

3.1-40

(a) differentiable:  $x \in [-1, 3] \setminus \{-1, 0, 2\}$

(b) continuous but not differentiable:  $x = -1$

(c) neither continuous nor differentiable:  $x = 0$  &  $x = 2$

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Suppose that  $g(t)$  and  $h(t)$  are defined for all values of  $t$  and

$g(0) = h(0) = 0$ , Can  $\lim_{t \rightarrow 0} \frac{g(t)}{h(t)}$  exist? If it does exist, must it be 0?

Let  $g(t) = 2t$ ,  $h(t) = t$

$$\Rightarrow \lim_{t \rightarrow 0} \frac{g(t)}{h(t)} = 2$$

So the limit may exist and may not be 0

3.2-57

$$(a) y = f(x) = x^3 - 4x + 1 \Rightarrow f'(x) = 3x^2 - 4$$

$f'(2) = 8 \Rightarrow$  Slope of the equation perpendicular to the tangent to the curve:  $-\frac{1}{8}$

$$\text{Equation: } y = -\frac{1}{8}(x-2) + 1 = -\frac{1}{8}x + \frac{5}{4}$$

(b)

$$f''(x) = 6x, \text{ solve } 6x = 0 \Rightarrow x = 0$$

Moreover,  $\underbrace{f''(x) < 0}_{\text{decreasing}}, x < 0$  &  $\underbrace{f''(x) > 0}_{\text{increasing}}, x > 0$

Hence we have the smallest slope  $f'(0) = -4$  at  $(0, 1)$ .

3.2-59 (c) Solve  $f(x) = 3x^2 - 4 = 8$

$$\Rightarrow 3x^2 = 12 \Rightarrow x^2 = 4 \Rightarrow x = \pm 2$$

$$f(2) = 1 \Rightarrow y = 8(x-2) + 1 = 8x - 15$$

$$f(-2) = 1 \Rightarrow y = 8(x+2) + 1 = 8x + 17$$

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$f(x)$  is curve 1

$f'(x)$  is curve 2

Since all the slope of the tangent

line to curve 2 is negative, and

there are positive values in curve 1.

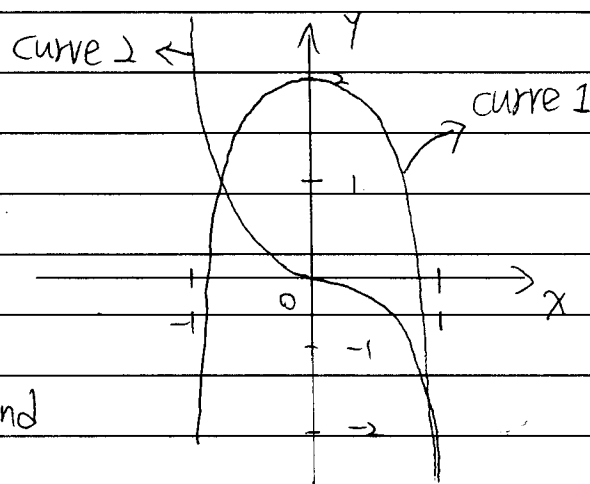
So curve 1 can not be the derivative of curve 2

Consider the slope of curve 1, we can find out that

the slope decreasing on  $(-1, 1)$  and have 0 derivative

at  $x=0$ , curve 2 satisfy all the phenomenon we found

in curve 1



$$\text{S3.5-extra1} \quad \frac{d}{dx} (f_1(x) f_2(x) \cdots f_n(x)) = f_1'(x) \cdot f_2(x) \cdots f_n(x) + f_1(x) \cdot (f_2(x) \cdots f_n(x))'$$

$$= f_1'(x) \cdot f_2(x) \cdots f_n(x) + f_1(x) \cdot f_2'(x) \cdot f_3(x) \cdots f_n(x) + f_1(x) \cdot f_2(x) \cdot (f_3(x) \cdots f_n(x))'$$

$$= \dots$$

$$= f_1'(x) f_2(x) \cdots f_n(x) + f_1(x) \cdot f_2'(x) \cdot f_3(x) \cdots f_n(x) + \dots$$

$$+ f_1(x) \cdots f_{i-1}(x) \cdot f_i'(x) \cdot f_{i+1}(x) \cdots f_n(x) + \dots + f_1(x) \cdots f_{n-1}(x) \cdot f_n'(x)$$

the  $i$ th term

$$\frac{d^n}{dx^n} (f(x) g(x)) = \sum_{k=0}^n C_k^n \left( \frac{d^k f}{dx^k} \right) \left( \frac{d^{n-k} g}{dx^{n-k}} \right)$$

5.5-extra

$$\frac{d}{dx} \begin{vmatrix} f(x) & g(x) \\ h(x) & k(x) \end{vmatrix} = \frac{d}{dx} (f(x)k(x) - g(x)h(x))$$

$$= f'(x)k(x) + f(x)k'(x) - (g'(x)h(x) + g(x)h'(x))$$

$$= (f'(x)k(x) - g(x)h'(x)) + (f(x)k'(x) - g'(x)h(x))$$

$$= \begin{vmatrix} f'(x) & g(x) \\ h'(x) & k(x) \end{vmatrix} + \begin{vmatrix} f(x) & g'(x) \\ h(x) & k'(x) \end{vmatrix}$$

The other equality is similar

$$\frac{d}{dx} \begin{vmatrix} f(x) & g(x) & h(x) \\ i(x) & j(x) & k(x) \\ l(x) & m(x) & n(x) \end{vmatrix} = \frac{d}{dx} \left( f(x) \begin{vmatrix} j(x) & k(x) \\ m(x) & n(x) \end{vmatrix} - i(x) \begin{vmatrix} g(x) & h(x) \\ m(x) & n(x) \end{vmatrix} + l(x) \begin{vmatrix} g(x) & h(x) \\ j(x) & k(x) \end{vmatrix} \right)$$

$$= \underbrace{f'(x) \begin{vmatrix} j(x) & k(x) \\ m(x) & n(x) \end{vmatrix}}_{\textcircled{1}} + \underbrace{f(x) \left( \begin{vmatrix} j'(x) & k(x) \\ m'(x) & n(x) \end{vmatrix} + \begin{vmatrix} j(x) & k'(x) \\ m(x) & n'(x) \end{vmatrix} \right)}_{\textcircled{2}} - \underbrace{i'(x) \begin{vmatrix} g(x) & h(x) \\ m(x) & n(x) \end{vmatrix}}_{\textcircled{1}}$$

$$- \underbrace{i(x) \left( \begin{vmatrix} g'(x) & h(x) \\ m'(x) & n(x) \end{vmatrix} + \begin{vmatrix} g(x) & h'(x) \\ m(x) & n'(x) \end{vmatrix} \right)}_{\textcircled{2}} + \underbrace{l'(x) \begin{vmatrix} g(x) & h(x) \\ j(x) & k(x) \end{vmatrix}}_{\textcircled{1}} + \underbrace{l(x) \left( \begin{vmatrix} g'(x) & h(x) \\ j'(x) & k(x) \end{vmatrix} + \begin{vmatrix} g(x) & h'(x) \\ j(x) & k'(x) \end{vmatrix} \right)}_{\textcircled{2}}$$

$$= \underbrace{\begin{vmatrix} f(x) & g(x) & h(x) \\ i'(x) & j(x) & k(x) \\ l'(x) & m(x) & n(x) \end{vmatrix}}_{\textcircled{1}} + \underbrace{\begin{vmatrix} f(x) & g'(x) & h(x) \\ i(x) & j'(x) & k(x) \\ l(x) & m'(x) & n(x) \end{vmatrix}}_{\textcircled{2}} + \underbrace{\begin{vmatrix} f(x) & g(x) & h'(x) \\ i(x) & j(x) & k'(x) \\ l(x) & m(x) & n'(x) \end{vmatrix}}_{\textcircled{3}}$$

Similarly, we have

$$\frac{d}{dx} \begin{vmatrix} f(x) & g(x) & h(x) \\ i(x) & j(x) & k(x) \\ l(x) & m(x) & n(x) \end{vmatrix} = \begin{vmatrix} f(x) & g(x) & h'(x) \\ i(x) & j(x) & k(x) \\ l(x) & m(x) & n(x) \end{vmatrix} + \begin{vmatrix} f(x) & g(x) & h(x) \\ i'(x) & j'(x) & k'(x) \\ l(x) & m(x) & n(x) \end{vmatrix} + \begin{vmatrix} f(x) & g(x) & h(x) \\ i(x) & j(x) & k(x) \\ l'(x) & m'(x) & n'(x) \end{vmatrix}$$

And the 4x4

$$\begin{aligned} \frac{d}{dx} \begin{vmatrix} a(x) & b(x) & c(x) & d(x) \\ e(x) & f(x) & g(x) & h(x) \\ i(x) & j(x) & k(x) & l(x) \\ m(x) & n(x) & p(x) & q(x) \end{vmatrix} &= \begin{vmatrix} a(x) & b(x) & c'(x) & d'(x) \\ e(x) & f(x) & g(x) & h(x) \\ i(x) & j(x) & k(x) & l(x) \\ m(x) & n(x) & p(x) & q(x) \end{vmatrix} + \begin{vmatrix} a(x) & b(x) & c(x) & d(x) \\ e'(x) & f'(x) & g'(x) & h'(x) \\ i(x) & j(x) & k(x) & l(x) \\ m(x) & n(x) & p(x) & q(x) \end{vmatrix} \\ &+ \begin{vmatrix} a(x) & b(x) & c(x) & d(x) \\ e(x) & f(x) & g(x) & h(x) \\ i'(x) & j'(x) & k'(x) & l'(x) \\ m(x) & n(x) & p(x) & q(x) \end{vmatrix} + \begin{vmatrix} a(x) & b(x) & c(x) & d(x) \\ e(x) & f(x) & g(x) & h(x) \\ i(x) & j(x) & k(x) & l(x) \\ m'(x) & n'(x) & p'(x) & q'(x) \end{vmatrix} \end{aligned}$$