

# On $h(x)$ Lucas $p$ -Polynomials\*

Bandhu Prasad†

Received 29 October 2023

## Abstract

In this paper,  $h(x)$  Lucas  $p$ -polynomials and a new Lucas  $Q_{p,h}(x)$  matrix are defined where  $p(\geq 0)$  is an integer and  $h(x)(> 0)$  is a polynomial with real coefficients. The properties of  $Q_{p,h}(x)$  matrix, relations among the code matrix elements and correct ability are mentioned.

## 1 Introduction

The Lucas  $p$ -numbers [3] are given by the recurrence relation

$$L_p(n) = L_p(n-1) + L_p(n-p-1)$$

with  $n > p+1$  and initial seeds

$$L_p(1) = L_p(2) = \cdots = L_p(p) = 1, \quad L_p(p+1) = p+2$$

where  $p = 0, 1, 2, \dots$ .

For  $p = 1$ ,  $L_1(n) = L_n$  are known as classical Lucas numbers. The ratio of two consecutive Lucas numbers converges to the irrational number,  $\mu = \lim_{n \rightarrow \infty} \frac{L_{n+1}}{L_n} = \frac{1+\sqrt{5}}{2}$  which is known as golden mean or golden ratio or golden proportion. The Lucas numbers and golden mean are useful in physical sciences, chemical sciences, mathematical sciences, computer sciences, biological sciences, architectures and arts [7, 8, 9, 10, 11, 15].

Extensions of Lucas  $p$ -numbers [4] are given by the recurrence relation

$$L_{p,m}(n) = mL_{p,m}(n-1) + L_{p,m}(n-p-1)$$

with initial seeds

$$L_{p,m}(1) = a_1, L_{p,m}(2) = a_2, L_{p,m}(3) = a_3, \dots, L_{p,m}(p+1) = a_{p+1}$$

where  $p(\geq 0)$  is integer,  $m(> 0)$ ,  $n > p+1$  and  $a_1, a_2, a_3, \dots, a_{p+1}$  are arbitrary real or complex numbers.

Different types of polynomials are given by Lucas-like recurrence relations. Such polynomials are known as Lucas polynomials. Lucas polynomials,  $L_n(x)$  given by the recurrence relation

$$L_n(x) = xL_{n-1}(x) + L_{n-2}(x), \quad n \geq 2$$

with initial seeds

$$L_0(x) = 2, \quad L_1(x) = x.$$

$h(x)$  Lucas polynomials,  $L_{h,n}(x)$  (where  $h(x)$  is a polynomial with real coefficients) are given by Nalli and Haukkanen [5] as follows:

$$L_{h,n+1}(x) = h(x)L_{h,n}(x) + L_{h,n-1}(x), \quad n \geq 1$$

with initial seeds

$$L_{h,0}(x) = 2, \quad L_{h,1}(x) = h(x).$$

\*Mathematics Subject Classifications: 11B39, 94B35, 94B25, 11T71.

†Department of Mathematics, Kandi Raj College, Kandi 742137, India

In this paper, we introduce  $h(x)(>0)$  Lucas  $p$ -polynomials,  $L_{p,h}(n, x)$  by the recurrence relation

$$L_{p,h}(n, x) = h(x)L_{p,h}(n-1, x) + L_{p,h}(n-p-1, x)$$

with initial seeds

$$L_{p,h}(1, x) = b_1, \quad L_{p,h}(2, x) = b_2, \quad L_{p,h}(3, x) = b_3, \dots, \quad L_{p,h}(p+1, x) = b_{p+1}$$

where  $p (\geq 0)$  is integer,  $h(x) (> 0)$  is a polynomial with real coefficients,  $n > p+1$  and  $b_1, b_2, b_3, \dots, b_{p+1}$  are arbitrary real or complex numbers.

### 1.1 $h(x)$ Lucas $p$ -Polynomials, $L_{p,h}(n, x)$

We consider the recurrence relation for integer  $p (\geq 0)$ ,  $h(x)(>0)$  and  $n = 0, \pm 1, \pm 2, \pm 3, \dots$ ,

$$L_{p,h}(n, x) = h(x)L_{p,h}(n-1, x) + L_{p,h}(n-p-1, x) \quad (1)$$

with the initial seeds

$$L_{p,h}(n, x) = h^{n-1}(x), \quad n = 1, 2, 3, \dots, p+1. \quad (2)$$

With the help of (1) and (2) we get the following table: Thus, we get  $h(x)$  Lucas  $p$ -polynomials,

Table 1:  $h(x)$  Lucas  $p$ -polynomials,  $L_{p,h}(n, x)$

$n \rightarrow$	...	0	-1	...	$-p+1$	$-p$	$-p-1$	...	$-2p+1$	$-2p$	$-2p-1$	$-2p-2$	...
$L_{p,h}(n, x)$	...	0	0	...	0	1	0	...	0	$-h(x)$	1	0	...

$$L_{p,h}(n, x) = h(x)L_{p,h}(n-1, x) + L_{p,h}(n-p-1, x) \quad (3)$$

for  $h(x)(>0)$ ,  $n = 0, \pm 1, \pm 2, \pm 3, \dots$  and  $p = 0, 1, 2, 3, \dots$ , where  $L_{p,h}(n, x) = h^{n-1}(x)$ ,  $n = 1, 2, 3, 4, \dots, p+1$ . The characteristic equation of  $h(x)$  Lucas  $p$ -polynomials are given by

$$y^{p+1} - h(x)y^p - 1 = 0. \quad (4)$$

The equation (4) has  $(p+1)$  roots. The only one positive root  $y = \mu_{p,h}(x)$ , called golden  $(p, h(x))$ -proportion, coincides with  $\mu_{p,m}$ , golden  $(p, m)$ -proportion when  $h(x) = m$ . Also when  $h(x) = 1$ ,  $\mu_{p,h}(x)$  coincides with  $\mu_p$ , golden  $p$ -proportion.

In section 2,  $Q_{p,h}(x)$  matrix are defined and the properties of  $Q_{p,h}(x)$  matrix are illustrated. In section 3, Lucas coding and decoding method are presented with an example. In section 4, code matrix is defined. In section 5, relations among the code matrix elements on  $h(x)$  Lucas  $p$ -polynomials are established. We also show that the relations, among the code matrix elements for  $h(x) = m(>0)$ , coincide with the relations among the code matrix elements for the  $m$ -extension of the Lucas  $p$ -numbers in information theory [1] and the relations among the code matrix elements for  $h(x) = 1$ , coincide with the generalized relations among the code matrix elements for the coding theory on Lucas  $p$  numbers [2]. In section 6, error detection and correction are described as in [2].

## 2 Lucas $Q_{p,h}(x)$ Matrix

In this paper, we define a new matrix called Lucas  $Q_{p,h}(x)$  matrix of order  $(p+1)$  on  $h(x)$  Lucas  $p$ -polynomial where  $p (\geq 0)$  is an integer and  $h(x) (> 0)$  is a polynomial with real coefficients. The  $Q_{p,h}(x)$  matrix is given

by

$$\begin{aligned}
 Q_{p,h}(x) &= \begin{pmatrix} h(x) & 1 & 0 & 0 & 0 & \cdots & 0 \\ 0 & 0 & 1 & 0 & 0 & \cdots & 0 \\ 0 & 0 & 0 & 1 & 0 & \cdots & 0 \\ 0 & 0 & 0 & 0 & 1 & \cdots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & 0 & 0 & \cdots & 1 \\ 1 & 0 & 0 & 0 & 0 & \cdots & 0 \end{pmatrix} \\
 &= \begin{pmatrix} L_{p,h}(2, x) & L_{p,h}(1, x) & \cdots & L_{p,h}(3-p, x) & L_{p,h}(2-p, x) \\ L_{p,h}(2-p, x) & L_{p,h}(1-p, x) & \cdots & L_{p,h}(3-2p, x) & L_{p,h}(2-2p, x) \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ L_{p,h}(0, x) & L_{p,h}(-1, x) & \cdots & L_{p,h}(1-p, x) & L_{p,h}(-p, x) \\ L_{p,h}(1, x) & L_{p,h}(0, x) & \cdots & L_{p,h}(2-p, x) & L_{p,h}(1-p, x) \end{pmatrix}
 \end{aligned}$$

by using (2).

For examples,

$$Q_{1,h}(x) = \begin{pmatrix} h(x) & 1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} L_{1,h}(2, x) & L_{1,h}(1, x) \\ L_{1,h}(1, x) & L_{1,h}(0, x) \end{pmatrix},$$

$$\text{Det } Q_{1,h}(x) = -1 = (-1)^1.$$

$$Q_{2,h}(x) = \begin{pmatrix} h(x) & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix} = \begin{pmatrix} L_{2,h}(2, x) & L_{2,h}(1, x) & L_{2,h}(0, x) \\ L_{2,h}(0, x) & L_{2,h}(-1, x) & L_{2,h}(-2, x) \\ L_{2,h}(1, x) & L_{2,h}(0, x) & L_{2,h}(-1, x) \end{pmatrix},$$

$$\text{Det } Q_{2,h}(x) = 1 = (-1)^2,$$

$$Q_{3,h}(x) = \begin{pmatrix} h(x) & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} L_{3,h}(2, x) & L_{3,h}(1, x) & L_{3,h}(0, x) & L_{3,h}(-1, x) \\ L_{3,h}(-1, x) & L_{3,h}(-2, x) & L_{3,h}(-3, x) & L_{3,h}(-4, x) \\ L_{3,h}(0, x) & L_{3,h}(-1, x) & L_{3,h}(-2, x) & L_{3,h}(-3, x) \\ L_{3,h}(1, x) & L_{3,h}(0, x) & L_{3,h}(-1, x) & L_{3,h}(-2, x) \end{pmatrix},$$

$$\text{Det } Q_{3,h}(x) = -1 = (-1)^3,$$

$$\begin{aligned}
 Q_{4,h}(x) &= \begin{pmatrix} h(x) & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 & 0 \end{pmatrix} \\
 &= \begin{pmatrix} L_{4,h}(2, x) & L_{4,h}(1, x) & L_{4,h}(0, x) & L_{4,h}(-1, x) & L_{4,h}(-2, x) \\ L_{4,h}(-2, x) & L_{4,h}(-3, x) & L_{4,h}(-4, x) & L_{4,h}(-5, x) & L_{4,h}(-6, x) \\ L_{4,h}(-1, x) & L_{4,h}(-2, x) & L_{4,h}(-3, x) & L_{4,h}(-4, x) & L_{4,h}(-5, x) \\ L_{4,h}(0, x) & L_{4,h}(-1, x) & L_{4,h}(-2, x) & L_{4,h}(-3, x) & L_{4,h}(-4, x) \\ L_{4,h}(1, x) & L_{4,h}(0, x) & L_{4,h}(-1, x) & L_{4,h}(-2, x) & L_{4,h}(-3, x) \end{pmatrix},
 \end{aligned}$$

$$\text{Det } Q_{4,h}(x) = 1 = (-1)^4,$$

and so on. Thus,  $\text{Det } Q_{p,h}(x) = (-1)^p$ , which is independent of  $h(x)$ .

## 2.1 Properties of $Q_{p,h}(x)$

**Theorem 1** For a given integer  $n$  ( $n = 0, \pm 1, \pm 2, \pm 3, \dots$ ) the  $n$ th power of the  $Q_{p,h}(x)$  matrix is given by

$$Q_{p,h}^n(x) = \begin{pmatrix} L_{p,h}(n+1, x) & L_{p,h}(n, x) & \cdots & L_{p,h}(n-p+2, x) & L_{p,h}(n-p+1, x) \\ L_{p,h}(n-p+1, x) & L_{p,h}(n-p, x) & \cdots & L_{p,h}(n-2p+2, x) & L_{p,h}(n-2p+1, x) \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ L_{p,h}(n-1, x) & L_{p,h}(n-2, x) & \cdots & L_{p,h}(n-p, x) & L_{p,h}(n-p-1, x) \\ L_{p,h}(n, x) & L_{p,h}(n-1, x) & \cdots & L_{p,h}(n-p+1, x) & L_{p,h}(n-p, x) \end{pmatrix}$$

where  $L_{p,h}(n, x) = h^{n-1}(x)$ ,  $n = 1, 2, 3, 4, \dots, p+1$ .

**Proof.** When  $p = 1$ , we have to prove

$$Q_{1,h}^n(x) = \begin{pmatrix} L_{1,h}(n+1, x) & L_{1,h}(n, x) \\ L_{1,h}(n, x) & L_{1,h}(n-1, x) \end{pmatrix}. \quad (5)$$

We will prove it by mathematical induction. For  $n = 1$ ,

$$Q_{1,h}(x) = \begin{pmatrix} h(x) & 1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} L_{1,h}(2, x) & L_{1,h}(1, x) \\ L_{1,h}(1, x) & L_{1,h}(0, x) \end{pmatrix} \text{ by (2),}$$

which is true for  $n = 1$ . For  $n = 2$ ,

$$Q_{1,h}^2(x) = \begin{pmatrix} h^2(x) + 1 & h(x) \\ h(x) & 1 \end{pmatrix} = \begin{pmatrix} L_{1,h}(3, x) & L_{1,h}(2, x) \\ L_{1,h}(2, x) & L_{1,h}(1, x) \end{pmatrix} \text{ by (2),}$$

which is true for  $n = 2$ . Suppose (5) is true for integer  $n = k$ , then

$$Q_{1,h}^k(x) = \begin{pmatrix} L_{1,h}(k+1, x) & L_{1,h}(k, x) \\ L_{1,h}(k, x) & L_{1,h}(k-1, x) \end{pmatrix}.$$

Now, we can write

$$\begin{aligned} Q_{1,h}^{k+1}(x) &= Q_{1,h}^k(x) Q_{1,h}(x) = \begin{pmatrix} L_{1,h}(k+1, x) & L_{1,h}(k, x) \\ L_{1,h}(k, x) & L_{1,h}(k-1, x) \end{pmatrix} \begin{pmatrix} h(x) & 1 \\ 1 & 0 \end{pmatrix} \\ &= \begin{pmatrix} L_{1,h}(k+2, x) & L_{1,h}(k+1, x) \\ L_{1,h}(k+1, x) & L_{1,h}(k, x) \end{pmatrix} \text{ by (2).} \end{aligned}$$

Hence by mathematical induction, we proved that

$$Q_{1,h}^n(x) = \begin{pmatrix} L_{1,h}(n+1, x) & L_{1,h}(n, x) \\ L_{1,h}(n, x) & L_{1,h}(n-1, x) \end{pmatrix}.$$

When  $p = 2$ , we have to prove

$$Q_{2,h}^n(x) = \begin{pmatrix} L_{2,h}(n+1, x) & L_{2,h}(n, x) & L_{2,h}(n-1, x) \\ L_{2,h}(n-1, x) & L_{2,h}(n-2, x) & L_{2,h}(n-3, x) \\ L_{2,h}(n, x) & L_{2,h}(n-1, x) & L_{2,h}(n-2, x) \end{pmatrix}. \quad (6)$$

We will prove it by mathematical induction. For  $n = 1$ ,

$$Q_{2,h}(x) = \begin{pmatrix} h(x) & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix} = \begin{pmatrix} L_{2,h}(2, x) & L_{2,h}(1, x) & L_{2,h}(0, x) \\ L_{2,h}(0, x) & L_{2,h}(-1, x) & L_{2,h}(-2, x) \\ L_{2,h}(1, x) & L_{2,h}(0, x) & L_{2,h}(-1, x) \end{pmatrix} \text{ by (2),}$$

which is true for  $n = 1$ .

For  $n = 2$ ,

$$Q_{2,h}^2(x) = \begin{pmatrix} h^2(x) & h(x) & 1 \\ 1 & 0 & 0 \\ h(x) & 1 & 0 \end{pmatrix} = \begin{pmatrix} L_{2,h}(3, x) & L_{2,h}(2, x) & L_{2,h}(1, x) \\ L_{2,h}(1, x) & L_{2,h}(0, x) & L_{2,h}(-1, x) \\ L_{2,h}(2, x) & L_{2,h}(1, x) & L_{2,h}(0, x) \end{pmatrix} \quad \text{by (2),}$$

which is true for  $n = 2$ .

Suppose (6) is true for integer  $n = k$ , then

$$Q_{2,h}^k(x) = \begin{pmatrix} L_{2,h}(k+1, x) & L_{2,h}(k, x) & L_{2,h}(k-1, x) \\ L_{2,h}(k-1, x) & L_{2,h}(k-2, x) & L_{2,h}(k-3, x) \\ L_{2,h}(k, x) & L_{2,h}(k-1, x) & L_{2,h}(k-2, x) \end{pmatrix}.$$

Now, we can write

$$\begin{aligned} Q_{2,h}^{k+1}(x) &= Q_{2,h}^k(x) Q_{2,h}(x) \\ &= \begin{pmatrix} L_{2,h}(k+1, x) & L_{2,h}(k, x) & L_{2,h}(k-1, x) \\ L_{2,h}(k-1, x) & L_{2,h}(k-2, x) & L_{2,h}(k-3, x) \\ L_{2,h}(k, x) & L_{2,h}(k-1, x) & L_{2,h}(k-2, x) \end{pmatrix} \begin{pmatrix} h(x) & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix} \\ &= \begin{pmatrix} L_{2,h}(k+2, x) & L_{2,h}(k+1, x) & L_{2,h}(k, x) \\ L_{2,h}(k, x) & L_{2,h}(k-1, x) & L_{2,h}(k-2, x) \\ L_{2,h}(k+1, x) & L_{2,h}(k, x) & L_{2,h}(k-1, x) \end{pmatrix} \quad \text{by (2).} \end{aligned}$$

Hence by mathematical induction, we proved that

$$Q_{2,h}^n(x) = \begin{pmatrix} L_{2,h}(n+1, x) & L_{2,h}(n, x) & L_{2,h}(n-1, x) \\ L_{2,h}(n-1, x) & L_{2,h}(n-2, x) & L_{2,h}(n-3, x) \\ L_{2,h}(n, x) & L_{2,h}(n-1, x) & L_{2,h}(n-2, x) \end{pmatrix}.$$

Therefore, by mathematical induction it can be proved for all values of  $p$ . Hence the theorem. ■

**Theorem 2**  $Q_{p,h}^n(x) = h(x)Q_{p,h}^{n-1}(x) + Q_{p,h}^{n-(p+1)}(x)$ .

**Proof.** By Theorem 1,

$$Q_{p,h}^n(x) = \begin{pmatrix} L_{p,h}(n+1, x) & L_{p,h}(n, x) & \cdots & L_{p,h}(n-p+2, x) & L_{p,h}(n-p+1, x) \\ L_{p,h}(n-p+1, x) & L_{p,h}(n-p, x) & \cdots & L_{p,h}(n-2p+2, x) & L_{p,h}(n-2p+1, x) \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ L_{p,h}(n-1, x) & L_{p,h}(n-2, x) & \cdots & L_{p,h}(n-p, x) & L_{p,h}(n-p-1, x) \\ L_{p,h}(n, x) & L_{p,h}(n-1, x) & \cdots & L_{p,h}(n-p+1, x) & L_{p,h}(n-p, x) \end{pmatrix}.$$

When  $p = 1$ ,

$$\begin{aligned} Q_{1,h}^n(x) &= \begin{pmatrix} L_{1,h}(n+1, x) & L_{1,h}(n, x) \\ L_{1,h}(n, x) & L_{1,h}(n-1, x) \end{pmatrix} \\ &= \begin{pmatrix} h(x)L_{1,h}(n, x) + L_{1,h}(n-1, x) & h(x)L_{1,h}(n-1, x) + L_{1,h}(n-2, x) \\ h(x)L_{1,h}(n-1, x) + L_{1,h}(n-2, x) & h(x)L_{1,h}(n-2, x) + L_{1,h}(n-3, x) \end{pmatrix} \\ &= h(x)Q_{1,h}^{n-1}(x) + Q_{1,h}^{n-2}(x). \end{aligned}$$

When  $p = 2$ ,

$$\begin{aligned}
 & Q_{2,h}^n(x) \\
 = & \begin{pmatrix} L_{2,h}(n+1, x) & L_{2,h}(n, x) & L_{2,h}(n-1, x) \\ L_{2,h}(n-1, x) & L_{2,h}(n-2, x) & L_{2,h}(n-3, x) \\ L_{2,h}(n, x) & L_{2,h}(n-1, x) & L_{2,h}(n-2, x) \end{pmatrix} \\
 = & \begin{pmatrix} h(x)L_{2,h}(n, x) + L_{2,h}(n-2, x) & h(x)L_{2,h}(n-1, x) + L_{2,h}(n-3, x) & h(x)L_{2,h}(n-2, x) + L_{2,h}(n-4, x) \\ h(x)L_{2,h}(n-2, x) + L_{2,h}(n-4, x) & h(x)L_{2,h}(n-3, x) + L_{2,h}(n-5, x) & h(x)L_{2,h}(n-4, x) + L_{2,h}(n-6, x) \\ h(x)L_{2,h}(n-1, x) + L_{2,h}(n-3, x) & h(x)L_{2,h}(n-2, x) + L_{2,h}(n-4, x) & h(x)L_{2,h}(n-3, x) + L_{2,h}(n-5, x) \end{pmatrix} \\
 = & h(x)Q_{2,h}^{n-1}(x) + Q_{2,h}^{n-3}(x).
 \end{aligned}$$

Similarly, we can show that,

$$Q_{p,h}^n(x) = h(x)Q_{p,h}^{n-1}(x) + Q_{p,h}^{n-(p+1)}(x).$$

Hence, the properties of  $Q_{p,h}^n(x)$  can be summarized as

- (i)  $Q_{p,h}^n(x) = h(x)Q_{p,h}^{n-1}(x) + Q_{p,h}^{n-(p+1)}(x)$ .
- (ii)  $\text{Det}(Q_{p,h}^n(x)) = [\text{Det}(Q_{p,h}(x))]^n = (-1)^{pn}$ , which is independent of  $h(x)$ .
- (iii) By inverse matrix method, we get  $Q_{p,h}^{-n}(x)$  from  $Q_{p,h}^n(x)$ .

For a particular case  $p = 1$ ,  $Q_{1,h}^{-n}(x)$  is given by

$$\begin{aligned}
 Q_{1,h}^{-n}(x) &= \begin{pmatrix} L_{2,h}(2k-1, x) & -L_{2,h}(2k, x) \\ -L_{2,h}(2k, x) & L_{2,h}(2k+1, x) \end{pmatrix}, \quad n = 2k, \text{ even}, \\
 Q_{1,h}^{-n}(x) &= \begin{pmatrix} -L_{2,h}(2k, x) & L_{2,h}(2k+1, x) \\ L_{2,h}(2k+1, x) & -L_{2,h}(2k+2, x) \end{pmatrix}, \quad n = 2k+1, \text{ odd},
 \end{aligned}$$

where  $p = 1, 2, 3, \dots$  and  $n = 0, \pm 1, \pm 2, \pm 3, \dots$ . ■

### 3 Lucas $Q_{p,h}(x)$ Coding and Decoding Method

Lucas  $Q_{p,h}(x)$  matrix is used to develop applications of the coding theory. We represent the initial message in the form of the square matrix,  $M$  of order  $(p+1)$  where  $p = 1, 2, 3, \dots$ . We take  $Q_{p,h}^n(x)$  matrix of order  $(p+1)$  as a coding matrix and its inverse matrix  $Q_{p,h}^{-n}(x)$  as a decoding matrix. We make a transformation  $M \times Q_{p,h}^n(x) = E$  as coding and a transformation  $E \times Q_{p,h}^{-n}(x) = M$  as decoding. We represent  $E$  as code matrix.

#### 3.1 Example of Lucas $Q_{p,h}(x)$ Coding and Decoding Method

We represent the initial message in form of the square matrix of order 2

$$M = \begin{pmatrix} m_1 & m_2 \\ m_3 & m_4 \end{pmatrix}.$$

Let us assume that all elements of the matrix are positive integers i.e.,  $m_1, m_2, m_3, m_4 > 0$ . For  $p = 1$ , let us select  $Q_{1,h}^n(x)$  matrix as the coding matrix for any value of  $n$ . For  $n = 4$ , we have

$$Q_{1,h}^4(x) = \begin{pmatrix} h^4(x) + 3h^2(x) + 1 & h^3(x) + 2h(x) \\ h^3(x) + 2h(x) & h^2(x) + 1 \end{pmatrix}.$$

So

$$Q_{1,h}^{-4}(x) = \begin{pmatrix} h^2(x) + 1 & -h^3(x) - 2h(x) \\ -h^3(x) - 2h(x) & h^4(x) + 3h^2(x) + 1 \end{pmatrix}.$$

Then the  $Q_{1,h}^4(x)$  coding of the message,  $M$  consists of the multiplication of the message,  $M$  by the matrix  $Q_{1,h}^4(x)$  that is

$$\begin{aligned} M \times Q_{1,h}^4(x) &= \begin{pmatrix} m_1 & m_2 \\ m_3 & m_4 \end{pmatrix} \begin{pmatrix} h^4(x) + 3h^2(x) + 1 & h^3(x) + 2h(x) \\ h^3(x) + 2h(x) & h^2(x) + 1 \end{pmatrix} \\ &= \begin{pmatrix} m_1(h^4(x) + 3h^2(x) + 1) + m_2(h^3(x) + 2h(x)) & m_1(h^3(x) + 2h(x)) + m_2(h^2(x) + 1) \\ m_3(h^4(x) + 3h^2(x) + 1) + m_4(h^3(x) + 2h(x)) & m_3(h^3(x) + 2h(x)) + m_4(h^2(x) + 1) \end{pmatrix} \\ &= \begin{pmatrix} e_1 & e_2 \\ e_3 & e_4 \end{pmatrix} = E \end{aligned} \quad (7)$$

where

$$e_1 = m_1(h^4(x) + 3h^2(x) + 1) + m_2(h^3(x) + 2h(x))$$

$$e_2 = m_1(h^3(x) + 2h(x)) + m_2(h^2(x) + 1),$$

$$e_3 = m_3(h^4(x) + 3h^2(x) + 1) + m_4(h^3(x) + 2h(x)),$$

$$e_4 = m_3(h^3(x) + 2h(x)) + m_4(h^2(x) + 1).$$

Then the code message,  $E$  is sent to the channel. The decoding of the code message,  $E$  is given by

$$\begin{aligned} &\begin{pmatrix} e_1 & e_2 \\ e_3 & e_4 \end{pmatrix} \begin{pmatrix} h^2(x) + 1 & -h^3(x) - 2h(x) \\ -h^3(x) - 2h(x) & h^4(x) + 3h^2(x) + 1 \end{pmatrix} \\ &= \begin{pmatrix} e_1(h^2(x) + 1) + e_2(-h^3(x) - 2h(x)) & e_1(-h^3(x) - 2h(x)) + e_2(h^4(x) + 3h^2(x) + 1) \\ e_3(h^2(x) + 1) + e_4(-h^3(x) - 2h(x)) & e_3(-h^3(x) - 2h(x)) + e_4(h^4(x) + 3h^2(x) + 1) \end{pmatrix} \\ &= \begin{pmatrix} m_1 & m_2 \\ m_3 & m_4 \end{pmatrix} = M. \end{aligned}$$

## 4 Determinant of the Code Matrix, $E$

The code matrix,  $E$  is given by the following formula  $E = M \times Q_{p,h}^n(x)$ . From the matrix theory [6] we have

$$\text{Det } E = \text{Det } (M \times Q_{p,h}^n(x)) = \text{Det } M \times \text{Det } Q_{p,h}^n(x) = \text{Det } M \times (-1)^{pn} = (-1)^{pn} \times \text{Det } M. \quad (8)$$

## 5 Relations Among the Code Matrix Elements on $h(x)$ Lucas $p$ -Polynomials

### 5.1 Case 1: $p = 1$

Similar to [2], we obtain

$$\frac{e_1}{e_2} \approx \mu_{1,h}(x) \quad \text{and} \quad \frac{e_3}{e_4} \approx \mu_{1,h}(x)$$

where  $\mu_{1,h}(x) = \frac{h(x) + \sqrt{h^2(x) + 4}}{2}$ ,  $e_1, e_2, e_3, e_4$  are given in (7).

### 5.2 Case 2: $p = 2$

In this case, let the message,

$$M = \begin{pmatrix} m_1 & m_2 & m_3 \\ m_4 & m_5 & m_6 \\ m_7 & m_8 & m_9 \end{pmatrix}.$$

Then, the  $Q_{2,h}^n(x)$  coding of the message,  $M$  is

$$M \times Q_{2,h}^n(x) = \begin{pmatrix} e_1 & e_2 & e_3 \\ e_4 & e_5 & e_6 \\ e_7 & e_8 & e_9 \end{pmatrix} = E.$$

Similar to [2], we obtain

$$\begin{aligned} \frac{e_1}{e_2} &\approx \mu_{2,h}(x), & \frac{e_2}{e_3} &\approx \mu_{2,h}(x), & \frac{e_1}{e_3} &\approx \mu_{2,h}^2(x), \\ \frac{e_4}{e_5} &\approx \mu_{2,h}(x), & \frac{e_5}{e_6} &\approx \mu_{2,h}(x), & \frac{e_4}{e_6} &\approx \mu_{2,h}^2(x), \\ \frac{e_7}{e_8} &\approx \mu_{2,h}(x), & \frac{e_8}{e_9} &\approx \mu_{2,h}(x), & \frac{e_7}{e_9} &\approx \mu_{2,h}^2(x), \end{aligned}$$

where

$$\mu_{2,h}(x) = \frac{s^2 + 2sh(x) + 4h^2(x)}{6s} \quad \text{and} \quad s = \sqrt{108 + 8h^3(x) + 12\sqrt{81 + 12h^3(x)}}.$$

### 5.3 Case 3: Generalized Relations Among the Code Elements

In general, similar to [2], when  $p = t$  and  $n > p + 1 = t + 1$ , The generalized relations among the code matrix elements are

$$\frac{e_1}{e_2} \approx \mu_{t,h}(x); \quad \frac{e_2}{e_3} \approx \mu_{t,h}(x); \quad \dots; \quad \frac{e_t}{e_{t+1}} \approx \mu_{t,h}(x),$$

$$\frac{e_1}{e_3} \approx \mu_{t,h}^2(x); \quad \frac{e_2}{e_4} \approx \mu_{t,h}^2(x); \quad \dots; \quad \frac{e_{t-1}}{e_{t+1}} \approx \mu_{t,h}^2(x),$$

...

...

$$\frac{e_1}{e_{t+1}} \approx \mu_{t,h}^t(x),$$

where  $e_1, e_2, e_3, \dots, e_t, e_{t+1}$  are the first row elements of the code matrix,  $E$ . We also obtain similar type of relations among the elements of the second row, third row,  $\dots$ ,  $(t+1)$ th row of the code matrix,  $E$  where  $\mu_{t,h}(x)$  is golden  $(t, h(x))$ -proportion.

## 6 Error Detection and Correction

The error-correcting codes [12, 13]) are used widely in information and communication system for the protection of the data from noise. The main purpose of the coding theory are the detection and correction of errors arising in the code message,  $E$  under influence of noise in the communication channel. For the Lucas coding and decoding method the correct ability is 93.33% like to [2] and it does not depend on  $h(x)$  for a case  $p = 1$ . Also, the correct ability of this method is 99.80% for  $p = 2$  [2]. In general, for  $p = t$  and  $n > p + 1 = t + 1$  the correct ability of this method is  $\frac{2^{(t+1)^2} - 2}{2^{(t+1)^2} - 1}$  which depends on  $p$  but not on  $h(x)$ . Hence, for large value of  $p$  the correct ability of this method is

$$\frac{2^{(p+1)^2} - 2}{2^{(p+1)^2} - 1} \approx 1 = 100\%.$$



## 7 Conclusion

The Lucas coding and decoding method is the main application of the Lucas  $Q_{p,h}(x)$  matrix. The correct ability of this method for the simple case  $p = 1$  is equal 93.33% that exceeds essentially all well-known correcting codes. The correct ability of this method for the case  $p = 2$  is 99.80%. The correct ability of this method increases as  $p$  increases and it is independent of  $h(x)$  but  $h(x)$  being a polynomial, improves the security in coding theory.

In future, we hope that the Lucas  $Q_{p,h}(x)$  matrices have wide applications in mathematics, physics, genetics, chemical sciences, computer sciences, information and coding theory etc. Future works can be extended for some new codes on the  $k$ -Lucas sequence and balancing sequence [14].

**Acknowledgments.** The author would like to thank the reviewers and editor for their valuable comments and suggestion for the improvement of this paper.

## References

- [1] B. Prasad,  $m$  extension of Lucas  $p$ -numbers in information theory, *Jordan J. Math. Stat.*, 12(2019), 541–556.
- [2] B. Prasad, Coding theory on Lucas  $p$ -numbers, *Discrete Math. Algorithms Appl.*, 8(2016), 17 pp.
- [3] A. Stakhov and B. Rozin, Theory of Binet formulas for Fibonacci and Lucas  $p$ -numbers, *Chaos Solitons Fractals*, 27(2006), 1162–1177.
- [4] E. G. Kocer, N. Tuglu and A. Stakhov, On the  $m$  extension of the Fibonacci and Lucas  $p$ -numbers, *Chaos, Solitons and Fractals*, 40(2009), 1890–1906.
- [5] A. Nalli and P. Haukkanen, On generalized Fibonacci and Lucas polynomials, *Chaos, Solitons and Fractals*, 42(2009), 3179–3186.
- [6] F. E. Hohn, *Elementary matrix Algebra*, New York: Macmillan Company, 1973. Third edition. The Macmillan Company, New York; Collier Macmillan Publishers, London, 1973.
- [7] M. S. El Naschie, The theory of cantor space time and high energy particle physics, *Chaos, Solitons and Fractals*, 41(2009), 2635–2646.
- [8] M. Esmaeili, T. A. Gulliver and A. Kakhbod, The Golden mean, Fibonacci matrices and partial weakly super-increasing sources, *Chaos, Solitons and Fractals*, 42(2009), 435–440.
- [9] M. S. El. Naschie, Topics in the mathematical physics of E-infinity theory, *Chaos, Solitons and Fractals*, 30(2006), 656–663.
- [10] V. W. Spinadel, *From the Golden Mean to Chaos*, Buenos Aires: Nueva, Libreria, 1998.
- [11] M. Basu and B. Prasad, Long range variations on the Fibonacci universal code, *J. Number Theory*, 130(2010), 1925–1931.
- [12] F. J. MacWilliams and N. J. A. Sloane, *Theory of Error-correcting Codes*, Amsterdam: North-Holland, 1977.
- [13] R. Blahut, *The Theory and Practice of Error Control Codes*, Addison-Wesley, Reading, MA, 1983.
- [14] E. Mehraban and M. Hashemi, Coding theory on the generalized balancing sequence, *Notes on Number Theory and Discrete Mathematics*, 29(2023), 503–524.
- [15] M. Hashemi and E. Mehraban, Some New Codes on the  $k$ -Fibonacci Sequence, *Mathematical Problems in Engineering*, (2021), 13 pages.