A Remark On A Nonlinear System Arising In A Theory Of Thermal Explosion^{*}

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Abstract

The purpose of this paper is to study the existence and multiplicity of positive solutions for a mathematical model of thermal explosion which is described by the system

 $\left\{ \begin{array}{ll} -\Delta u = \lambda f(v), & x \in \Omega, \\ -\Delta v = \lambda g(u), & x \in \Omega, \\ \mathbf{n}.\nabla u + a(u)u = 0, & x \in \partial\Omega, \\ \mathbf{n}.\nabla v + b(v)v = 0, & x \in \partial\Omega, \end{array} \right.$

where Ω is a bounded smooth domain of \mathbb{R}^N , Δ is the Laplacian operator, $\lambda > 0$ is a parameter, f, g are C^1 strictly increasing functions that have a combined sublinear effect at ∞ , and $a, b : [0, \infty) \to (0, \infty)$ are strictly increasing C^1 functions. We establish our existence and multiplicity results by the method of sub- and supersolutions.

1 Introduction

A classical problem in combustion theory is a model of thermal explosion which occurs due to a spontaneous ignition in a rapid combustion process. In this paper, we consider a model involving a nonlinear boundary heat loss which is not a very typical one in classical combustion theory, but is relevant to some more applications (see [4, 10, 12, 5] for details). The model reads as:

$$\begin{array}{ll}
\theta(t) - \Delta\theta = \lambda f(\eta), & (t, x) \in (0, \infty) \times \Omega, \\
\eta(t) - \Delta\eta = \lambda g(\theta), & (t, x) \in (0, \infty) \times \Omega, \\
\mathbf{n}.\nabla\theta + a(\theta)\theta = 0, & (t, x) \in (0, \infty) \times \partial\Omega, \\
\mathbf{n}.\nabla\eta + b(\eta)\eta = 0, & (t, x) \in (0, \infty) \times \partial\Omega, \\
\theta(0, x) = 0 = \eta(0, x).
\end{array}$$
(1)

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Here θ, η are the appropriately scaled temperature in a bounded smooth domain $\Omega \subset \mathbb{R}^{N}$, $N \ge 1$, and f, g are the normalized reaction rate. We assume that f, g satisfy the following assumptions:

(H1) $f, g \in C([0, \infty))$ are strictly increasing functions,

(H2) $\lim_{s\to\infty} \frac{f(Ag(s))}{s} = 0$, for all A > 0.

On the C^2 boundary $\partial\Omega$, with the outward unit normal denoted by **n**, the heat-loss parameters $a(\theta), b(\eta)$ are assumed to satisfy the following hypothesis:

(H3) $a, b: [0, \infty) \to (0, \infty)$ are strictly increasing bounded C^1 functions.

Physically this assumption means that a heat loss through the boundary always exists and increases linearly with the temperature even in the small temperature regime.

A bifurcation (or scaling) parameter $\lambda > 0$ can be associated with the size of domain Ω in (1) which grows linearly as the measure of Ω increases. It is well known that, after normalizing for the size of Ω , the long term behavior of solution of the system (1) is close to the solution of the time-independent system:

$$\begin{cases}
-\Delta u = \lambda f(v), & x \in \Omega, \\
-\Delta v = \lambda g(u), & x \in \Omega, \\
\mathbf{n}.\nabla u + a(u)u = 0, & x \in \partial\Omega, \\
\mathbf{n}.\nabla v + b(v)v = 0, & x \in \partial\Omega.
\end{cases}$$
(2)

The motivation for this study cames from the work in [7] where the authors established the existence, uniqueness and multiplicity of positive solutions for certain range of λ for the single equation of the form

$$\begin{cases} -\Delta u = \lambda f(u), & x \in \Omega, \\ \mathbf{n} . \nabla u + a(u)u = 0, & x \in \partial \Omega \end{cases}$$

Here we extend this study to Laplacian system of the form (2). In [1], Ali-Shivaji-Ramaswamy discussed the existence of multiple positive solutions to such systems with Dirichlet boundary conditions. One can refer to [3, 8] for some recent existence and uniqueness results of elliptic problems with nonlinear boundary conditions.

2 Existence Results

In this section, we shall establish our existence results via the method of sub - supersolution. A pair of nonnegative functions $(\psi_1, \psi_2) \in W^{1,2} \cap C(\overline{\Omega}) \times W^{1,2} \cap C(\overline{\Omega})$ and a pair $(z_1, z_2) \in W^{1,2} \cap C(\overline{\Omega}) \times W^{1,2} \cap C(\overline{\Omega})$ are called a subsolution and supersolution of the system (2) if they satisfy

$$\begin{cases}
-\Delta\psi_{1} \leq \lambda f(\psi_{2}), & x \in \Omega, \\
-\Delta\psi_{2} \leq \lambda g(\psi_{1}), & x \in \Omega, \\
\mathbf{n}.\nabla\psi_{1} + a(\psi_{1})\psi_{1} \leq 0, & x \in \partial\Omega, \\
\mathbf{n}.\nabla\psi_{2} + b(\psi_{2})\psi_{2} \leq 0, & x \in \partial\Omega,
\end{cases}$$
(3)

and

$$\begin{cases}
-\Delta z_1 \ge \lambda f(z_2), & x \in \Omega, \\
-\Delta z_2 \ge \lambda g(z_1), & x \in \Omega, \\
\mathbf{n}.\nabla z_1 + a(z_1)z_1 \ge 0, & x \in \partial\Omega, \\
\mathbf{n}.\nabla z_2 + b(z_2)z_2 \ge 0, & x \in \partial\Omega,
\end{cases}$$
(4)

respectively. It is well known that if there exist sub and supersolutions (ψ_1, ψ_2) and (z_1, z_2) respectively of the system (2) such that $(\psi_1, \psi_2) \leq (z_1, z_2)$. Then the system (2) has a solution (u, v) such that $(u, v) \in [(\psi_1, \psi_2), (z_1, z_2)]$ (see [2, 6]). Alsayed et al.

By strict sub and super-solutions we understand functions (ψ_1, ψ_2) and (z_1, z_2) for which strict inequalities (3) and (4) hold.

Our multiplicity results are obtained by constructing sub and super-solution pairs that satisfy the following lemma.

Lemma 1 ([6, 9, 11]) Suppose that the system (2) has a sub-solution (ψ_1, ψ_2) , a strict super-solution (ζ_1, ζ_2) , a strict sub-solution (w_1, w_2) , and a super-solution (z_1, z_2) for the system (2) such that

$$(\psi_1, \psi_2) \le (\zeta_1, \zeta_2) \le (z_1, z_2),$$

 $(\psi_1, \psi_2) \le (w_1, w_2) \le (z_1, z_2),$

and $(w_1, w_2) \nleq (\zeta_1, \zeta_2)$. Then the system (2) has at least three distinct solutions (u_i, v_i) , i = 1, 2, 3 such that

$$(u_1, v_1) \in [(\psi_1, \psi_2), (\zeta_1, \zeta_2)], \ (u_2, v_2) \in [(w_1, w_2), (z_1, z_2)]$$

and

$$(u_3, v_3) \in \left[(\psi_1, \psi_2), (z_1, z_2) \right] \setminus \left(\left[(\psi_1, \psi_2), (\zeta_1, \zeta_2) \right] \cup \left[(w_1, w_2), (z_1, z_2) \right] \right).$$

To precisely state our existence result we consider the unique classical solution e_r of the following linear elliptic problem

$$\left\{ \begin{array}{ll} -\Delta e_r = 1, & x \in \Omega, \\ \mathbf{n}.\nabla e_r + r_0 e_r = 0, & x \in \partial \Omega \end{array} \right.$$

for r = a, b, where $r_0 = r(0)$. Then we establish the following theorem.

Theorem 1 Let (H1)–(H3) hold and f(0) or g(0) be strictly positive. Then the system (2) has a positive solution (u, v) for all $\lambda > 0$.

Proof. It is easy to see that $(\psi_1, \psi_2) = (0, 0)$ is a subsolution of the system (2). We now construct the supersolution (z_1, z_2) . Let $(z_1, z_2) = (C_{\lambda} e_a, \lambda g(C_{\lambda} || e_b ||_{\infty}) e_b)$, where C_{λ} is a large number to be chosen later. We shall verify that (z_1, z_2) is a supersolution of the system (2) for all $\lambda > 0$. By (H2) we can choose C_{λ} large enough so that

$$C_{\lambda} \ge \lambda f \Big(\lambda g(C_{\lambda} \| e_b \|_{\infty}) \| e_b \|_{\infty} \Big),$$

and therefore

$$\begin{aligned} -\Delta z_1 &= C_{\lambda} \ge \lambda f \Big(\lambda g(C_{\lambda} \| e_b \|_{\infty}) \| e_b \|_{\infty} \Big) \\ &\ge \lambda f \Big(\lambda g(C_{\lambda} \| e_b \|_{\infty}) e_b \Big) \\ &= \lambda f(z_2) \text{ in } \Omega, \end{aligned}$$

and

$$\mathbf{n} \cdot \nabla z_1 + a(z_1)z_1 \geq C_{\lambda} \mathbf{n} \cdot \nabla e_a + C_{\lambda} e_a a_0$$

= $C_{\lambda} (\mathbf{n} \cdot \nabla e_a + e_a a_0)$
= $0 \text{ on } \partial \Omega.$

Next,

$$-\Delta z_2 = \lambda g \Big(C_\lambda \| e_b \|_\infty \Big) \ge \lambda g \Big(C_\lambda e_b \Big) = \lambda g(z_1), \text{ in } \Omega,$$

and

$$\mathbf{n} \cdot \nabla z_2 + b(z_2) z_2 \geq \lambda g \Big(C_\lambda \| e_b \|_\infty \Big) \mathbf{n} \cdot \nabla e_b + \lambda g \Big(C_\lambda \| e_b \|_\infty \Big) e_b b_0$$
$$= \lambda g \Big(C_\lambda \| e_b \|_\infty \Big) (\mathbf{n} \cdot \nabla e_b + b_0 e_b) = 0, \text{ on } \partial \Omega$$

which implies that (z_1, z_2) is indeed a positive supersolution of the system (2). Therefore the system (2) has a positive solution for all $\lambda > 0$.

Our second result concerns with multiplicity of solution for the system (2) and gives an estimate on the parameter λ when such a situation occurs. For positive constants $a_i, b_i; i = 1, 2$, define

$$Q_1(a_1, b_1) = \min\{\frac{a_1}{f(b_1)}, \frac{b_1}{g(a_1)}\}$$

and

$$Q_2(a_2, b_2) = \max\{\frac{a_2}{f(b_2)}, \frac{b_2}{g(a_2)}\}.$$

Then we establish:

Theorem 2 Assume f(0) or g(0) be positive. Let B_R be the largest ball of radius R inscribed in Ω , for $0 < \epsilon < R$, we define

$$C_1(\Omega) = \inf_{\epsilon} \frac{N}{\epsilon^N} \frac{R^{N-1}}{R-\epsilon},$$

and $C(\Omega) = C_1(\Omega) \|e_r\|_{\infty}$, for r = a, b. Let (H1)-(H3) hold and $\frac{Q_1}{Q_2} > C(\Omega)$ for some $a_i, b_i, i = 1, 2$. Then the system (2) has at least three positive solutions for $\lambda \in (\lambda_*, \lambda^*)$, where $\lambda_* = CQ_2$ and $\lambda^* = \frac{Q_1}{\|e_r\|_{\infty}}$, for r = a, b.

Proof. We will establish a pair of subsolutions (ψ_1, ψ_2) , (w_1, w_2) and a pair of supersolutions (ζ_1, ζ_2) ,

 $(z_1, z_2), \text{ satisfying Lemma 1. Clearly } (\psi_1, \psi_2) = (0, 0) \text{ is a subsolution of the system (2)}.$ We next construct a positive supersolution $(\zeta_1, \zeta_2), \text{ of the system (2) when } \lambda < \frac{Q_1}{\|e_r\|_{\infty}}, \text{ for } r = a, b. \text{ Since } \lambda < \frac{a_1}{f(b_1)\|e_a\|_{\infty}}, \text{ we can choose } \epsilon > 0 \text{ so small that } \lambda f(b_1) < \frac{a_1}{\epsilon + \|e_a\|_{\infty}}.$ Let

$$(\zeta_1, \zeta_2) = (a_1 \frac{e_a + \epsilon}{\|e_a\|_{\infty} + \epsilon}, b_1 \frac{e_b + \epsilon}{\|e_b\|_{\infty} + \epsilon}).$$

Then, we have

$$-\Delta \zeta_1 = \frac{a_1}{\epsilon + \|e_a\|_{\infty}} > \lambda f(b_1)$$

$$\geq \lambda f\left(b_1 \frac{e_b + \epsilon}{\|e_b\|_{\infty} + \epsilon}\right)$$

$$= \lambda f(\zeta_2) \text{ in } \Omega,$$

and

$$\mathbf{n} \cdot \nabla \zeta_1 + a(\zeta_1)\zeta_1 \geq \frac{a_1}{\epsilon + \|e_a\|_{\infty}} \Big(\mathbf{n} \cdot \nabla e_a + (e_a + \epsilon)a_0 \Big)$$
$$= \frac{a_1}{\epsilon + \|e_a\|_{\infty}} (\mathbf{n} \cdot \nabla e_a + a_0 e_a + a_0 \epsilon)$$
$$= \frac{a_1 a_0 \epsilon}{\epsilon + \|e_a\|_{\infty}}$$
$$> 0 \text{ on } \partial \Omega.$$

Similar argument shows that ζ_2 satisfies $-\Delta\zeta_2 > \lambda g(\zeta_1)$ in Ω , and $\mathbf{n} \cdot \nabla \zeta_2 + b(\zeta_2)\zeta_2 > 0$.

Next let us construct a strict sub-solution (w_1, w_2) of the system (2). First note that a system

$$\begin{cases} -\Delta u_D = \lambda f(v_D), & x \in \Omega, \\ -\Delta v_D = \lambda g(u_D), & x \in \Omega, \\ u_D = 0 = v_D, & x \in \partial \Omega \end{cases}$$

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admits a strict sub-solution (w_{1D}, w_{2D}) with $||w_{1D}||_{\infty} \ge a_2$ and $||w_{2D}||_{\infty} \ge b_2$ provided $\lambda < \lambda^*$ (see [1]). Then we have $(w_1, w_2) \not\le (\zeta_1, \zeta_2)$. From Hopf's lemma, $\mathbf{n} \cdot \nabla w_{iD} < 0$ for i = 1, 2. Therefore, setting $w_1 = w_{1D}$ and $w_2 = w_{2D}$ we obtain a strict sub-solution for the system (2). for $\lambda > \lambda_*$.

Let (z_1, z_2) be the super solution as in the proof of Theorem 2 Further, $w_i, \zeta_i \leq z_i, i = 1, 2$ for C_{λ} large. Hence there exist positive solutions $(u_i, v_i), i = 1, 2, 3$ such that

$$(u_1, v_1) \in [(\psi_1, \psi_2), (\zeta_1, \zeta_2)], \ (u_2, v_2) \in [(w_1, w_2), (z_1, z_2)]$$

and

$$(u_3, v_3) \in \left[(\psi_1, \psi_2), (z_1, z_2) \right] \setminus \left(\left[(\psi_1, \psi_2), (\zeta_1, \zeta_2) \right] \cup \left[(w_1, w_2), (z_1, z_2) \right] \right).$$

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