

Linear Algebra 11/23

Remark

Let U be an open subset of $\mathbb{R}^n$.

Then

$\Omega^p(U) = \{ \text{differential } p\text{-forms on } U \}$

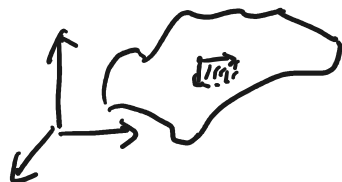
$$= C^\infty(U) \otimes_{\mathbb{R}} \wedge^p(\mathbb{R}^n)^\vee = \left\{ \sum_{i_1, \dots, i_p} f \otimes \varepsilon_{i_1} \wedge \dots \wedge \varepsilon_{i_p} \right\}$$

$U \times \wedge^p(\mathbb{R}^n)^\vee = \text{cotangent bundle}$
 $\downarrow \uparrow$
 $C^\infty(U)$

If $p = n$,

← span {det}

$$\Omega^n(U) = C^\infty(U) \otimes_{\mathbb{R}} \underline{\wedge^n(\mathbb{R}^n)^\vee}$$



Bilinear forms

V : vector space over $\mathbb{k}$, $\dim V < \infty$

Def

A bilinear form B is a bilinear map $B: V \times V \rightarrow \mathbb{k}$.

A bilinear form B is nondegenerate

if $B(\vec{v}, \vec{w}) = 0 \quad \forall \vec{w} \in V \Rightarrow \vec{v} = 0$

($\Leftrightarrow B^*: V \rightarrow V^*, \vec{v} \mapsto B(\vec{v}, -)$ is iso) $\Leftrightarrow B^*(\vec{v}) = \text{zero map}$

We say B is symmetric if

$$B(\vec{v}, \vec{w}) = B(\vec{w}, \vec{v}) \quad \forall \vec{v}, \vec{w} \in V.$$

If $k = \mathbb{C}$, we say $B: V \times V \rightarrow \mathbb{C}$ is a sesquilinear form if

- $B(\vec{u} + \vec{v}, \vec{w}) = B(\vec{u}, \vec{w}) + B(\vec{v}, \vec{w})$
 $B(\vec{u}, \vec{v} + \vec{w}) = B(\vec{u}, \vec{v}) + B(\vec{u}, \vec{w})$

- $B(\lambda \vec{u}, \vec{v}) = \overline{\lambda} B(\vec{u}, \vec{v})$
 $B(\vec{u}, \lambda \vec{v}) = \lambda B(\vec{u}, \vec{v})$

Example

① $k \times k \rightarrow k, (a, b) \mapsto ab$

is a bilinear form

(symmetric, nondegenerate)

② Inner products on real vector spaces

are symmetric nondegenerate
bilinear forms

Recall

An inner product

$$\langle \cdot, \cdot \rangle : V \times V \rightarrow \mathbb{R}$$

is a symmetric, bilinear map
s.t.

$$\langle \vec{v}, \vec{v} \rangle > 0$$

[positive definite]

$$\forall \vec{v} \neq 0.$$

nondegenerate

$$\because \langle \vec{v}, \vec{w} \rangle = 0 \quad \forall \vec{w}$$

$$\Rightarrow \langle \vec{v}, \vec{v} \rangle = 0$$

$$\Rightarrow \vec{v} = 0$$

$$(3) \quad M_{m \times n}(\mathbb{K}) \times M_{m \times n}(\mathbb{K}) \rightarrow \mathbb{K}$$

$$(A, B) \mapsto \text{tr}(A \cdot B^T)$$

is a bilinear form.

Def

A bilinear form $\omega : V \times V \rightarrow \mathbb{K}$

is skew-symmetric (or antisymmetric)

if $\omega(\vec{v}, \vec{w}) = -\omega(\vec{w}, \vec{v}) \quad \forall \vec{v}, \vec{w} \in V$

A symplectic bilinear form is a nondegenerate skew-symmetric bilinear

Example

The bilinear form $\omega: \mathbb{R}^2 \times \mathbb{R}^2 \rightarrow \mathbb{R}$

$$\omega\left(\begin{pmatrix} x_1 \\ x_2 \end{pmatrix}, \begin{pmatrix} y_1 \\ y_2 \end{pmatrix}\right) = x_1 y_2 - x_2 y_1$$

↪ Hamiltonian system in classical mechanics

is a symplectic bilinear form.

skew-symmetric:

$$\begin{aligned} \omega(\vec{y}, \vec{x}) &= y_1 x_2 - y_2 x_1 = -(x_1 y_2 - x_2 y_1) \\ &= -\omega(\vec{x}, \vec{y}) \end{aligned}$$

Remark ($\dim V = n < \infty$)

① $\{\text{symmetric bilinear forms on } V\}$

$$\cong S^2 V^V$$

$$\Rightarrow \dim = \binom{n+1}{2}$$

Recall

$$S^2 V^V \cong \text{Hom}(S^2 V, \mathbb{k})$$

$$= \{ \text{symmetric bilinear maps } \dots \}$$

$$T: V \times V \rightarrow K$$

$$(2) \quad \{ \text{skew-symmetric bilinear forms on } V \} \\ \cong \wedge^2 V^V$$

$$\Rightarrow \dim = \binom{n}{2}$$

(3) $\{ \text{nondgenerate bilinear forms} \}$
is NOT a vector space

Prop (Coordinate representation)

Let $\{e_1, \dots, e_n\}$ be a basis for V .

A bilinear linear form V is uniquely determined by

$$B_{ij} := B(e_i, e_j) \in K$$

$$\forall i, j = 1, \dots, n$$

Furthermore, if $\vec{v} = \sum_{i=1}^n a_i e_i$, $\vec{w} = \sum_{j=1}^n b_j e_j$
then

$$B(v, w) = \sum_{i,j=1}^n a_i b_j B_{ij} \quad (*)$$

$$= \begin{pmatrix} a_1 & \dots & a_n \end{pmatrix} \begin{pmatrix} B_{11} & \dots & B_{1n} \\ \vdots & & \vdots \\ B_{n1} & \dots & B_{nn} \end{pmatrix} \begin{pmatrix} b_1 \\ \vdots \\ b_n \end{pmatrix}$$

$$= (u_1 \dots u_n)_{1 \times n} \begin{pmatrix} i \\ B_{n1} \dots B_{nn} \end{pmatrix}_{n \times n} \begin{pmatrix} i \\ b_n \end{pmatrix}_{n \times 1}$$

Prop

① B is nondegenerate $\Leftrightarrow (B_{ij})$ is invertible

② B is symmetric $\Leftrightarrow (B_{ij})$ is symmetric, i.e.,
 $(B_{ij})^T = (B_{ij})$

③ B is skew-symmetric $\Leftrightarrow (B_{ij})$ is skew-symmetric
 i.e.
 $(B_{ij})^T + (B_{ij}) = 0$

pf (sketch)

①: (B_{ij}) = matrix representation of
 $B^\# : V \rightarrow V^V, \vec{v} \mapsto B(\vec{v}, -)$

② & ③: Use (*)

$$\begin{aligned}
 B(\vec{v}, \vec{w})^T &= B(\vec{v}, \vec{w}) \begin{cases} \stackrel{\textcircled{2}}{=} B(\vec{w}, \vec{v}) \\ \stackrel{\textcircled{3}}{=} -B(\vec{w}, \vec{v}) \end{cases} \\
 \parallel \\
 \left((a_1 \dots a_n) (B_{ij}) \begin{pmatrix} b_1 \\ \vdots \\ b_n \end{pmatrix} \right)^T &= (b_1 \dots b_n) \left[(B_{ij})^T \begin{pmatrix} a_1 \\ \vdots \\ a_n \end{pmatrix} \right] \\
 &= B^T(\vec{w}, \vec{v})
 \end{aligned}$$

$$\textcircled{2}: B(\vec{v}, \vec{w}) = B(\vec{w}, \vec{v}) = (b_1 \cdots b_n) (B_{ij}) \begin{pmatrix} a_1 \\ \vdots \\ a_n \end{pmatrix}$$

$$\Rightarrow (B_{ij}) = (B_{ij})^T$$

ft

Module

Recall a ring is a set R equipped with two binary operations $+$ and $\cdot$ satisfying

① $(R, +)$ is a "abelian group", i.e.

(a) $(a+b)+c = a+(b+c)$

(b) $a+b = b+a$

(c) $\exists 0 \in R$ st. $a+0 = a \quad \forall a \in R$

(d) $\forall a \in R, \exists -a \in R$ st.

$$a + (-a) = 0$$

② $(R, \cdot)$ is a "monoid", i.e.

(a) $(a \cdot b) \cdot c = a \cdot (b \cdot c)$ (eg. Hugenford)

(b) $\exists \underline{1_R} \in R$ st. $\leftarrow$ Some people don't require this

$$a \cdot 1_R = 1_R \cdot a = a \quad \forall a \in R$$

- ③ " $\cdot$ " is distributive w.r.t. " $+$ " i.e.,
- (a) $a \cdot (b+c) = a \cdot b + a \cdot c$
- (b) $(b+c) \cdot a = b \cdot a + c \cdot a$

Example Following are rings

- ① Any fields.
- ② $\mathbb{Z} = \{\text{integers}\}$
- ③ $M_n(\mathbb{K}) = \{n \times n \text{ matrixes}\}$
- ④ $C^\infty(\mathbb{R}^n) = \{ \text{smooth functions } \mathbb{R}^n \rightarrow \mathbb{R} \}$
 $(f \cdot g)(x) = f(x) \cdot g(x)$
- ⑤ $\mathbb{K}[x_1, \dots, x_n]$

$R = \text{ring}$

Def

A (left) R -module M consists of
 an abelian group $(M, +_M)$ and
 a scalar multiplication

$$\cdot : R \times M \rightarrow M$$

st. $\forall r, s \in R, \forall x, y \in M$

$$\textcircled{1} r \cdot (x +_M y) = r \cdot x +_M r \cdot y$$

$$\textcircled{2} (r+s) \cdot x = r \cdot x + s \cdot x \quad (\text{Hungerford})$$

$$\textcircled{3} (rs) \cdot x = r \cdot (s \cdot x)$$

$$\textcircled{4} 1_R \cdot x = x$$

Some authors
don't require $\textcircled{4}$
They say "unital
module"
if $\textcircled{4}$ is satisfied

A right R-module is defined similarly
with $\bullet : M \times R \rightarrow R$ (Main difference:
 $x \cdot (rs) = (x \cdot r) \cdot s$)

Example

① Any k -vector sps are k -module

② Any abelian gp is a $\mathbb{Z}$ -module

Let $(A, +)$ be an abelian gp.

$$n \in \mathbb{Z}, \quad x \in A$$

If $n > 0$, $\quad n \text{ times}$

$$n \cdot x := \underbrace{x + x + \dots + x}_n$$

If $n = 0$,

$$0 \cdot x := 0$$

If $n < 0$, $\quad -n \text{ times}$

$$n \cdot x := -(x + x + \dots + x)$$

③ $R \times R \times \dots \times R$ is an R -module

$$a \cdot (x_1, \dots, x_n) = (ax_1, \dots, ax_n)$$

④ $M_n(R)$ is an R -module.

⑤ $\{\text{derivations of } C^\infty(\mathbb{R}^n)\}$

$$= \left\{ X: C^\infty(\mathbb{R}^n) \rightarrow C^\infty(\mathbb{R}^n) \text{ is } \mathbb{R}\text{-linear and} \right. \\ \left. X(fg) = X(f) \cdot g + f \cdot X(g) \right\}$$

$$\text{eg } X = \frac{\partial}{\partial x_i}$$

is a $C^\infty(\mathbb{R}^n)$ -module.

$$\text{For } a \in C^\infty(\mathbb{R}^n), \quad \underbrace{C^\infty(\mathbb{R}^n)}_{\downarrow} \cdot \underbrace{C^\infty(\mathbb{R}^n)}_{\downarrow}$$

$$(a \cdot X)(f) = \underline{a} \cdot (\underline{Xf}) \quad \forall f \in C^\infty(\mathbb{R}^n)$$

Remark (Left R -module v.s. right R -module)

Let M be a left R -module

N be a right R -module

Let

$$L_a(x) := a \cdot x$$

$$a, b \in R$$

$$R_b(y) := y \cdot b$$

$$x \in M, y \in N$$

in an

$$(i) (L_a \circ L_b)(x) = a \cdot (L_b(x)) = a \cdot (b \cdot x) \\ = (ab) \cdot x = L_{ab}(x)$$

i.e. $L_a \circ L_b = L_{ab}$

$$(ii) (R_a \circ R_b)(y) = (R_b(y)) \cdot a = (y \cdot b) \cdot a \\ = y \cdot (ba) = R_{ba}(y)$$

i.e. $R_a \circ R_b = R_{ba}$

$$S^3(V \oplus W) = \left\{ \sum_{\substack{\parallel \\ \vec{v}_1 + \vec{w}_1, \vec{v}_2 + \vec{w}_2, \vec{v}_3 + \vec{w}_3}} x_1 \otimes x_2 \otimes x_3 \mid x_1, x_2, x_3 \in V \oplus W \right\} \\ = (\vec{v}_1 + \vec{w}_1) \otimes (\vec{v}_2 + \vec{w}_2) \otimes (\vec{v}_3 + \vec{w}_3) \\ = \underbrace{\vec{v}_1 \otimes \vec{v}_2 \otimes \vec{v}_3}_{S^3 V} + \underbrace{\vec{v}_1 \otimes \vec{v}_2 \otimes \vec{w}_3}_{S^2 V \otimes W} + \dots$$

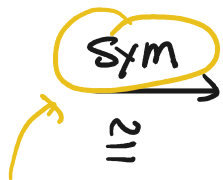
HW7.4.(c) $\xleftrightarrow{1 \leftrightarrow 2} \text{because } v_2 \otimes v_1 + v_1 \otimes v_2 \in \text{Sym}^2(V)$

$A = v_1 \otimes v_2 + v_2 \otimes v_1 \in \text{Sym}^2(V)$, $B = v_3 \in \text{Sym}^1(V)$ But $A \otimes B \notin \text{Sym}^3(V)$

Find $C \in \text{S.T.}$ $\pi(C) = \pi(A) \otimes \pi(B)$

Recall: $S^k V = V \otimes \dots \otimes V / \sim$ $\xleftarrow{\pi} V \otimes \dots \otimes V$

.....



$$\{\text{symmetric tensors}\} = \text{Sym}^k V \subseteq V^{\otimes k}$$

$$\text{Sym}(\vec{v}_1 \otimes \dots \otimes \vec{v}_k) = \frac{1}{k!} \sum_{\sigma \in S_k} \vec{v}_{\sigma(1)} \otimes \dots \otimes \vec{v}_{\sigma(k)} \in$$

$$C = \overset{\text{Symmetrization}}{(V_1 \otimes V_2 + V_2 \otimes V_1) \otimes V_3}$$

$$= \text{Symmetrization} (V_1 \otimes V_2 \otimes V_3 + V_2 \otimes V_1 \otimes V_3)$$

$$= \frac{1}{6} (V_1 \otimes V_2 \otimes V_3 + V_1 \otimes V_3 \otimes V_2 + V_2 \otimes V_1 \otimes V_3 + V_2 \otimes V_3 \otimes V_1 + V_3 \otimes V_1 \otimes V_2 + V_3 \otimes V_2 \otimes V_1)$$

$$+ \frac{1}{6} (\dots) \in \text{Sym}^3(V)$$

$$\pi(C) = \frac{1}{6} \pi(\dots) + \frac{1}{6} \pi(\dots)$$

$$= \pi(V_1 \otimes V_2 \otimes V_3) + \pi(V_2 \otimes V_1 \otimes V_3)$$

$$= 2 V_1 \otimes V_2 \otimes V_3 = \pi(A) \otimes \pi(B)$$

$$\begin{array}{ccc} \text{Sym}^k(V) \times \text{Sym}^l(V) & \xrightarrow{\otimes} & \text{Sym}^{k+l}(V) \\ \uparrow \pi & & \uparrow \text{Sym} \\ \text{Sym}^k(V) & & \text{Sym}^l(V) \end{array}$$

$$S(V) \times S(V) \rightarrow S(V)$$

$$A \circ B = \text{Sym}(\pi(A) \otimes \pi(B)) \quad \#$$

Example

matrix •

$M_n(k)$ is a left $M_n(k)$ -module: $A \cdot X = \overset{\downarrow}{AX}$
 is also a right $M_n(k)$ -module: $X \cdot A = XA$

$$(L_A \circ L_B)(X) = ABX = L_{AB}(X)$$

$$(R_A \circ R_B)(X) = XBA = R_{BA}(X) \neq \underset{\downarrow}{R_{AB}(X)} \\ XAB$$

Remark (Relation between left R-mod and right R-mod)

Let R^{op} be the ring with

underlying set = R
 and multiplication $\cdot$ in R

$$a \square b := b \cdot a$$

e.g. $M_n(k)^{\text{op}} \quad A \square B = BA$

One has the bijection

$\sim \mid \cap \quad > \quad \sim \mid \cap \quad >$ right

$$\{ \text{left } R\text{-module} \} \longleftrightarrow \{ R^{\text{op}}\text{-module} \}$$

$$\underbrace{a \cdot x}_{\substack{\in \\ R^{\text{op}}}} \longleftrightarrow x \circ \underbrace{a^{\text{op}}}_{\substack{\in \\ R^{\text{op}}}}$$

More precisely, let M be a left R -mod.

Define a right R^{op} -module structure on M by

$$x \circ a^{\text{op}} := a \cdot x$$

This a right R^{op} -module because

$$\begin{aligned} \underbrace{(x \circ a^{\text{op}})}_{\substack{\text{def of} \\ R^{\text{op}}}} \circ b^{\text{op}} &= (a \cdot x) \circ b^{\text{op}} \\ &= b \cdot (a \cdot x) \stackrel{\substack{\text{left } R\text{-mod axiom} \\ \downarrow}}{=} (b \cdot a) \cdot x \\ &= (a^{\text{op}} \circ b^{\text{op}}) \cdot x \\ &= \underbrace{x \circ (a^{\text{op}} \circ b^{\text{op}})}_{\substack{\Rightarrow \text{ it satisfies axiom of} \\ \text{right } R^{\text{op}}\text{-mod}}} \end{aligned}$$

Def

Let M and N be (left) R -modules.

A map $f: M \rightarrow N$ is called a homomorphism of R -modules or R -linear map if

$$f'(a \cdot x + b \cdot y) = a \cdot f(x) + b \cdot f(y)$$

$$\forall a, b \in R \quad \forall x, y \in M.$$

isomorphism = 1-1, onto, R -linear map

$$\ker(f) = f^{-1}(0), \quad \text{im}(f) = f(M)$$

A submodule of M is a subset of M which is also an R -module under the operations of M .

Let N be a submodule of M .

$$M/N := M/\sim$$

where

$$x \sim y \iff x - y \in N.$$

The set M/N is equipped an R -module structure

$$[x] + [y] = [x + y]$$

$$a \cdot [x] = [a \cdot x]$$

Lemma

$(M/N, +, \cdot)$ is an R -module

$$a \cdot 0 = 0 \quad a \cdot 1 = a \quad a \cdot (-1) = -a \quad a \cdot 0 = 0$$

— called a quotient module

Direct sums and direct products also can be defined similarly as vector spaces.

Remark (Difference between modules and vector spaces)

Main difference is an R -module does NOT necessarily have a basis.

e.g.

$$M = \mathbb{Z}_2 = \mathbb{Z}/2\mathbb{Z} \text{ is a } \mathbb{Z}\text{-module} \\ = \{0, 1\}$$

$$n \cdot 0 = 0 \quad \forall n \in \mathbb{Z}$$

$$n \cdot 1 = \begin{cases} 0 & \text{if } n \text{ is even} \\ 1 & \text{if } n \text{ is odd} \end{cases}$$

Recall

$B = \{e_1, \dots, e_n\}$ is a basis

$$\Leftrightarrow \forall x \in M, \exists! c_1, \dots, c_n \in R$$

$$\text{s.t. } x = c_1 e_1 + c_2 e_2 + \dots + c_n e_n$$

In the case of $M = \mathbb{Z}_2$, $\nexists$ such B

Suppose B is a basis for $\mathbb{Z}_2$.

$\Rightarrow \exists!$ ^{impossible} $C_1, \dots, C_n \in \mathbb{Z}$

$$1 = C_1 x_1 + \dots + C_n x_n$$

But

$$1 = \underbrace{(C_1 + 2)}_{\substack{+ \\ C_1}} x_1 + C_2 x_2 + \dots + C_n x_n = C_1 x_1 + 2x_1 + C_2 x_2 + \dots + C_n x_n = C_1 x_1$$

$\rightarrow \leftarrow$ to "!"

$\nexists$

HW6.5

(a) Show $\exists!$ linear map $E: V^{\vee} \otimes V \rightarrow k$ s.t.

$$E(\xi \otimes v) = \xi(v)$$

pf

Note the map

$$\begin{aligned} B: V^{\vee} \times V &\longrightarrow k \\ (\xi, v) &\longmapsto \xi(v) \end{aligned}$$

is a bilinear map, because

$$\begin{aligned} B(a_1 \xi_1 + a_2 \xi_2, v) &= (a_1 \xi_1 + a_2 \xi_2)(v) \\ &= a_1 \xi_1(v) + a_2 \xi_2(v) \end{aligned}$$

$$= a_1 B(\xi_1, v) + a_2 B(\xi_2, v)$$

and

$$B(\xi, b_1 v_1 + b_2 v_2) = \xi(b_1 v_1 + b_2 v_2)$$

$$= b_1 \xi(v_1) + b_2 \xi(v_2)$$

$$= b_1 B(\xi, v_1) + b_2 B(\xi, v_2)$$

By the universal property of $\otimes$, $\exists!$ linear

$$E: V^\vee \otimes V \rightarrow k$$

$$\text{s.t. } E(\xi \otimes v) = B(\xi, v) = \xi(v) \quad \#$$

(b) Show $\text{tr} \circ \Phi = \bar{\xi}$, where

$$\Phi: V^\vee \otimes V \rightarrow \text{Hom}(V, V),$$

$$\Phi(\xi \otimes v)(w) = \xi(w) \cdot v.$$

Let $\{e_1, \dots, e_n\}$ be a basis for V

$\{\hat{e}_1, \dots, \hat{e}_n\}$ be the dual basis for $V^\vee$.

$\Rightarrow \{\hat{e}_i \otimes e_j \mid i, j = 1, \dots, n\}$ is a basis for $V^\vee \otimes V$

So $\text{tr} \circ \Phi = \bar{\xi}$

$$\text{tr} \circ \Phi = \bar{L}$$

$\Leftrightarrow$

$$(\text{tr} \circ \Phi)(\hat{e}_i \otimes e_j) = \bar{L}(\hat{e}_i \otimes e_j)$$

$$\forall i, j = 1, \dots, n$$

LHS:

Since $\bar{\Phi}(\hat{e}_i \otimes e_j)(e_k) = \hat{e}_i(e_k) \cdot e_j = \begin{cases} e_j & k=i \\ 0 & k \neq i \end{cases}$

$$\Rightarrow (\bar{\Phi}(\hat{e}_i \otimes e_j)) = \bar{e}_j \cdot \begin{pmatrix} 0 & \dots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \dots & 1 & \dots & 0 \end{pmatrix}$$

$$\Rightarrow \text{tr}(\bar{\Phi}(\hat{e}_i \otimes e_j)) = \begin{cases} 1 & i=j \\ 0 & i \neq j \end{cases}$$

RHS:

$$\bar{L}(\hat{e}_i \otimes e_j) = \hat{e}_i(e_j) = \begin{cases} 1 & i=j \\ 0 & i \neq j \end{cases} \quad \#$$