

Linear Algebra 12/21

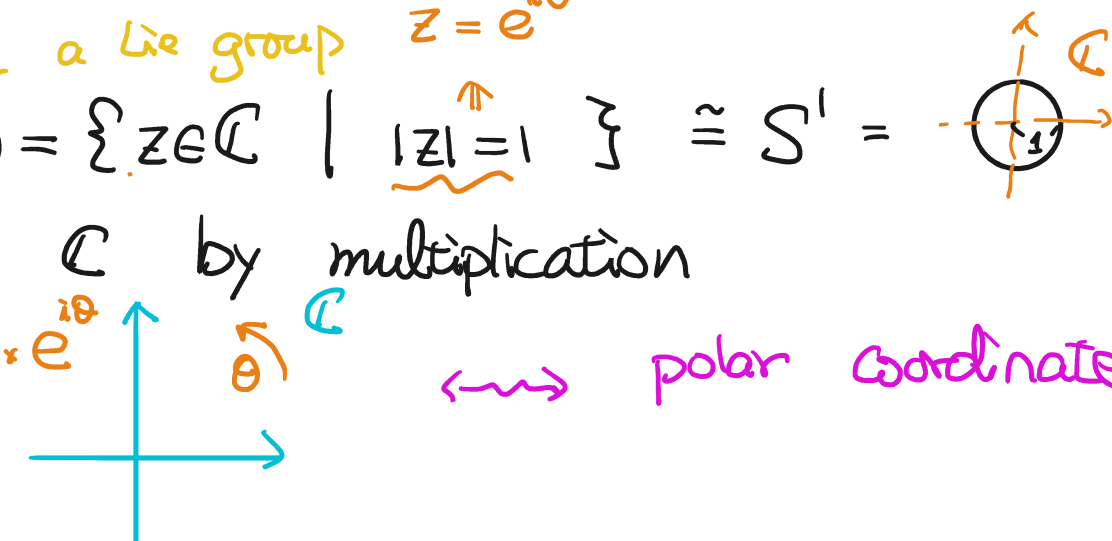
Group $\longleftrightarrow$ Symmetry

Lie group $\longleftrightarrow$ Smooth symmetry

e.g. $\underbrace{U(1)}_{\text{a Lie group}} = \{z \in \mathbb{C} \mid \underbrace{|z|=1}_{z=e^{i\theta}}\} \cong S^1 = \text{---} \bigcirc \text{---}$

acts on $\mathbb{C}$ by multiplication

$\xleftrightarrow{\text{polar coordinate}}$



Today:

Closed subgroups of $GL_n(\mathbb{C})$

A big success of Lie theory:

$\exists$ nice correspondence between

$\{ \text{Lie groups} \}$

$\longleftrightarrow$

$\{ \text{Lie algebras} \}$

vector + bilinear map
s.t. ...

...

much easier

difficult

much easier

Examples of matrix group

Regarding $M_n(\mathbb{C})$ as $\mathbb{R}^{2n^2}$ it is a metric space. Since

$$\det: M_n(\mathbb{C}) \longrightarrow \mathbb{C}$$

$$\det(a_{ij}) = \sum_{\sigma \in S_n} (-1)^\sigma a_{1\sigma(1)} \cdots a_{n\sigma(n)}$$

polynomial
(variables)
= a_{ij}

is a poly, in particular, continuous,

open in $\mathbb{C}$

$$\rightarrow \underline{GL_n(\mathbb{C})} = \det^{-1}(\underline{\mathbb{C} - \{0\}})$$

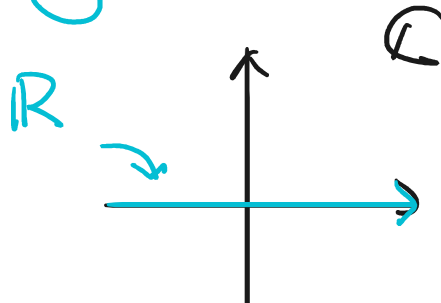
metric
space

is an open subset of $M_n(\mathbb{C})$

general linear group over $\mathbb{C}$

Example

① $\mathbb{R} \xrightarrow{\text{closed}} \mathbb{C}$



$M_n(\mathbb{R})$ is also closed in $M_n(\mathbb{C})$

$$\Rightarrow \underline{GL_n(\mathbb{R})} = \{A \in M_n(\mathbb{R}) \mid \det(A) \neq 0\}$$

subgp of $GL_n(\mathbb{C})$

$\underbrace{\quad}_{\text{is closed in } GL_n(\mathbb{C})} = \underbrace{GL_n(\mathbb{C}) \cap M_n(\mathbb{R})}_{\text{general linear group over } \mathbb{R}}$

Recall: As a subspace $GL_n(\mathbb{C}) \subseteq M_n(\mathbb{C})$, the closed subsets in $GL_n(\mathbb{C})$

$$= \{ GL_n(\mathbb{C}) \cap K \mid K \text{ is closed in } M_n(\mathbb{C}) \}$$

② The special linear group over $\mathbb{C}$ is

$$SL_n(\mathbb{C}) = \{ A \in GL_n(\mathbb{C}) \mid \det(A) = 1 \}$$

$$= GL_n(\mathbb{C}) \cap \underbrace{\det^{-1}(\{1\})}_{\substack{\subset M_n(\mathbb{C}) \\ \text{closed}}}$$

which is a closed subgroup of $GL_n(\mathbb{C})$

For $A, B \in SL_n(\mathbb{C})$,

$$\det(AB) = \det(A) \det(B)$$

$$= 1 \times 1 = 1$$

$$\Rightarrow A \cdot B \in SL_n(\mathbb{C})$$

Similarly,

$$O(n) = \{ A \in M_n(\mathbb{R}) \mid \det(A) = 1 \}$$

$$O_n(\mathbb{R}) = \{ A \in M_n(\mathbb{R}) \mid A^T = -A \}$$

$$= \det^{-1}(\{1\}) \cap M_n(\mathbb{R}) \cap GL_n(\mathbb{C})$$

is a closed subgroup of $GL_n(\mathbb{C})$ [#]

③ The unitary group of degree n is

$$U(n) = \{ A \in GL_n(\mathbb{C}) \mid \underbrace{AA^* = A^*A = I_n}_{\Leftrightarrow A^{-1} = A^*} \}$$

where A^* is the conjugate transpose of

e.g. $A = \begin{pmatrix} i & 1-i \\ 1 & 2 \end{pmatrix} \Rightarrow A^* = \begin{pmatrix} \bar{i} & \bar{1} \\ \overline{1-i} & \bar{2} \end{pmatrix}^A$

$$= \begin{pmatrix} -i & 1 \\ 1+i & 2 \end{pmatrix}$$

e.g. $U(1) = \{ \overset{\mathbb{Z}}{\parallel} \underset{\mathbb{C}}{A} \in GL(\mathbb{C}) = \mathbb{C} \setminus \{0\} \mid \overset{|z|^2}{\parallel} \bar{z}z = z\bar{z} = 1 \}$



A matrix in $U(n)$ is called a unitary matrix.

$$U(1) = \{ z \in \mathbb{C} \mid |z| = 1 \} = \{ e^{i\theta} \mid \theta \in [0, 2\pi) \}$$

NOTE $U(n)$ is the solution set of

$$AA^* - I_n = 0$$

Assume
 $\swarrow$ $A = (a_{ij})$
 $A^* = (\bar{a}_{ji})$

$$= \left(\sum_{k=1}^n a_{ik} \bar{a}_{jk} \right)_{i,j} - I_n$$

Continuous

$$U(n) = \left(\text{a continuous function} \right)^{-1}(\{0\})$$

is closed in $GL_n(\mathbb{C})$

$U(n)$ is a subgp because

$$\forall A, B \in U(n),$$

$$\begin{aligned} (AB)^* &= B^* \cdot A^* \\ &= B^{-1} \cdot A^{-1} = \underbrace{(A \cdot B)^{-1}} \end{aligned}$$

Note

$$\begin{aligned} (AB)^T &= B^T A^T \\ \overline{AB} &= \bar{A} \cdot \bar{B} \\ \Rightarrow (AB)^* &= B^* A^* \end{aligned}$$

$$\Rightarrow AB \in U(n)$$

*

④ The orthogonal group in dim n is

$$O(n) = \{ A \in M_n(\mathbb{R}) \mid A A^T = \underline{A^T A = I_n} \}$$

$$= U(n) \cap GL_n(\mathbb{R})$$

$$\dots \subset GL_n(\mathbb{R}) \subset GL_n(\mathbb{C})$$

which is also closed in $GL_n(\mathbb{C})$.

It is a subgroup because

$$\forall A, B \in O(n),$$

$$(AB)^T = B^T \cdot A^T = B^T \cdot \tilde{A} = (AB)^T$$

$$\Rightarrow AB \in O(n).$$

Remark

why? $\Uparrow$ $A^T A = I$

$$O(n) = \left\{ \text{distance-preserving linear transformations} \right\}$$

Note that

(i) $\|\vec{v}\| = \sqrt{\langle \vec{v}, \vec{v} \rangle}$, $\langle \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix}, \begin{pmatrix} y_1 \\ \vdots \\ y_n \end{pmatrix} \rangle = \sum_{i=1}^n x_i y_i$

(ii) $d(\vec{v}, \vec{w}) = \|\vec{v} - \vec{w}\|$



(iii) distance-preserving = $\langle, \rangle$ -preserving in $\mathbb{R}^n$

(iv) $\langle A\vec{v}, \vec{w} \rangle = \langle \vec{v}, A^T \vec{w} \rangle$

(v) A^T is $\langle, \rangle$ -preserving

$$\Leftrightarrow \langle A\vec{v}, A\vec{w} \rangle = \langle \vec{v}, \vec{w} \rangle$$

$$\Leftrightarrow \langle \vec{v}, A^T A \vec{w} \rangle = \langle \vec{v}, \vec{w} \rangle \quad \forall \vec{v}, \vec{w} \in \mathbb{R}^n$$

$$\Leftrightarrow A^T A = I_n$$

$a = \cos \theta$
 $b = -\sin \theta$
 $\dots$

$$\begin{pmatrix} a^2 + b^2 & ac + bd \\ ac + bd & c^2 + d^2 \end{pmatrix} = I_2$$

Case $n=2$:

$$\begin{aligned}
 O(2) &= \left\{ \begin{pmatrix} a & b \\ c & d \end{pmatrix} \mid \begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} a & c \\ b & d \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \right\} \\
 &= \left\{ \underbrace{\begin{pmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{pmatrix}}_{\det=1} \cdot \underbrace{\begin{pmatrix} \sin\theta & \cos\theta \\ \cos\theta & -\sin\theta \end{pmatrix}}_{\det=-1} \mid \theta \in \mathbb{R} \right\}
 \end{aligned}$$

rotation

rotation $\times$ reflection

$\theta=0 \Rightarrow \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$

= reflection along $x=y$

NOT connected

The special orthogonal group ^{in dim n} is

$$SO(n) = O(n) \cap SL(n)$$

$$= \{ A \in O(n) \mid \det(A) = 1 \}$$

= the connected component of $O(n)$ which contains I_n

e.g., $SO(2) = \left\{ \begin{pmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{pmatrix} \mid \theta \in \mathbb{R} \right\}$

$$\cong \{ \cos\theta + i\sin\theta \mid \theta \in \mathbb{R} \} = U(1)$$

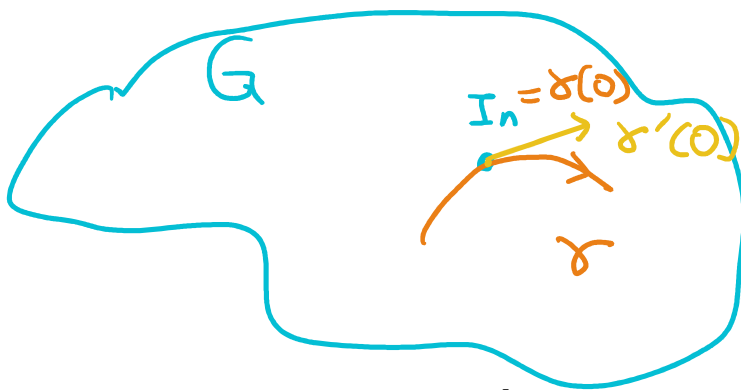
Lie algebra of a matrix group

Let G be a closed subgroup of $GL_n(\mathbb{C})$

The Lie algebra associated with G is

$$\mathfrak{g} = \text{Lie}(G) = T_{I_n} G$$

$$= \left\{ \delta'(0) \in \underbrace{M_n(\mathbb{C})}_{\substack{\dim_{\mathbb{R}} 2n^2 \\ \mathbb{R}}} \mid \begin{array}{l} \delta: (-\varepsilon, \varepsilon) \rightarrow \overset{GL_n(\mathbb{C})}{\underset{U}{G}} \\ \text{is smooth, and} \\ \delta(0) = I_n \end{array} \right\}$$



e.g. $U(1) = \{ z \in \mathbb{C} \mid |z|=1 \}$

$\mathfrak{g} = \text{Lie}(U(1))$

Lemma

$\mathfrak{g} = \text{Lie}(G)$ is a real vector subspace of $M_n(\mathbb{C}) \cong \mathbb{R}^{2n^2}$.

pf

$$(i) \quad 0 = \left(\text{constant curve at } I_n \right)' = 0$$

$$\in \mathfrak{g}$$

(ii) For $\alpha'(0), \beta'(0) \in \mathfrak{g}$,

$$\alpha'(0) + \beta'(0) = \alpha'(0) \overset{I_n}{\parallel} \beta'(0) + \alpha'(0) \overset{I_n}{\parallel} \beta'(0)$$

$$= (\alpha \cdot \beta)'(0) \in \mathfrak{g}$$

$$(-\varepsilon, \varepsilon) \rightarrow G$$

difference is speed


(iii) For $c \in \mathbb{R}$, $\delta'(0) \in \mathfrak{g}$,

$$(\delta(c \cdot t))' \Big|_{t=0} = \delta'(c \cdot 0) \cdot c$$

$$= c \cdot \delta'(0) \in \mathfrak{g} \quad \#$$

Thm

$\mathfrak{g} = \text{Lie}(G)$ is a real Lie subalgebra of $M_n(\mathbb{C})$ equipped the commutator bracket

That is, ($\mathfrak{g} \subseteq M_n(\mathbb{C})$)

$$\forall A, B \in \mathfrak{g}, \quad [A, B] = AB - BA \in \mathfrak{g}$$

pf (sketch)

For $A = \alpha'(0)$, $B = \beta'(0) \in \mathfrak{g}$, we define

$$F: (-\varepsilon, \varepsilon) \times (-\varepsilon, \varepsilon) \rightarrow G$$

$$F(s, t) = \alpha(s) \cdot \beta(t) \cdot \alpha(s)^{-1}$$

Note:

$$\begin{aligned} F(s, 0) &= \alpha(s) \cdot I_n \cdot \alpha(s)^{-1} \\ &= I_n \end{aligned}$$

The curve

↓

$$\gamma: (-\varepsilon, \varepsilon) \rightarrow \mathfrak{g}, \quad \gamma(s) = \frac{d}{dt} \Big|_{t=0} F(s, t)$$

$$= \underline{\alpha(s) \beta'(0) \alpha(s)^{-1}} \in \mathfrak{g}$$

is a smooth curve in $\mathfrak{g}$.

Since $\mathfrak{g}$ is a real vector subsp of $M_n(\mathbb{C})$, it is closed in $M_n(\mathbb{C})$, and the limit

$$\lim_{s \rightarrow 0} \frac{\gamma(s) - \gamma(0)}{s} \stackrel{\in \mathfrak{g}}{=} \gamma'(0) \stackrel{-\alpha'(0)}{=} \alpha'(0) \beta'(0) \underbrace{\alpha(0)^{-1}}_{I_n} + \underbrace{\alpha(0)}_{I_n} \beta'(0) \underbrace{(\alpha(s)^{-1})'}_{\substack{\text{recall} \\ s \rightarrow 0}}$$

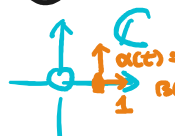
$$= \alpha'(0) \beta'(0) - \beta'(0) \alpha'(0) = AB - BA$$

is still in $\mathfrak{g}$ $\neq$

Example

$$\textcircled{1} \text{ Lie}(GL_n(\mathbb{C})) = \mathfrak{gl}_n(\mathbb{C}) = M_n(\mathbb{C})$$

e.g. $GL_1(\mathbb{C}) = \mathbb{C}^*$



$$\begin{aligned} \alpha(t) &= 1+it & \Rightarrow \alpha'(0) &= i \\ \beta(t) &= 1 & \Rightarrow \beta'(0) &= 0 \\ & \Rightarrow i, 1 \in \mathfrak{g} \\ & \Rightarrow \text{span}\{i, 1\} \subseteq \mathfrak{g} \\ & \quad \parallel \\ & \quad \mathbb{C} = M_1(\mathbb{C}) \end{aligned}$$

$$\textcircled{2} \text{ Lie}(GL_n(\mathbb{R})) = \mathfrak{gl}_n(\mathbb{R}) = M_n(\mathbb{R})$$

$$\textcircled{3} \text{ Lie}(SL_n(\mathbb{C})) = \mathfrak{sl}_n(\mathbb{C})$$

$$= \{ A \in M_n(\mathbb{C}) \mid \text{tr}(A) = 0 \}$$

why?

Recall: $SL_n(\mathbb{C}) = \{ A \in M_n(\mathbb{C}) \mid \det(A) = 1 \}$

(Lemma $\det(e^A) = e^{\text{tr} A}$)

If $\text{tr}(A) = 0$, then the curve

$$\gamma(t) = e^{tA}$$

maps into $SL_n(\mathbb{C})$ because

$$\det(\gamma(t)) = \det(e^{tA}) = e^{t \text{tr}(A)} = 1$$

And

$$\gamma'(0) = A \cdot e^{tA} \big|_{t=0} = A \in \text{Lie}(SL_n(\mathbb{C}))$$

$$\Rightarrow \mathfrak{sl}_n(\mathbb{C}) \subseteq \text{Lie}(SL_n(\mathbb{C}))$$

exer: $\supseteq$

④ $\text{Lie}(SL_n(\mathbb{R})) = \mathfrak{sl}_n(\mathbb{R}) = \{ A \in M_n(\mathbb{R}) \mid \text{tr}(A) = 0 \}$

⑤ $\text{Lie}(U(n)) = \mathfrak{u}(n) = \{ A \in M_n(\mathbb{C}) \mid A + A^* = 0 \}$
 $\uparrow$
 pf: skip

$$\textcircled{6} \text{ Lie}(\text{O}(n)) = \mathfrak{o}(n) = \{A \in M_n(\mathbb{R}) \mid A + A^T = 0\}$$

$$\parallel$$

$$\text{Lie}(\text{SO}(n)) = \mathfrak{so}(n) //$$

pf

$$\text{Recall } \text{O}(n) = \{A \in M_n(\mathbb{R}) \mid A^T A = -I_n\}$$

$$\underline{\text{Lie}(\text{O}(n)) \subseteq \mathfrak{o}(n):}$$

$$\text{Let } \gamma: (-\varepsilon, \varepsilon) \rightarrow \text{O}(n), \quad \gamma(0) = I_n$$

$$\Rightarrow \gamma(t)^T \cdot \gamma(t) = -I_n$$

$$\Rightarrow \frac{d}{dt} \Big|_{t=0} (\gamma(t)^T \cdot \gamma(t)) = \frac{d}{dt} \Big|_{t=0} (-I_n) = 0$$

$$\boxed{(\gamma(t)^T)' \Big|_{t=0}} \cdot \underline{I_n} + \underline{I_n^T} \cdot \gamma'(0)$$

$$= (\gamma'(0))^T$$

$$= \gamma'(0)^T + \gamma'(0) = 0$$

$$\text{So } \gamma'(0) \in \mathfrak{o}(n)$$

$$\underline{\mathfrak{o}(n) \subseteq \text{Lie}(\text{O}(n))}$$

Lemma

$$e^{A^T} = (e^A)^T$$

For $A \in \mathcal{O}(n)$, i.e. $A^T = -A$, we consider

$$\gamma: (-\varepsilon, \varepsilon) \rightarrow M_n(\mathbb{R}), \quad \gamma(t) = e^{tA}$$

$$\begin{aligned} \Rightarrow \gamma(t)^T &= (e^{tA})^T = e^{t \cdot A^T} = e^{-tA} \\ &= (e^{tA})^{-1} = \gamma(t)^{-1} \end{aligned}$$

$$\text{i.e. } \gamma(t)^T \cdot \gamma(t) = I_n$$

$$\text{i.e. } \gamma(t) \in \mathcal{O}(n)$$

Furthermore,

$$\begin{aligned} \gamma'(0) &= (e^{tA})' \Big|_{t=0} = A e^{tA} \Big|_{t=0} \\ &= A \in \text{Lie}(\mathcal{O}(n)) \end{aligned}$$

#

TOPICS IN LINEAR ALGEBRA

HSUAN-YI LIAO

ABSTRACT. Lecture notes for the course “Advanced Linear Algebra” at National Tsing Hua University.

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HW11

2(a). Let $x \in \mathbb{R}$

Show $\text{ev}_x: C^\infty(\mathbb{R}) \rightarrow \mathbb{R}$, $\text{ev}_x(f) = f(x)$
is an alg morphism

pf

$$\text{ev}_x(f+g) = f(x) + g(x)$$

$$\text{ev}_x(a \cdot f) = a \cdot f(x) \quad a \in \mathbb{R}$$

$$\text{ev}_x(f \cdot g) = (f \cdot g)(x) = f(x) \cdot g(x)$$

$$\text{ev}_x(1) = 1(x) = 1$$

#

7. Let $\mathfrak{g}$ be a Lie alg.

Construct a linear $f: \boxed{S\mathfrak{g}} \rightarrow U\mathfrak{g}$

st. $f|_{S_k^*} \neq 0 \quad \forall k$

$\equiv \frac{1}{k!} \langle x \otimes y - y \otimes x \rangle$

sol

Define

pbw: $S\mathfrak{g} \rightarrow U\mathfrak{g}$

by

$$\text{pbw}(X_1 \otimes \dots \otimes X_k) = \frac{1}{k!} \sum_{\sigma \in S_k} X_{\sigma(1)} \cdot X_{\sigma(2)} \cdots X_{\sigma(k)}$$

well-defined #

Details: $\underbrace{k}_{\sigma_1 \cdots \sigma_k} (X_1, \dots, X_k)$ $\searrow$ multilinear

$\Uparrow$

$$\begin{array}{ccc}
 \overset{\downarrow}{\mathfrak{g}}^{\otimes \dots \otimes \mathfrak{g}} & \xrightarrow[\exists! \text{ linear}]{\phi} & \mathcal{U}\mathfrak{g} \\
 x_1 \otimes \dots \otimes x_k & \xrightarrow{\quad} & \frac{1}{k!} \sum_{\sigma \in S_k} x_{\sigma(1)} \dots x_{\sigma(k)} \\
 \downarrow & \text{linear pbw} \nearrow \exists! & \\
 S^k \mathfrak{g} = \mathfrak{g}^{\otimes k} / \text{Span}\{x_1 \otimes \dots (x_i \otimes x_{i+1} - x_{i+1} \otimes x_i) \dots x_k\} & & \phi \nearrow \circ
 \end{array}$$