

# Linear Algebra 1½

## § Symmetric tensor product

Recall

In  $V \otimes V$ ,

$$\vec{v}_1 \otimes \vec{v}_2 \neq \vec{v}_2 \otimes \vec{v}_1 \text{ in general}$$

If you want a commutative product,  
you can do ...

Def.

The Symmetric tensor product  $V \circ V$   
is the quotient space

$$S^2 V = V \circ V = \frac{V \otimes V}{\text{Span}\{x \otimes y - y \otimes x \mid x, y \in V\}}$$

which is also denoted by  $S^2 V$   
(or  $\text{Sym}^2 V$ )

More generally,

$$S^k V = \frac{V \otimes \dots \otimes V}{\text{Span}\{\underbrace{\vec{v}_1 \otimes \dots \otimes \vec{v}_{i-1} \otimes}_{\text{k times}} (\vec{v}_i \otimes \vec{v}_{i+1} - \vec{v}_{i+1} \otimes \vec{v}_i) \otimes \dots \otimes \vec{v}_k \mid \dots \}}$$

We denote

$$\vec{v}_1, \dots, \vec{v}_k \in V$$

$$\vec{v}_1 \odot \dots \odot \vec{v}_k = [\vec{v}_1 \otimes \dots \otimes \vec{v}_k] \in S^k V$$

Remark

In  $S^k V$ , we have

$$\begin{aligned} & \vec{v}_1 \odot \dots \odot \vec{v}_i \odot \vec{v}_{i+1} \odot \dots \odot \vec{v}_k \\ &= \vec{v}_1 \odot \dots \odot \vec{v}_{i+1} \odot \vec{v}_i \odot \dots \odot \vec{v}_k \\ &= \vec{v}_{\sigma(1)} \odot \dots \odot \vec{v}_{\sigma(k)} \end{aligned}$$

$\forall \sigma \in S_k =$  permutation group.

Recall:

- $S_k = \{ \sigma: \{1, \dots, k\} \rightarrow \{1, \dots, k\} \text{ 1-1, onto maps} \}$
- $\sigma = (i_1 i_1 + 1) (i_2 i_2 + 1) \dots (i_n i_n + 1)$   
for some  $i_1, \dots, i_n \in \{1, \dots, k-1\}$  NOT fixed by  $\sigma$   
but (even/odd)
- $\sigma$  is even if  $N$  is even  
odd if  $N$  is odd parity of  $N$   
is fixed by  $\sigma$
- $(-1)^\sigma := \begin{cases} +1 & \text{if } \sigma \text{ is even} \\ -1 & \text{if } \sigma \text{ is odd.} \end{cases}$

Example

Let  $e_1, e_2$  be the standard basis for  $\mathbb{R}^2$

In  $S^2\mathbb{R}^2$ ,

$$(e_1 + 2e_2) \odot (3e_1 + 4e_2)$$

$e_1 \odot e_2$

||

$$= 3e_1 \odot e_1 + 4e_1 \odot e_2 + 6e_2 \odot e_1 + 8e_2 \odot e_2$$

$$= 3e_1 \odot e_1 + 10e_1 \odot e_2 + 8e_2 \odot e_2$$

■

Let  $\varphi: \overbrace{V \times \dots \times V}^k \rightarrow S^k V$  be the map

$$\varphi(\vec{v}_1, \dots, \vec{v}_k) = \vec{v}_1 \odot \dots \odot \vec{v}_k$$

which is  $k$ -linear and Symmetric, i.e.,

$$\varphi(\vec{v}_{\sigma(1)}, \dots, \vec{v}_{\sigma(k)}) = \varphi(\vec{v}_1, \dots, \vec{v}_k) \quad \forall \sigma \in S_k.$$

Prop

If  $f: \overbrace{V \times \dots \times V}^k \rightarrow W$  is a multilinear map with the property  $\forall \vec{v}_1, \dots, \vec{v}_k \in V$ .

$$f(\vec{v}_{\sigma(1)}, \dots, \vec{v}_{\sigma(k)}) = f(\vec{v}_1, \dots, \vec{v}_k) \quad \forall \sigma \in S_k,$$

then  $\exists!$  linear map

$$\tilde{f}: S^k V \rightarrow W$$

st.  $\overbrace{\tilde{f}}^{\text{is } k\text{-linear}}, \underline{\tilde{f}} \xrightarrow{\text{def}} 1_n$

$$V \times \cdots \times V \xrightarrow{\quad} VV$$

↓ φ  
SV

f ↗

Commutes.

### Remark

So we have

$$\left\{ \begin{array}{c} V \times \cdots \times V \xrightarrow{k \text{-linear}} W \\ \text{Symmetric} \end{array} \right\} \xleftarrow[\text{onto}]{} \left\{ \begin{array}{c} SV \xrightarrow{\text{linear}} W \end{array} \right\}$$

$\hat{f} \circ \varphi$  ↗

### pf of Prop

$$V \times \cdots \times V \xrightarrow{\quad} W$$

↓  
 $V^{\otimes k}$

$\hat{f}$  ↗

k-linear  
symmetric

$\exists!$  linear  $\hat{f}$  ↗

$\hat{f}(R) = 0$

$\exists!$  linear  $\hat{f}$  ↗

$\cancel{V^{\otimes k}/R} = SV$

#

### Example

The mod

$$\overline{V} \times \cdots \times \overline{V} \rightarrow V^{\otimes k}$$

$$(\vec{v}_1, \dots, \vec{v}_k) \mapsto \frac{1}{k!} \sum_{\sigma \in S_k} (\vec{v}_{\sigma(1)} \otimes \vec{v}_{\sigma(2)} \otimes \cdots \otimes \vec{v}_{\sigma(k)})$$

is multilinear and symmetric

e.g.

$$(\vec{v}_1, \vec{v}_2) \mapsto \frac{1}{2} (\vec{v}_1 \otimes \vec{v}_2 + \vec{v}_2 \otimes \vec{v}_1)$$

$$(\vec{v}_2, \vec{v}_1) \mapsto \frac{1}{2} (\vec{v}_2 \otimes \vec{v}_1 + \vec{v}_1 \otimes \vec{v}_2)$$

So  $\exists!$  linear map  $\text{Sym}: S^k V \rightarrow V^{\otimes k}$  s.t.

$$\text{Sym}(\vec{v}_1 \odot \cdots \odot \vec{v}_k) = \frac{1}{k!} \sum_{\sigma \in S_k} (\vec{v}_{\sigma(1)} \otimes \cdots \otimes \vec{v}_{\sigma(k)})$$


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Note

- $\text{Sym}: S^k V \rightarrow V^{\otimes k}$  is well-defined
- $\pi \circ \text{Sym} = \text{id}_{S^k V}$ , where  
 $\pi: V^{\otimes k} \rightarrow S^k V = \frac{V^{\otimes k}}{R}$ ,  $\pi(x) = [x]$   
 is the quotient map

because

$$(\pi \circ \text{Sym})(\vec{v}_1 \odot \cdots \odot \vec{v}_k)$$

$$\vec{v}_1 \odot \cdots \odot \vec{v}_k$$

"

$$= \frac{1}{k!} \sum_{\sigma \in S_k} \underbrace{\vec{v}_{\sigma(1)} \odot \cdots \odot \vec{v}_{\sigma(k)}}_{\text{underlined}}$$

$$\begin{aligned}
 &= \frac{1}{k!} \sum_{\sigma \in S_k} \vec{v}_1 \odot \cdots \odot \vec{v}_k \\
 &= \frac{1}{k!} \cdot k! \cdot \vec{v}_1 \odot \cdots \odot \vec{v}_k = \text{id}(\vec{v}_1 \odot \cdots \odot \vec{v}_k) \\
 &\quad \Downarrow \quad \Downarrow \\
 &\therefore \pi \cdot \underline{\text{sym}} = \text{id}
 \end{aligned}$$

Prop

The map  $\text{sym}: S^k V \rightarrow V^{\otimes k}$  is one-to-one

An alternative definition of  $S^k V$

Let  $\sigma \in S_k$ . Since the map

$$\begin{array}{ccc}
 \text{---} & \text{---} & \text{---} \\
 \vec{v}_1 \otimes \cdots \otimes \vec{v}_k & \longrightarrow & V^{\otimes k} \\
 (\vec{v}_1, \dots, \vec{v}_k) & \longmapsto & (\vec{v}_{\sigma(1)} \otimes \vec{v}_{\sigma(2)} \otimes \cdots \otimes \vec{v}_{\sigma(k)})
 \end{array}$$

is multilinear,  $\exists!$  linear map

$$T_0 : V^{\otimes k} \longrightarrow V^{\otimes k}$$

s.t.

$$T_0(\vec{v}_1 \otimes \cdots \otimes \vec{v}_k) = (\vec{v}_{\sigma(1)} \otimes \cdots \otimes \vec{v}_{\sigma(k)})$$

Let  $\{e_i | i \in I\}$  be a basis for  $V$ .

An element  $A \in V^{\otimes k}$  is of the form

$$\lambda - \gamma - \alpha - \beta - \cdots$$

$$A = \sum_{\substack{(i_1, \dots, i_k) \in I^k \\ \text{finite sum}}} a_{i_1, \dots, i_k} e_{i_1} \otimes \dots \otimes e_{i_k}$$

$\Rightarrow$

$$\begin{aligned} T_0(A) &= \sum a_{i_1, \dots, i_k} e_{i_{\sigma(1)}} \otimes \dots \otimes e_{i_{\sigma(k)}} \\ &= \sum a_{i_{\sigma(1)}, \dots, i_{\sigma(k)}} \cdot e_{i_1} \otimes \dots \otimes e_{i_k} \end{aligned}$$

Prop

$S_i$

$$\underline{\text{Sym}(S^k V)} = \left\{ A \in V^{\otimes k} \mid T_0(A) = A \quad \forall \sigma \in S_k \right\}$$

$$= \left\{ A \in V^{\otimes k} \mid a_{i_1, \dots, i_k} = a_{i_{\sigma(1)}, \dots, i_{\sigma(k)}} \quad \forall \sigma \in S_k \right\}$$

pf

$$\underline{\text{Sym}(S^k V)} \subseteq S: \text{ direct computation}$$

check:

$$\forall \vec{v}_1, \dots, \vec{v}_k \in V.$$

$$\underline{T_0(\text{Sym}(\vec{v}_1 \otimes \dots \otimes \vec{v}_k))} = \text{Sym}(\vec{v}_1 \otimes \dots \otimes \vec{v}_k)$$

$$\begin{aligned} T_0\left(\sum_{\substack{\alpha \in S_k \\ \text{II}}} \vec{v}_{\alpha(1)} \otimes \dots \otimes \vec{v}_{\alpha(k)}\right) &\stackrel{\text{def}}{=} \left\{ \alpha \circ \sigma \mid \alpha \in S_k \right\} \\ &\stackrel{\text{def}}{=} \left\{ \alpha \mid \alpha \in S_k \right\} \end{aligned}$$

$$= \frac{1}{k!} \sum_{\alpha \in S_k} \vec{v}_{\alpha(1)} \otimes \dots \otimes \vec{v}_{\alpha(k)}$$

$$1 \prec \vec{v}_1 \otimes \dots \otimes \vec{v}_k \rightarrow \text{Sym}(\vec{v}_1 \otimes \dots \otimes \vec{v}_k)$$

$$= \frac{1}{k!} \sum_{\alpha \in S_k} v_{\text{vac}}(\alpha) \otimes v_{\text{back}}(\alpha) = \omega_{S^k V} \otimes v_{\text{back}}$$

$S \subseteq \text{Sym}(S^k V)$ :

$$\forall A = \sum a_{i_1, \dots, i_k} e_{i_1} \otimes \dots \otimes e_{i_k} \in S$$

one can check:

$$A = \text{Sym} \left( \sum_{i_1 \leq \dots \leq i_k} a_{i_1, \dots, i_k} e_{i_1} \otimes \dots \otimes e_{i_k} \right) \in \text{Sym}(S^k V)$$

$$i_1 = \dots = i_{n_1} < i_{n_1+1} = \dots = i_{n_1+n_2}$$

e.g.  $A = e_1 \otimes e_2 \otimes e_2 + e_2 \otimes e_1 \otimes e_2 + e_2 \otimes e_2 \otimes e_1$ ,  $T_0(A) = A^\vee$

so

$$\text{Sym}(e_1 \otimes e_2 \otimes e_2)$$

$$= \frac{1}{6!} \left( \begin{matrix} 2 & 1 & 3 \\ e_1 \otimes e_2 \otimes e_2 & + e_2 \otimes e_1 \otimes e_2 & + e_2 \otimes e_2 \otimes e_1 \\ 1 & 3 & 2 \\ e_1 \otimes e_2 \otimes e_2 & + e_2 \otimes e_1 \otimes e_2 & + e_2 \otimes e_2 \otimes e_1 \\ 3 & 2 & 1 \end{matrix} \right)$$

$$= \frac{1}{3} (e_1 \otimes e_2 \otimes e_2 + e_2 \otimes e_1 \otimes e_2 + e_2 \otimes e_2 \otimes e_1)$$

$$= \frac{1}{3} A$$

Some people  $S = \text{Sym}(S^k V)$  as the

definition of  $S^k V$ , and an element in  $\text{sym}(S^k V)$  is called a symmetric tensor.

By Prop.

$$\text{sym}: S^k V \xrightarrow{\quad \text{``} \quad} \text{sym}(S^k V) \subseteq V^{\otimes k}$$

is an isomorphism.

Prop

Let  $\{e_1, \dots, e_n\}$  be a basis for  $V$ .

Then

$$\{e_{i_1} \otimes \dots \otimes e_{i_k} \mid 1 \leq i_1 \leq \dots \leq i_k \leq n\}$$

is a basis for  $S^k V$ .

$$\overset{n}{\overbrace{e \dots \otimes}} \overset{k-1}{\overbrace{i \dots i}}$$

In particular,

$$\dim S^k V = \binom{n+k-1}{k}$$

$$n = 1 + \dots + 1$$

## § Skew-symmetric tensor product

Def

$$\vec{v}_1 \circ \vec{v}_2 = \vec{v}_2 \otimes \vec{v}_1$$

$$\dots \dots \backslash \backslash / \quad \vec{v}_1 \wedge \vec{v}_2 = - \vec{v}_2 \wedge \vec{v}_1$$

$$V \wedge V := V \otimes V / \text{span} \{ x \otimes y + y \otimes x \mid x, y \in V \}$$

which is also denoted by  $\wedge^2 V$

skew-Symmetric tensor product

or wedge product

More generally,

$$\wedge^k V := \frac{\text{span} \{ \vec{v}_1 \otimes \dots \otimes (\vec{v}_i \otimes \vec{v}_{i+1} + \vec{v}_{i+1} \otimes \vec{v}_i) \otimes \dots \otimes \vec{v}_k \}}{\text{span} \{ \vec{v}_1 \otimes \dots \otimes (\vec{v}_i \otimes \vec{v}_{i+1} + \vec{v}_{i+1} \otimes \vec{v}_i) \otimes \dots \otimes \vec{v}_k \}}$$

$$\vec{v}_1 \wedge \dots \wedge \vec{v}_k := [\vec{v}_1 \otimes \dots \otimes \vec{v}_k] \in \wedge^k V = \frac{\text{span} \{ \vec{v}_1 \otimes \dots \otimes \vec{v}_k \}}{R}$$

Remark

In  $\wedge^k V$ ,

$$\vec{v}_1 \wedge \dots \wedge \underline{\vec{v}_i \wedge \vec{v}_{i+1} \wedge \dots \wedge \vec{v}_k} = - \underline{\vec{v}_1 \wedge \dots \wedge \vec{v}_{i+1} \wedge \vec{v}_i \wedge \dots \wedge \vec{v}_k}$$

$$= (-1)^{\sigma} \cdot \vec{v}_{\sigma(1)} \wedge \dots \wedge \vec{v}_{\sigma(k)} \quad \forall \sigma \in S_k$$

Also note that

$$\vec{v} \wedge \vec{v} = - \vec{v} \wedge \vec{v}$$

$$\Rightarrow 2 \cdot \vec{v} \wedge \vec{v} = 0 \Rightarrow \vec{v} \wedge \vec{v} = 0 \quad (\text{if char } k \neq 2)$$

### Example

In  $\Lambda^2 \mathbb{R}^2$ ,

$$(e_1 + 2e_2) \wedge (3e_1 + 4e_2)$$

$$= 3 \cancel{[e_1 \wedge e_1]} + 4e_1 \wedge e_2 + 6 \cancel{[e_2 \wedge e_1]} + 8e_2 \wedge \cancel{e_2}$$

$$= -2 \cdot e_1 \wedge e_2$$

### Prop

If  $f: \overset{k}{\underset{\times}{V}} \rightarrow W$  is multilinear and

$$\rightsquigarrow f(\vec{v}_1, \dots, \vec{v}_k) = \sum_{\sigma \in S_k} f(\vec{v}_{\sigma(1)}, \dots, \vec{v}_{\sigma(k)})$$

i.e. skew-symmetric

$$\forall \sigma \in S_k$$

then  $\exists!$  linear  $\tilde{f}: \Lambda^k V \rightarrow W$  s.t.

$$\begin{array}{ccc}
 (\vec{v}_1, \dots, \vec{v}_k) & \overset{\Lambda^k V}{\underset{\times}{\longrightarrow}} & W \\
 \downarrow & \downarrow & \xrightarrow{\text{multilinear skew-sym}} \\
 \vec{v}_1 \wedge \dots \wedge \vec{v}_k & \Lambda^k V & \xrightarrow{\text{---}}
 \end{array}$$

$\exists! \tilde{f}$  linear

Commutes

### Example

$\exists!$  linear map

$$\tilde{\text{Sym}}: \Lambda^k V \rightarrow V^{\otimes k}$$

s.t.

$$\tilde{\text{Sym}}(\vec{v}_1 \wedge \cdots \wedge \vec{v}_k) = \frac{1}{k!} \sum_{\sigma \in S_k} \epsilon_{12}^{\sigma} \vec{v}_{\sigma(1)} \otimes \cdots \otimes \vec{v}_{\sigma(k)}$$

because  $V^{k \times k} \rightarrow V^{\otimes k}$

$$(\vec{v}_1, \dots, \vec{v}_k) \mapsto \frac{1}{k!} \sum_{\sigma \in S_k} \epsilon_{12}^{\sigma} \vec{v}_{\sigma(1)} \otimes \cdots \otimes \vec{v}_{\sigma(k)}$$

is skew-sym multilinear

Prop

$$\tilde{\text{Sym}}: \Lambda^k V \rightarrow V^{\otimes k} \quad \text{is one-to-one}$$

Prop

another definition  
↓

$$\tilde{\text{Sym}}(\Lambda^k V) = \left\{ \underset{A \in V^{\otimes k}}{=} \mid T_0(A) = \epsilon_{12}^{\sigma} \cdot A \quad \forall \sigma \in S_k \right\}$$

A is called skew-Symmetric tensor

Prop (Suppose  $\text{char } k \neq 2$ )

Let  $\{e_1, \dots, e_n\}$  be a basis for  $V$ .

Then

$$\{e_{i_1} \wedge e_{i_2} \wedge \cdots \wedge e_{i_k} \mid 1 \leq i_1 < i_2 < \cdots < i_k \leq n\}$$

is a basis for  $\Lambda^k V$  (Recall  $e_1 \wedge \underbrace{e_2 \wedge \cdots}_{=0} = 0$ )

In particular,

$$\dim \Lambda^k V = \binom{n}{k}.$$

## § Pairings

Let  $f, g: V \rightarrow k$ .

$$f \circ g : S^2 V \rightarrow k = ?$$

$$f \wedge g : \Lambda^2 V \rightarrow k = ?$$

Problem:

The formula:

$$(f \circ g)(\vec{v} \circ \vec{w}) = \underline{\underline{f(\vec{v}) \cdot g(\vec{w})}}$$

is NOT well-defined !! \*

$$(f \circ g)(\vec{w} \circ \vec{v}) = \underline{\underline{f(\vec{w}) \cdot g(\vec{v})}}$$

Recall we have

$$\langle \cdot | \cdot \rangle : V \otimes V^* \rightarrow k, \langle \vec{v} | f \rangle = f(\vec{v})$$

or

$$\langle \cdot | \cdot \rangle : V^* \otimes V \rightarrow k, \langle f | \vec{v} \rangle = f(\vec{v})$$

This induces

$$(V^*)^{\otimes k} \times V^{\otimes k} \rightarrow k$$

$$\begin{aligned} \langle f_1 \otimes \dots \otimes f_k | \vec{v}_1 \otimes \dots \otimes \vec{v}_k \rangle &= \langle f_1 | \vec{v}_1 \rangle \cdot \langle f_2 | \vec{v}_2 \rangle \dots \langle f_k | \vec{v}_k \rangle \\ &= f_1(\vec{v}_1) \cdot \dots \cdot f_k(\vec{v}_k) \quad \text{← multilinear} \end{aligned}$$

∴

$$\langle \cdot | \cdot \rangle : S^k(V^*) \times S^k V \rightarrow k$$

$$\begin{aligned}
 & \langle f_1 \otimes \cdots \otimes f_k | \vec{v}_1 \otimes \cdots \otimes \vec{v}_k \rangle \quad k! \operatorname{Sym}(\vec{v}_1 \otimes \cdots \otimes \vec{v}_k) \\
 &= \langle f_1 \otimes \cdots \otimes f_k | \sum_{\alpha \in S_k} \vec{v}_{\alpha(1)} \otimes \cdots \otimes \vec{v}_{\alpha(k)} \rangle \\
 &= \sum_{\alpha \in S_k} f_1(\vec{v}_{\alpha(1)}) \cdot f_2(\vec{v}_{\alpha(2)}) \cdots f_k(\vec{v}_{\alpha(k)})
 \end{aligned}$$

Lemma

This  $\langle \cdot | \cdot \rangle$  is well-defined.

Similarly, one has

$$\langle \cdot | \cdot \rangle : \Lambda^k(V^*) \times \Lambda^k V \rightarrow \mathbb{k}$$

with the property

Lemma

$$\begin{aligned}
 & \langle f_1 \wedge f_2 \wedge \cdots \wedge f_k | \vec{v}_1 \wedge \cdots \wedge \vec{v}_k \rangle \quad \text{This is well-defined} \\
 &:= \langle f_1 \otimes \cdots \otimes f_k | \sum_{\alpha \in S_k} (-1)^\alpha \vec{v}_{\alpha(1)} \otimes \cdots \otimes \vec{v}_{\alpha(k)} \rangle \\
 &= \sum_{\alpha \in S_k} (-1)^\alpha f_1(\vec{v}_{\alpha(1)}) \cdots f_k(\vec{v}_{\alpha(k)})
 \end{aligned}$$

Prop

Suppose  $\dim V < \infty$ . Then

$$S^k(V^*) \xrightarrow{\cong} (\Lambda^k V)^*, \quad \theta \mapsto \langle \theta | - \rangle$$

$$\Lambda^k(V^*) \xrightarrow{\cong} (\Lambda^k V)^*, \quad \omega \mapsto \langle \omega | - \rangle$$

are isomorphisms.

$S^k V$  = linear diff. op. on  $V$   
order  $k$

$$\frac{\partial}{\partial x_1} \frac{\partial}{\partial x_2} = \frac{\partial^2}{\partial x_1 \partial x_2}$$

Remark

$S^k(V^*) \cong \{ \text{homogeneous polynomials of degree } k \text{ on } V \}$

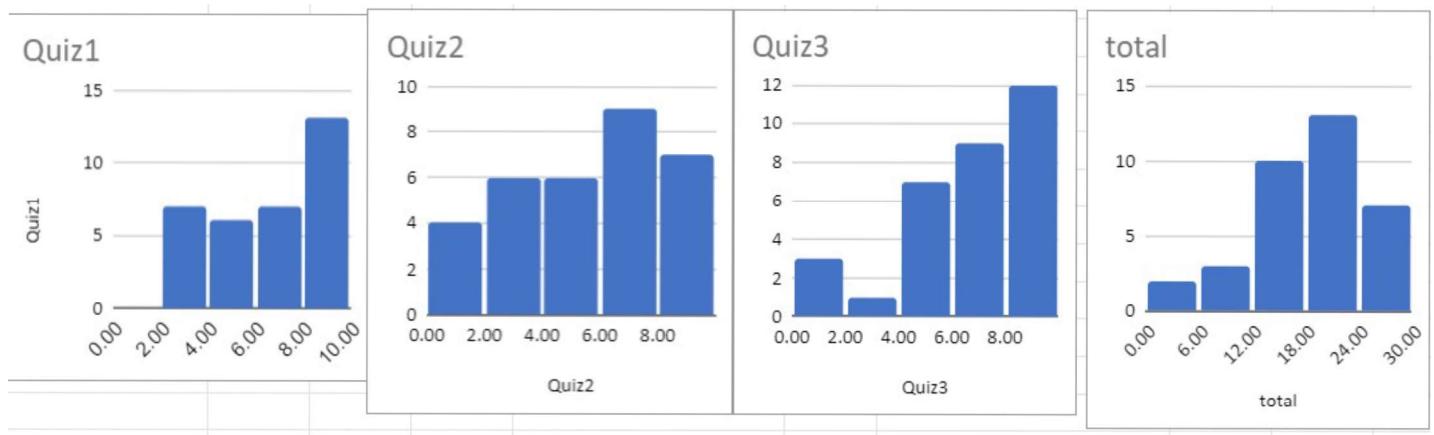
e.g.  $f \in S(V^*) = V^*$ ,  $f: V \rightarrow \mathbb{k}$  is linear

With a basis,

$$x_1 e_1 + x_2 e_2 + \dots + x_n e_n \quad a_i = f(e_i)$$

$$f(x_1, \dots, x_n) = a_1 x_1 + \dots + a_n x_n$$

for some  $a_1, \dots, a_n \in \mathbb{k}$   $[f] = \begin{pmatrix} a_1 & \dots & a_n \\ \hline f(e_i) \end{pmatrix}$



Average  
Average (except 0)  
Quartile0  
Quartile1  
Quartile2  
Quartile3  
Quartile4  
標準差  
非零數  
不到總分50%人數  
滿分/A+人數

17.85714	6.3428575.485714	6.205882
17.85714	6.3428575.8181816.806451	
3	2	0
14	4	3
18	7	6
21.5	8	8
28	10	10
6.399185	2.436762.863270	2.637485
35	35	33
35	11	12
<del>35</del>	2	3
		2

HW3. 4. b

Given  $\vec{A}_{i_1, i_2, i_3}^j \in k$ , show that  $\exists$  multilinear map  $f: V_1 \times V_2 \times V_3 \rightarrow W$  whose coordinate representation is  $(\vec{A}_{i_1, i_2, i_3}^j)$

Assume  $\vec{v}_1^1, \dots, \vec{v}_{n_1}^1$  basis for  $V_1$   
 $\vec{v}_1^2, \dots, \vec{v}_{n_2}^2$  ..  $V_2$   
 $\vec{v}_1^3, \dots, \vec{v}_{n_3}^3$  ..  $V_3$   
 $\vec{w}_1, \dots, \vec{w}_m$  ..  $W$ .

For  $x \in V_1, y \in V_2, z \in V_3, \exists! \alpha_{i_1}, \beta_{i_2}, \gamma_{i_3} \in \mathbb{K}$

s.t.

$$x = \sum_{i_1=1}^{n_1} \alpha_{i_1} \vec{v}_{i_1}^1, \quad y = \sum_{i_2=1}^{n_2} \beta_{i_2} \vec{v}_{i_2}^2, \quad z = \sum_{i_3=1}^{n_3} \gamma_{i_3} \vec{v}_{i_3}^3$$

Define

$$f: V_1 \times V_2 \times V_3 \rightarrow W$$

by

$$f(x, y, z) = f\left(\sum \alpha_{i_1} \vec{v}_{i_1}^1, \sum \beta_{i_2} \vec{v}_{i_2}^2, \sum \gamma_{i_3} \vec{v}_{i_3}^3\right)$$

$$:= \sum_{i_1, i_2, i_3, j} \alpha_{i_1} \beta_{i_2} \gamma_{i_3} \boxed{\overset{\delta}{\underset{\text{if hope}}{\underset{\alpha_{i_1, i_2, i_3}}{\overbrace{\alpha_{i_1, i_2, i_3}}}}} \vec{w}_j$$

coeff in  $f(\vec{v}_{i_1}^1, \vec{v}_{i_2}^2, \vec{v}_{i_3}^3)$   
of  $\vec{w}_j$

Then

check  $f$  is multilinear