

Linear Algebra 12/7

An (associative) algebra has 3 operations

\hat{A} over R

R -module (i) addition
 (ii) scalar multiplication
 (iii) multiplication

ring

st.

$$a \cdot (xy) = (a \cdot x)y \quad \forall a \in R, x, y \in A$$

Example (Tensor algebra)

$$TV = \bigoplus_{k=0}^{\infty} \underbrace{V \otimes \dots \otimes V}_k \quad (V^{\otimes 0} = \mathbb{k})$$

vector space over \mathbb{k}

with the multiplication characterized by

$$\begin{aligned}
 & \underbrace{(\vec{v}_1 \otimes \dots \otimes \vec{v}_k)}_{\substack{\in V^{\otimes k} \\ \downarrow \\ \text{usually denoted} \\ \text{by } \otimes}} \cdot \underbrace{(\vec{v}_{k+1} \otimes \dots \otimes \vec{v}_{k+l})}_{\in V^{\otimes l}} \\
 &= \vec{v}_1 \otimes \dots \otimes \vec{v}_k \otimes \vec{v}_{k+1} \otimes \dots \otimes \vec{v}_{k+l} \in V^{\otimes k+l}
 \end{aligned}$$

Recall

If N is a submodule of M , then we have the quotient module $M/N \leftarrow$ also a module

If we want to have alg str on M/N , we shall require the algebra to be 1

we should require the denominator to be an ideal, I , i.e., \hat{N}
 (two-sided)

- I is a submodule of A

- $\forall x \in A, \forall y \in I,$

$$xy \in I \quad \text{and} \quad yx \in I$$

In this case, one has a natural alg str on A/I .

For a subset $S \subseteq A$, we denote by $\langle S \rangle$ the ideal generated by S .

Example

$$\textcircled{1} \quad SV = TV / \langle \{x \otimes y - y \otimes x \mid x, y \in V\} \rangle$$

$x \otimes y - y \otimes x = 0$
 \uparrow

is called the symmetric alg on V .

The multiplication is denoted by \odot $(x \wedge y) \wedge (z \wedge w) = (z \wedge w) \wedge (x \wedge y)$

$$\textcircled{2} \quad \wedge V = TV / \langle \{x \otimes y + y \otimes x \mid x, y \in V\} \rangle$$

$\Rightarrow x \wedge y + y \wedge x = 0$
 $x, y \in V$

is called the exterior alg on V

The multiplication is denoted by \wedge

Lie algebra

Def

A Lie algebra \mathfrak{g} is a vector space \mathfrak{g} together with a bilinear map

$$[-, -]: \mathfrak{g} \times \mathfrak{g} \rightarrow \mathfrak{g}$$

called the Lie bracket s.t.

$$(i) \quad [x, y] = -[y, x] \quad \forall x, y \in \mathfrak{g}$$

(ii) (Jacobi identity)

$$[x, [y, z]] = [[x, y], z] + [y, [x, z]]$$

or equivalently,

$$[x, [y, z]] + [y, [z, x]] + [z, [x, y]] = 0$$

Example Let A be an alg over k

① The commutator

$$[x, y] = xy - yx, \quad x, y \in A$$

is a Lie bracket on A .

$(A, [,])$ is a Lie alg.

② The derivations of A form a

Lie alg. $\text{Der}(A) = \{ \text{derivations of } A \}$

Here a derivation X is a k -linear map $X: A \rightarrow A$ s.t.

$$X(ab) = X(a)b + aX(b)$$

e.g. $\frac{d}{dx}$ is a derivation of $C^\infty(\mathbb{R})$

For $X, Y \in \text{Der}(A)$.

$$[X, Y] := X \circ Y - Y \circ X$$

Q: Is $[X, Y] \in \text{Der}(A)$?

check

$$[X, Y](ab) = X(Y(ab)) - Y(X(ab))$$

$$= X(Y(a)b + aY(b))$$

$$- Y(X(a)b + aX(b))$$

$$= X(Y(a)b) + X(aY(b)) - Y(X(a)b) - Y(aX(b))$$

$$= \underbrace{X(Y(a)b)}_{[X, Y]} + \underbrace{Y(a)X(b)}_{[X, Y]} + \underbrace{X(a)Y(b)}_{[X, Y]} + aX(Y(b)) - \underbrace{Y(X(a)b)}_{[X, Y]} - \underbrace{X(a)Y(b)}_{[X, Y]} - aY(X(b))$$

$$= (XY - YX)(a) \cdot b + a \cdot (XY - YX)(b)$$

Conclusion

$(\text{Der}(A), [\cdot, \cdot])$ is a Lie alg.

③ Since $M_n(\mathbb{k})$ is an alg,

$(M_n(\mathbb{k}), \overset{\text{Commutator}}{[\cdot, \cdot]})$ is a Lie alg.

④ $\mathfrak{sl}_2(\mathbb{C}) = \left\{ A \in M_2(\mathbb{C}) \mid \text{tr}(A) = 0 \right\}$
 $\begin{pmatrix} a & b \\ c & d \end{pmatrix}$ $\begin{matrix} \text{a+d} \\ \text{a+d} \end{matrix}$

whose Lie bracket is

$$[A, B] = AB - BA = 0$$

$$\begin{aligned} \text{tr}[A, B] &= \text{tr}(AB) - \text{tr}(BA) \\ &= \text{tr}(AB) - \text{tr}(BA) \end{aligned}$$

As a vector space,

$$\dim_{\mathbb{C}}(\mathfrak{sl}_2(\mathbb{C})) = 3$$

and

$$E = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, \quad F = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}, \quad H = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

form a basis for $\mathfrak{sl}_2(\mathbb{C})$.

The Lie bracket is determined by

$$[E, F] = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} - \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = H$$

$$[H, E] = \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} - \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} = \begin{pmatrix} 0 & -1 \\ 0 & 0 \end{pmatrix} = -E$$

$$[H, E] = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} - \begin{pmatrix} 0 & 0 \\ 0 & -1 \end{pmatrix} = \begin{pmatrix} 0 & 2 \\ 0 & 0 \end{pmatrix} = 2E$$

Def

Let \mathfrak{g} be a Lie alg. The universal enveloping algebra $U\mathfrak{g}$ of \mathfrak{g} is the quotient alg.

$$U\mathfrak{g} = T\mathfrak{g} / \langle \{x \otimes y - y \otimes x - [x, y] \mid x, y \in \mathfrak{g}\} \rangle$$

$x \cdot y - y \cdot x = [x, y]$ in $U\mathfrak{g}$
 $\forall x, y \in \mathfrak{g}$

In fact, $U\mathfrak{g}$ is endowed the map

$$\varphi: \mathfrak{g} \xrightarrow{\cong} T\mathfrak{g} \xrightarrow{\text{quotient map}} U\mathfrak{g}$$

Prop (Universal property for $U\mathfrak{g}$)

Let \mathfrak{g} be a Lie alg. A be an alg.

If $f: \mathfrak{g} \rightarrow A$ is linear with ^{the} property

$$f([x, y]) = f(x)f(y) - f(y)f(x) \quad \forall x, y \in \mathfrak{g}$$

(i.e. $f: \mathfrak{g} \rightarrow (A, [,])$ is a Lie alg mor), then

$\exists!$ alg. mor $\tilde{f}: U\mathfrak{g} \rightarrow A$ s.t. $\tilde{f} \circ \varphi = f$

$$\mathfrak{g} \xrightarrow{\varphi} U\mathfrak{g}$$

$$\forall \text{ Lie alg mor } \begin{matrix} \downarrow \\ f \end{matrix} \quad \begin{matrix} \downarrow \\ A \end{matrix} \quad \text{alg mor } \begin{matrix} \downarrow \\ \bar{f} \end{matrix}$$

Remark

A representation of a Lie alg \mathfrak{g} is a vector space V together with a Lie alg mor $\phi: \mathfrak{g} \rightarrow \text{End}(V) = \{f: V \rightarrow V \mid f \text{ linear}\}$

A representation of an alg A is

a vector space V together with an alg. mor $\Phi: A \rightarrow \text{End}(V)$.
 $a \in A, \vec{v} \in V$
 $a \cdot \vec{v} = \Phi(a)(\vec{v}) \in V$

In fact, reprn of $A = A$ -module V

The universal property of $\mathcal{U}\mathfrak{g}$ implies

representation of Lie alg \mathfrak{g} = representation of alg $\mathcal{U}\mathfrak{g}$

$$\begin{array}{ccc} \mathfrak{g} & \longleftrightarrow & \mathcal{U}\mathfrak{g} \\ & \searrow \phi & \downarrow \exists! \Phi \\ & & \text{End } V \end{array}$$

Matrix

Curves in Complex matrixes

Let $I = (-\varepsilon, \varepsilon)$ be an open interval.

and $\gamma: I \rightarrow M_{m \times n}(\mathbb{C})$.

We say γ is differentiable (resp. continuous, smooth)

if γ is differentiable (resp. continuous, smooth)

as a map $I \rightarrow \mathbb{R}^{2mn} \cong M_{m \times n}(\mathbb{C}) \cong \mathbb{C}^{mn}$

More explicitly, the curve

$$\gamma(t) = \begin{pmatrix} a_{11}(t) + i b_{11}(t) & \cdots & a_{1n}(t) + i b_{1n}(t) \\ \vdots & \ddots & \vdots \\ a_{m1}(t) + i b_{m1}(t) & \cdots & a_{mn}(t) + i b_{mn}(t) \end{pmatrix}$$

is differentiable (resp.) if all the

$a_{jk}(t)$, $b_{jk}(t)$ are differentiable (resp. ...)

If γ is differentiable, its derivative is

$$\gamma'(t) = \begin{pmatrix} a'_{11}(t) + i b'_{11}(t) & \cdots & a'_{1n}(t) + i b'_{1n}(t) \\ \vdots & \ddots & \vdots \\ a'_{m1}(t) + i b'_{m1}(t) & \cdots & a'_{mn}(t) + i b'_{mn}(t) \end{pmatrix}$$

Prop

matrix multiplication

$$\left(\alpha(t) \cdot \beta(t) \right)' = \alpha'(t) \cdot \beta(t) + \alpha(t) \cdot \beta'(t)$$

Therefore, if $\alpha: I \rightarrow \underline{GL}_n(\mathbb{C})$ and $\alpha(0) = I_n$,
 $n \times n$ invertible matrixes

then

$$\left. \frac{d}{dt} \alpha^{-1}(t) \right|_{t=0} = -\alpha'(0)$$

sketch of pf

1x1 matrix: $M_1(\mathbb{C}) \cong \mathbb{C}$

$$z_1(t) = a_1(t) + i b_1(t)$$

$$z_2(t) = a_2(t) + i b_2(t)$$

$$\Rightarrow z_1(t) \cdot z_2(t) = a_1 a_2 - b_1 b_2 + i(a_1 b_2 + b_1 a_2)$$

$$\begin{aligned} \Rightarrow (z_1 \cdot z_2)' &= \underbrace{(a_1 a_2 - b_1 b_2)'} + i \underbrace{(a_1 b_2 + b_1 a_2)'} \\ &= (a_1 a_2)' - (b_1 b_2)' = a_1' a_2 + a_1 a_2' \\ &\quad - b_1' b_2 - b_1 b_2' \end{aligned}$$

$a_1' b_2 + a_1 b_2' + b_1' a_2 + b_1 a_2'$
|| similarly

$$\begin{aligned} &= \underbrace{(a_1' a_2 + a_1 a_2')} - \underbrace{(b_1' b_2 + b_1 b_2')} \\ &\quad + i \underbrace{(a_1' b_2 + a_1 b_2')} + i \underbrace{(b_1' a_2 + b_1 a_2')} \end{aligned}$$

$$\begin{aligned} z_1' \cdot z_2 + z_1 \cdot z_2' &= (a_1' + i b_1') (a_2 + i b_2) \\ &\quad + (a_1 + i b_1) (a_2' + i b_2') \end{aligned}$$

$$= (\underline{a_1' a_2} - \underline{b_1' b_2}) + i (\underline{b_1' a_2} + \underline{a_1' b_2})$$

$$+ (\underline{a_1 a_2'} - \underline{b_1 b_2'}) + i (\underline{b_1 a_2'} + \underline{a_1 b_2'})$$

If $\gamma(t) = (z_{jk}(t))_{m \times n}$, $\tilde{\gamma}(t) = (\tilde{z}_{pq}(t))_{n \times r}$

then $= z_{jk}' \cdot \tilde{z}_{kg} + z_{jk} \cdot \tilde{z}_{kg}'$

$$(\gamma \cdot \tilde{\gamma})' = \left(\sum_k \underline{(z_{jk} \tilde{z}_{kg})'} \right)_{j,g}$$

$$= \left(\sum_k z_{jk}' \cdot \tilde{z}_{kg} \right) + \left(\sum_k z_{jk} \cdot \tilde{z}_{kg}' \right)$$

$$= \gamma' \cdot \tilde{\gamma} + \gamma \cdot \tilde{\gamma}'$$

#

If $\alpha: I \rightarrow GL_n(\mathbb{C})$, $\alpha(0) = I_n$, then

$$\alpha \cdot \alpha^{-1} = I_n.$$

$$\Rightarrow (\alpha \cdot \alpha^{-1})' = (I_n)' = O_{n \times n}$$

$$\alpha' \cdot \alpha^{-1} + \alpha \cdot (\alpha^{-1})'$$

$$\Rightarrow \alpha \cdot (\alpha^{-1})' = -\alpha' \cdot \alpha^{-1}$$

$$\Rightarrow (\alpha^{-1})' = -\alpha^{-1} \cdot \alpha' \cdot \alpha^{-1}$$

$$\Rightarrow (\alpha^{-1})'(0) = -\alpha^{-1}(0) \cdot \alpha'(0) \cdot \alpha^{-1}(0)$$

$$= -I_n^{-1} \cdot \alpha'(0) \cdot I_n^{-1} = -\alpha'(0) \quad \#$$

Prop

If $\sigma: I \rightarrow M_n(\mathbb{C})$

$$\sigma(t) = (z_{jk}(t))_{n \times n}$$

is differentiable, then

$$(\det(\sigma(t)))' = \det \begin{pmatrix} z'_{11}(t) & z_{12}(t) & \dots & z_{1n}(t) \\ \vdots & \vdots & & \vdots \\ z'_{n1}(t) & \dots & \dots & z_{nn}(t) \end{pmatrix} +$$

$$\det \begin{pmatrix} z_{11} & z'_{12} & z_{13} & \dots & z_{1n} \\ \vdots & \vdots & \vdots & \dots & \vdots \\ z_{n1} & z'_{n2} & z_{n3} & \dots & z_{nn} \end{pmatrix} + \dots + \det \begin{pmatrix} \dots & z'_{1n} \\ \vdots & \vdots \\ \dots & z'_{nn} \end{pmatrix}$$

pf

$$\det(z_{jk}) = \sum_{\sigma \in S_n} (-1)^\sigma \cdot z_{1\sigma(1)} \cdot z_{2\sigma(2)} \dots z_{n\sigma(n)}$$

$$\Rightarrow (\det(z_{jk}))' = \sum_{\sigma \in S_n} (-1)^\sigma \left(\underbrace{z_{1\sigma(1)} \cdot z_{2\sigma(2)} \dots z_{n\sigma(n)}}_{\parallel} \right)'$$

$$z'_{1\sigma(1)} \cdot z_{2\sigma(2)} \dots z_{n\sigma(n)} + \dots + z_{1\sigma(1)} \dots z_{n\sigma(n-1)} z'_{n\sigma(n)}$$

$$= \sum_{\sigma \in S_n} (-1)^\sigma \left(\dots + \sum_{\sigma \in S_n} (-1)^\sigma \dots \right)$$

$$= \det \begin{pmatrix} z'_{11} & \dots \\ \vdots & \dots \end{pmatrix} + \dots + \det \begin{pmatrix} \dots & z'_{1n} \\ \dots & \dots \end{pmatrix}$$

$\left(\begin{array}{c} \vdots \\ z_{ni} \end{array} \right)$

$\left(\begin{array}{c} \vdots \\ z_{ni} \end{array} \right) \#$

Exponential map

The exponential map $\exp: M_n(\mathbb{C}) \rightarrow \underline{GL_n(\mathbb{C})}$ is defined by the power series

$$\exp(A) = e^A = \sum_{k=0}^{\infty} \frac{1}{k!} A^k$$

which is convergent at any matrix $A \in M_n(\mathbb{C})$.

Lemma

The map $\exp: M_n(\mathbb{C}) \rightarrow M_n(\mathbb{C})$ is well-defined (ie. convergent).

$$\bar{\Phi} : V^\vee \otimes V \rightarrow \text{Hom}(V, V), \quad \bar{\Phi}(\xi \otimes w) = \langle - | \xi \rangle \cdot w$$

$$E : V^\vee \otimes V \rightarrow \mathbb{k}, \quad E(\xi \otimes v) = \xi(v)$$

(b) Show

$$\text{tr} \circ \bar{\Phi} = E \quad \otimes$$

pf $V^\vee \otimes V \rightarrow \mathbb{k}$

Since both $\text{tr} \circ \bar{\Phi}$ and E are linear, it suffices to check \otimes on a basis for $V^\vee \otimes V$

Let $\beta = \{e_1, \dots, e_n\}$ be a basis for V

$\{\hat{e}_1, \dots, \hat{e}_n\}$ be the dual basis for V^\vee

i.e. $\hat{e}_i(e_j) = \begin{cases} 1, & i=j \\ 0, & i \neq j \end{cases}$

$\Rightarrow \{\hat{e}_i \otimes e_j \mid i, j = 1, \dots, n\}$ is a basis for $V^\vee \otimes V$

$$(i) \quad (\text{tr} \circ \bar{\Phi})(\hat{e}_i \otimes e_j) = \text{tr}(\bar{\Phi}(\hat{e}_i \otimes e_j))$$

$$[\bar{\Phi}(\hat{e}_i \otimes e_j)]_{\beta} = \begin{matrix} \begin{matrix} \vdots \\ \hat{e}_i \text{th Column} \\ \vdots \end{matrix} \\ \begin{pmatrix} 0 & \vdots & 0 \\ \dots & 1 & \dots \\ 0 & \vdots & 0 \end{pmatrix} \end{matrix} \quad \begin{matrix} V \rightarrow V, e_k \mapsto \hat{e}_i(e_k) \cdot e_j \\ = \begin{cases} e_j & k=i \\ \dots & \dots \end{cases} \end{matrix}$$

$$\Rightarrow \text{tr}(\Phi(\hat{e}_i \otimes e_j)) = \begin{cases} 0 & i \neq j \\ 1 & i = j \end{cases}$$

$$(ii) \quad E(\hat{e}_i \otimes e_j) = \hat{e}_i(e_j) = \begin{cases} 0 & i \neq j \\ 1 & i = j \end{cases}$$

$$\text{So } \text{tr} \circ \Phi = E$$

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