

Remark

$$(\rho, \phi, \theta) \longleftrightarrow (r, \theta, z)$$

$$d\rho d\phi d\theta \longleftrightarrow dr dz d\theta$$

$$(\rho, \phi) \longleftrightarrow (z, r)$$

$$\rho \cos \phi = z, \quad \rho \sin \phi = r$$

$$(R, \theta) \longrightarrow (X, Y)$$

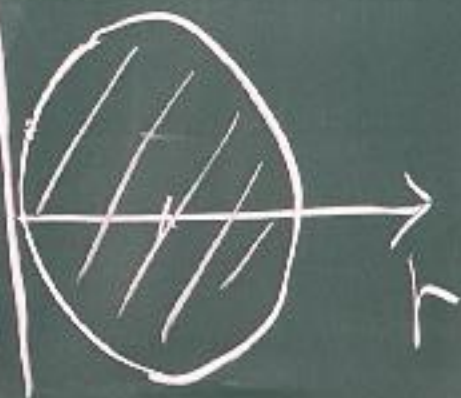
Example: $0 \leq \rho \leq 2 \sin \phi$

$$\rho = 2 \sin \phi \quad 0 \leq \phi \leq \pi$$

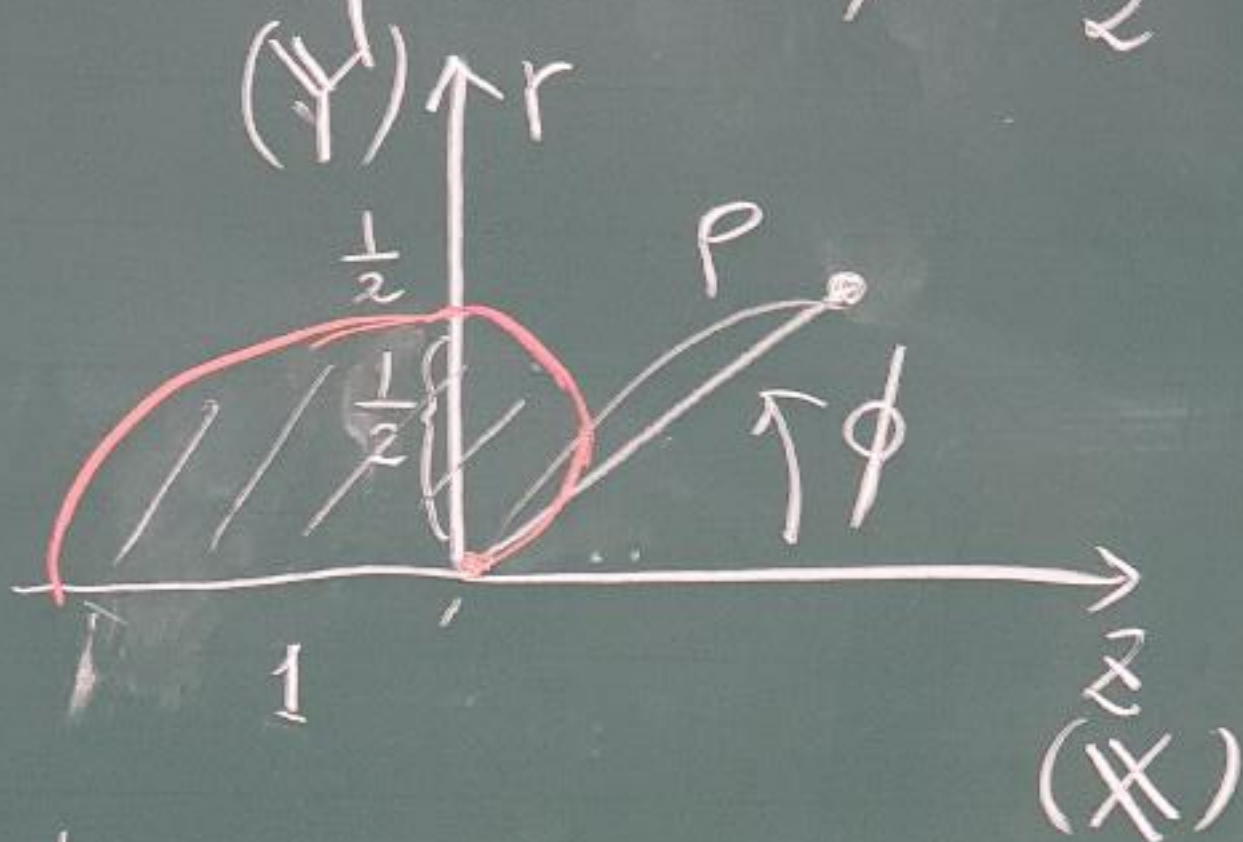
$$\Rightarrow \rho^2 = 2\rho \sin \phi$$

$$\Rightarrow r^2 + z^2 = 2r$$

$$\Rightarrow (r-1)^2 + z^2 = 1$$



Example. $0 \leq \rho \leq \frac{1 - \cos \phi}{2}$



Line integrals.

Notations.

$$f: \mathbb{R}^3 \rightarrow \mathbb{R}$$

$$(x, y, z) \rightarrow f$$

$$\vec{F}: \mathbb{R}^3 \rightarrow \mathbb{R}^3$$

$$(x, y, z) \rightarrow \begin{pmatrix} F_1(x, y, z) \\ F_2(x, y, z) \\ F_3(x, y, z) \end{pmatrix}$$

Gradient: of f : ∇f

curl of \vec{F} : $\nabla \times \vec{F}$ (curl \vec{F})

divergence of \vec{F} : $\nabla \cdot \vec{F}$ (div \vec{F})

$$\nabla \longleftrightarrow (\partial_x, \partial_y, \partial_z)$$

$$\nabla f \stackrel{\text{def}}{=} (\partial_x f, \partial_y f, \partial_z f)$$

$$\nabla \cdot \vec{F} = (\partial_x, \partial_y, \partial_z) \cdot \begin{pmatrix} F_1 \\ F_2 \\ F_3 \end{pmatrix}$$
$$\stackrel{\text{def}}{=} \partial_x F_1 + \partial_y F_2 + \partial_z F_3$$

$$\nabla \times \vec{F} = \begin{vmatrix} i & j & k \\ \partial_x & \partial_y & \partial_z \\ F_1 & F_2 & F_3 \end{vmatrix}$$

$$\stackrel{\text{def}}{=} (\partial_y F_3 - \partial_z F_2, \partial_z F_1 - \partial_x F_3, \partial_x F_2 - \partial_y F_1)$$

Goal: $\int_A^B \nabla f(\vec{r}) \cdot d\vec{r} = f(B) - f(A)$

$$\vec{r} = (x, y, z), \quad d\vec{r} = \vec{T} ds$$

$$A \in \mathbb{R}^3, \quad B \in \mathbb{R}^3$$

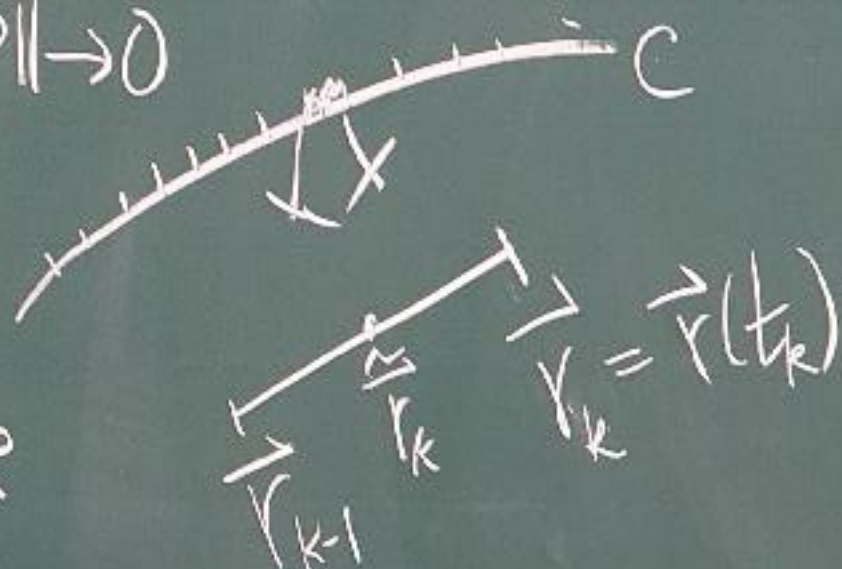
(Analogue of $\int_a^b f_x(t, y, z) dt = f(b, y, z) - f(a, y, z)$)

We first introduce related integrals.

$$(1) \int_C f(x, y, z) ds = \lim_{\|P\| \rightarrow 0} \sum_{k=1}^n f(\vec{r}_k) \Delta S_k$$

$$f: D \subseteq \mathbb{R}^3 \rightarrow \mathbb{R}$$

$C \subseteq D$ is a smooth curve



$$\Delta S_k = |\vec{r}_k - \vec{r}_{k-1}| \quad \text{If } C = \{ \vec{r}(t), a \leq t \leq b \}$$

$$\Rightarrow \Delta S_k = \frac{|\vec{r}_k - \vec{r}_{k-1}|}{\Delta t_k} \Delta t_k \xrightarrow{\|P\| \rightarrow 0} ds = \left| \frac{d\vec{r}(t)}{dt} \right| dt$$

Ex $f(x, y, z) = x - 3y^2 + z$

C: line segment joining $(0, 0, 0)$
 $(1, 1, 1)$

$$\int_C f(x, y, z) ds = ?$$

Sol: $\vec{r}(t) = (t, t, t), 0 \leq t \leq 1$

$$f(\vec{r}(t)) = t - 3t^2 + t$$

$$|\vec{r}'(t)| = |(1, 1, 1)| = \sqrt{3}$$

$$\text{Ans} = \int_0^1 (t - 3t^2 + t) \sqrt{3} dt = 0$$

Rm If we take $\vec{r}(\tau) = (1-\tau^2, 1-\tau^2, t\tau^2)$

$$0 \leq \tau \leq 1$$

$$\text{let } t(\tau) = 1 - \tau^2 \Rightarrow \vec{r}(\tau) = \vec{r}(t(\tau))$$

$$\frac{d\vec{r}}{d\tau} = (-2\tau, -2\tau, -2\tau) = \frac{d\vec{r}}{dt} \frac{dt}{d\tau}$$

$$\underline{\text{Ans}} = \int_{\tau=0}^1 f(\vec{r}(\tau)) \left| \frac{d\vec{r}}{d\tau} \right| d\tau$$

$$= \int_{t=1}^0 f(\vec{r}(t)) \left| \frac{d\vec{r}}{dt} \right| \left| \frac{dt}{d\tau} \right| d\tau$$

$$\left| \frac{dt}{d\tau} \right| = |-2\tau| = -\frac{dt}{d\tau}$$

$$= - \int_{t=1}^0 f(\vec{r}(t)) \left| \frac{d\vec{r}}{dt} \right| \frac{dt}{d\tau} d\tau$$

$$= \int_0^1 f(\vec{r}(t)) \left| \frac{d\vec{r}}{dt} \right| dt$$

$$\text{Ex: } f(x, y, z) = x - 3y^2 + z$$

$$C = C_1 \cup C_2$$

C_1 : line segment joining $(0, 0, 0)$, $(1, 1, 0)$

C_2 : line seg. joining $(1, 1, 0)$ and $(1, 1, 1)$

$$\int_C f(x, y, z) ds = ?$$

Sol. $C_1: \vec{r}_1(t) = (t, t, 0), 0 \leq t \leq 1$

$$C_2: \vec{r}_2(t) = (1, 1, t), 0 \leq t \leq 1$$

$$\int_C = \int_{C_1} + \int_{C_2}$$

$$\int_{C_1} f ds = \int_0^1 (t - 3t^2) \sqrt{2} dt = \frac{-\sqrt{2}}{2}$$

$$\int_{C_2} f ds = \int_0^1 (-2 + t) dt = \frac{-3}{2}$$

Related integral (2)

$$\int_C \vec{F} \cdot \vec{T} ds$$

Also denoted as $\int_C \vec{F}(\vec{r}) \cdot d\vec{r} = \int_a^b \vec{F}(\vec{r}(t)) \cdot \frac{d\vec{r}(t)}{dt} dt$

$$\vec{F}: D \rightarrow \mathbb{R}^3$$

$$(x, y, z) \rightarrow (F_1, F_2, F_3)$$

$C \subseteq D$: a smooth curve with prescribed orientation

$\vec{r}(t)$: parametrization of C

with "direction of increasing t "

= "orientation of C "

$$\vec{T} = \frac{d\vec{r}(t)}{dt} / \left| \frac{d\vec{r}(t)}{dt} \right|$$

unit tangent vector in the prescribed direction

Remark

$$ds = \left| \frac{d\vec{r}(t)}{dt} \right| dt$$

$$\vec{T} ds = \frac{d\vec{r}(t)}{dt} / \left| \frac{d\vec{r}(t)}{dt} \right| \cdot \left| \frac{d\vec{r}(t)}{dt} \right| dt$$

$$= \frac{d\vec{r}(t)}{dt} dt$$

$$\therefore \int_C \vec{F} \cdot \vec{T} ds = \int_a^b \vec{F}(\vec{r}(t)) \cdot \frac{d\vec{r}(t)}{dt} dt$$

$$\left(= \int_C \vec{F}(\vec{r}) \cdot d\vec{r} \right)$$