$\{ \text{invertible } n \times n \text{ matrices} \}$$

Consider  $M_n(\mathbb{C})$  as  $\mathbb{C}^{n^2} \cong \mathbb{R}^{2n^2}$   
metric space  
we have "open",  
"closed", ...

Lemma

$$\det : M_n(\mathbb{C}) \rightarrow \mathbb{C}$$

exer:

prove the lemma.

is a smooth function (in particular,  
a continuous function)

Therefore,

$$\mathbb{C} \cong \mathbb{R}^2$$

U open

$$GL_n(\mathbb{C}) = \det^{-1}(\mathbb{C} - \{0\})$$

is an open subset of  $M_n(\mathbb{C}) \cong \mathbb{R}^{2n^2}$

In particular,  $GL_n(\mathbb{C})$  is a manifold.

(in particular, a topological space)

We say  $G$  is a closed subgroup of  $GL_n(\mathbb{C})$  if

- (i)  $G$  is a closed subset of  $GL_n(\mathbb{C})$
- (ii)  $G$  is a subgroup of  $GL_n(\mathbb{C})$ .

Thm (Closed subgroup thm). in general.  
a Lie group

If  $H$  is a closed subgroup of  $GL_n(\mathbb{C})$  then  $H$  is an embedded Lie subgroup of  $G$ .

In particular, the maps

$$H \times H \rightarrow H, \quad (x, y) \mapsto x \cdot y$$

$$H \rightarrow H, \quad x \mapsto x$$

are smooth.