

Chapter 3 Second Order Differential Equation

Linear Superposition Principle

$$y'' + p(t)y' + q(t)y = 0 \quad (\text{linear ODE})$$

$y_1(t) \cdot y_2(t)$ are solutions :

$\Rightarrow c_1 y_1(t) + c_2 y_2(t)$ is also a solution

$$ay'' + by' + cy = 0 \quad a, b, c \in \mathbb{R}$$

Try e^{rt} , r to be determined

$$\Rightarrow (ar^2 + br + c) e^{rt} = 0$$

If r is a solution of $ar^2 + br + c = 0$, then e^{rt} is a solution of

$$ay'' + by' + cy = 0.$$

3 cases

case (1) : $r = r_1, r_2 \quad r_1, r_2 \in \mathbb{R}$, and $r_1 \neq r_2$.

\exists at least 2 solutions $e^{r_1 t}, e^{r_2 t}$ & $c_1 e^{r_1 t} + c_2 e^{r_2 t}$

case (2) : $r = \alpha + \beta i \quad \alpha, \beta \in \mathbb{R}$

$\Rightarrow e^{(\alpha+i\beta)t}, e^{(\alpha-i\beta)t}$ are solutions of $ay'' + by' + cy = 0$

$$c_1 e^{(\alpha+i\beta)t} + c_2 e^{(\alpha-i\beta)t}$$

$$= (c_1 + c_2) e^{\alpha t} (\cos \beta t) + i(c_1 - c_2) e^{\alpha t} \sin \beta t$$

$$= \tilde{c}_1 e^{\alpha t} \cos \beta t + i \tilde{c}_2 e^{\alpha t} \sin \beta t$$

$$e^{(\alpha+i\beta)t} = e^{\alpha t} \cdot e^{i\beta t} = e^{\alpha t} (\cos \beta t + i \sin \beta t)$$

$$e^{(\alpha-i\beta)t} = e^{\alpha t} \cdot e^{-i\beta t} = e^{\alpha t} (\cos \beta t - i \sin \beta t)$$

case (3) : double roots r_1, r_2

e^{rt} and te^{rt} are 2 solutions. ($b^2 = 4ac$)

For (3), i.e. $r = -b/2a$, e^{rt} is a solution

Try $p(t)e^{rt}$ as follow:

$$(p(t)e^{rt})' = p'e^{rt} + rpe^{rt}$$

$$(p(t)e^{rt})'' = p''e^{rt} + 2rp'e^{rt} + r^2pe^{rt}$$

Plugging into $ay'' + by' + cy = 0$, we get

$$a(p'' + 2p'r + pr^2) + b(p' + pr) + cp = 0$$

$$ap'' + (2ar + b)p' + (ar^2 + br + c)p = 0$$

Hence $ap'' = 0$ and we may choose $p(t) = t$.

Question : all 3 cases $\exists y_1(t), y_2(t)$

$$y_1 \neq \text{constant } y_2(t)$$

Are there solutions not of the form $c_1y_1(t) + c_2y_2(t)$?

Ans

$$\begin{cases} ay'' + by' + cy = 0 \\ y(t_0) = y_0 \\ y'(t_0) = y_0 \end{cases}$$

has exactly one solution.

Eg $e^{r_1t}, e^{r_2t}, r_1 \neq r_2 \in \mathbb{R}$

If another solution $y_*(t)$

Can we find c_1, c_2

$$\begin{cases} c_1y_1(0) + c_2y_2(0) = y_*(0) \\ c_1y_1'(0) + c_2y_2'(0) = y_*'(0) \end{cases}$$

If we can find c_1, c_2

$$\Rightarrow \begin{cases} c_1 y_1(t) + c_2 y_2(t) & \text{have the same } y(0) \text{ and } y'(0) \\ y_*(t) \end{cases}$$

From uniqueness $\Rightarrow y_*(t) = c_1 y_1(t) + c_2 y_2(t)$

$$\begin{aligned} y_1(0) = 1 \quad y_2(0) = 1 \\ y_1'(0) = r_1 \quad y_2'(0) = r_2 + r_1 \quad \Rightarrow c_1, c_2 \text{ exists.} \end{aligned}$$

2nd Order Linear ODE

(1) Homogeneous ODE

$$y'' + p(t)y' + q(t)y = 0$$

Existence of linearly independent solution

Consider $ar^2 + br + c = 0$

3 cases

case (1) : 2 real roots $r_1 \neq r_2$

$$\Rightarrow c_1 e^{r_1 t} + c_2 e^{r_2 t} \text{ the solutions}$$

case (2) : multiple real roots r, r

$$\Rightarrow c_1 e^{rt} + c_2 t e^{rt} \quad \forall c_1, c_2$$

case (3) : 2 complex conjugate roots

$$\alpha \pm i\beta \quad \alpha, \beta \in \mathbb{R} \quad \beta \neq 0$$

$$\Rightarrow c_1 e^{\alpha t} \cos \beta t + c_2 e^{\alpha t} \sin \beta t \quad \forall c_1, c_2.$$

Given $y_1(t), y_2(t)$ 2 linear indep solution

homogeneous 2nd order ODE

How to construct solution of

$$(\star\star) \begin{cases} ay'' + by' + cy = 0 \\ y(0) = y_0 \\ y'(0) = y'_0 \end{cases}$$

Ans : Find $c_1, c_2 \in \mathbb{R}$ s.t.

$$(\star) \begin{cases} c_1 y_1(0) + c_2 y_2(0) = y_0 \\ c_1 y'_1(0) + c_2 y'_2(0) = y'_0 \end{cases}$$

$\Rightarrow c_1 y_1(t) + c_2 y_2(t)$ is the solution.

(\star) has a solution

given y_0, y'_0 , can always find unique c_1, c_2 .

$$\text{iff } \begin{vmatrix} y_1(0) & y_2(0) \\ y'_1(0) & y'_2(0) \end{vmatrix} \neq 0$$

$$\text{i.e. } \begin{pmatrix} y_1(t) \\ y'_1(t) \end{pmatrix} \begin{pmatrix} y_2(t) \\ y'_2(t) \end{pmatrix} \text{ are linear indep}$$

in \mathbb{R}^2 at $t = 0$.

Definition : $y_1(t), y_2(t)$ are linearly dependent

$$\text{iff } \exists c_1, c_2 \in \mathbb{R} \text{ s.t. } c_1 y_1(t) + c_2 y_2(t) \equiv 0 \quad \text{for all } t \in (\alpha, \beta).$$

Linear independent \Leftrightarrow NOT linear dependent.

Proposition : $y_1(t) = c y_2(t)$

$$\Rightarrow \begin{vmatrix} y_1(t) & y_2(t) \\ y'_1(t) & y'_2(t) \end{vmatrix} = 0$$

$$\Rightarrow \begin{vmatrix} y_1(0) & y_2(0) \\ y'_1(0) & y'_2(0) \end{vmatrix} = 0$$

Theorem : p, q continuous on (α, β)

y_1, y_2 are solutions of $y'' + p(t)y' + q(t)y = 0$

$$\begin{vmatrix} y_1(0) & y_2(0) \\ y_1'(0) & y_2'(0) \end{vmatrix} = 0 \Leftrightarrow \begin{vmatrix} y_1(t) & y_2(t) \\ y_1'(t) & y_2'(t) \end{vmatrix} = 0$$

$$\forall t \in (\alpha, \beta) \quad 0 \in (\alpha, \beta)$$

$$\text{Define } w(t) = \begin{vmatrix} y_1(t) & y_2(t) \\ y_1'(t) & y_2'(t) \end{vmatrix}$$

$$\Rightarrow w'(t) = \begin{vmatrix} y_1'(t) & y_2'(t) \\ y_1'(t) & y_2'(t) \end{vmatrix} + \begin{vmatrix} y_1(t) & y_2(t) \\ y_1''(t) & y_2''(t) \end{vmatrix}$$

$$\Rightarrow w'(t) = \begin{vmatrix} y_1(t) & y_2(t) \\ -py_1' - qy_1 & -py_2' - qy_2 \end{vmatrix} = -p(t)w(t)$$

$$\therefore w(t) = w(0) \exp\left(-\int_0^t p(s) ds\right).$$

$$w(t) = 0 \Leftrightarrow w(0) = 0$$

Corollary : If $y_1(t), y_2(t)$ are two solutions of $ay'' + by' + cy = 0$ with

$$\begin{vmatrix} y_1(0) & y_2(0) \\ y_1'(0) & y_2'(0) \end{vmatrix} \neq 0$$

Then the solution to $(\star\star)$ is uniquely given by (\star) .

Proof : The existence has been done, $\therefore c_1 y_1(t) + c_2 y_2(t)$ satisfies $(\star\star)$

And the uniqueness is equivalent to

$$(\star\star\star) \begin{cases} ay'' + by' + cy = 0 \\ y(0) = y'(0) = 0 \end{cases} \text{ implies } y(t) = 0.$$

Because if $y_A(t)$ and $y_B(t)$ both solve $(\star\star)$, then $y_A - y_B$ solve $(\star\star\star)$

Why is $(\star\star\star)$ true?

$$\text{Consider } w_1(t) = \begin{vmatrix} y_1(t) & y_1(t) \\ y_1'(t) & y_1'(t) \end{vmatrix} \quad \text{and} \quad w_2(t) = \begin{vmatrix} y_2(t) & y_2(t) \\ y_2'(t) & y_2'(t) \end{vmatrix}$$

Since $y(0) = y'(0) = 0 \Rightarrow w_1(0) = w_2(0) = 0$

$$\Rightarrow w_1(0) = w_2(0) = 0$$

i.e. $\begin{pmatrix} y(t) \\ y'(t) \end{pmatrix}$ is linearly dependent with both

$\begin{pmatrix} y_1(t) \\ y_1'(t) \end{pmatrix}$ and $\begin{pmatrix} y_2(t) \\ y_2'(t) \end{pmatrix}$. Therefore, $y(t) = 0, y'(t) = 0$

Example

$$\begin{cases} y'' + k^2 y = 0 \\ y(0) = 1 \\ y'(0) = 0 \end{cases} \quad \text{--- (1)} \quad \text{and} \quad \begin{cases} y'' + k^2 y = 0 \\ y(0) = 0 \\ y'(0) = 1 \end{cases} \quad \text{--- (2)}$$

$$(1) : y(t) = \cos kt$$

$$(2) : y(t) = \frac{1}{k} \sin kt$$

In general

$$\begin{cases} y'' + k^2 y = 0 \\ y(0) = A \\ y'(0) = B \end{cases}$$

$$\Rightarrow y(t) = A \cos kt + B \frac{1}{k} \sin kt$$

Remark

"The existence of two linear indep. \Rightarrow unique" is also valid for $y'' + p(t)y + q(t)y = 0$.

But "existence of Two linear indep. solutions" was not proved in class.

Example : Solve the following initial value problem

$$\begin{cases} y'' - k^2 y = 0 \\ y(0) = A \\ y'(0) = B \end{cases}$$

First note that $y'' - k^2 y = 0$ has a family of solutions $y = c_1 e^{kt} + c_2 e^{-kt}$. According

to the initial condition, we have

$$\begin{aligned} A &= y(0) = c_1 + c_2 \\ B &= y'(0) = c_1 k - c_2 k \end{aligned}$$

Hence, $c_1 = (Ak + B)/2k$ and $c_2 = (Ak - B)/2k$.

Inhomogeneous 2nd Order ODE

Suppose $y_1(t)$, $y_2(t)$ are two linear indep solutions in the case of $g(t) = 0$. Then

$$\begin{cases} y'' + p(t)y' + q(t)y = g(t) \\ y(0) = y_0, y'(0) = y'_0 \end{cases}$$

has a solution of the form

$$y = c_1 y_1(t) + c_2 y_2(t) + Y(t),$$

where $c_1 y_1 + c_2 y_2$ is the solution to the homogeneous initial value problem

$$\begin{cases} y'' + py' + qy = 0 \\ y(0) = y_0, \quad y'(0) = y'_0 \end{cases}$$

and $Y(t)$ is the solution to the equation

$$\begin{cases} y'' + py' + qy = g(t) \\ y(0) = 0, \quad y'(0) = 0 \end{cases}$$

Remark Given (1) \Rightarrow solution to (2) is unique, same proof as before.

Remark If given $Y(t)$

$$\begin{cases} Y'' + pY' + qY = g \\ Y(0) = A \quad Y'(0) = B \end{cases}$$

\Rightarrow solution to (2) is given by $c_1 y_1(t) + c_2 y_2(t) + Y(t)$.

Inhomogeneous 2nd Order Linear ODE

$$\begin{cases} y'' + p(t)y' + q(t)y = g(t) & \text{--- (1)} \\ y(t_0) = y_0 & y'(t_0) = y'_0 \end{cases}$$

For homogeneous ODE

$$y'' + p(t)y' + q(t)y = 0 \text{ --- (2)}$$

$\exists y_1(t), y_2(t)$ is linear independent solutions

i.e. $w(y_1, y_2) \neq 0 \ (\forall t)$

$$\begin{vmatrix} y_1 & y_2 \\ y'_1 & y'_2 \end{vmatrix} (t)$$

$$w' + pw = 0$$

such that all solutions of (2) is of the $c_1 y_1(t) + c_2 y_2(t)$

$y_1(t), y_2(t)$ can be explicitly found for the constant coefficient case. For the general case, we only know the existence of $y_1(t), y_2(t)$ from theorem of the solution to (1) is unique.

We can decompose the solution as $y(t) = c_1 y_1(t) + c_2 y_2(t) + Y(t)$ where y_1, y_2 are linear independent solutions of (2), $Y(t)$ is any solution to $y'' + py' + qy = g$. c_1, c_2 are chosen so that $y(t_0) = y_0, y'(t_0) = y'_0$.

Next, we introduce some methods that picks a $Y(t)$ (special solution) in terms of $y_1(t)$ and $y_2(t)$.

(a) guess (method of undetermined coefficient)

(b) variation of parameter.

Variation of Parameter

Try $y(t) = u_1(t)y_1(t) + u_2(t)y_2(t)$ with u_1, u_2 to be determined. There are some

freedom in choosing u_1, u_2 . Put them into $y'' + p(t)y' + q(t)y = g(t)$, we obtain

$$\begin{aligned} y'' + py' + qy &= u_1''y_1 + u_2''y_2 + 2u_1'y_1' + 2u_2'y_2' + u_1y_1'' + u_2y_2'' \\ &\quad + p(u_1'y_1 + u_2'y_2 + u_1y_1' + u_2y_2') + q(u_1y_1 + u_2y_2) \\ &= g(t) \end{aligned}$$

We impose $u_1'y_1 + u_2'y_2 = 0$ — — — (1)

$\Rightarrow u_1'y_1' + u_2'y_2' = g(t)$ — — — (2)

$$\Rightarrow \begin{cases} u_1'y_1 + u_2'y_2 = 0 \\ u_1'y_1' + u_2'y_2' = g(t) \end{cases}$$

solve for u_1', u_2'

$$u_1'(t) = \frac{-y_2(t)g(t)}{w(y_1, y_2)(t)} \quad \text{and} \quad u_2'(t) = \frac{y_1(t)g(t)}{w(y_1, y_2)(t)}$$

$$u_1(t) = \int_{t_0}^t \frac{-y_2 g}{w} ds \quad \text{and} \quad u_2(t) = \int_{t_0}^t \frac{y_1 g}{w} ds$$

$$\Rightarrow Y(t_0) = u_1(t_0)y_1(t_0) + u_2(t_0)y_2(t_0) = 0$$

$$Y'(t_0) = (u_1'y_1 + u_2'y_2)(t_0) + (u_1y_1' + u_2y_2')(t_0) = 0$$

$$\Rightarrow \begin{cases} Y'' + pY' + qY = g(t) \\ Y(t_0) = 0 \quad Y'(t_0) = 0 \end{cases}$$

Find a particular solution of $y'' + 2y' - 4y = 3e^{2t} + 2\sin t - 8e^t \cos 2t$

Consider $y'' + 3y' + 4y$

$y_1(t), y_2(t)$ are the solutions of $y'' - 3y' - 4y = 0$

$$\Rightarrow y_1(t) = e^{4t}, y_2(t) = e^{-t}$$

By the linear superposition, it suffices to find the solutions of

$$y'' - 3y' - 4y = \begin{cases} 3e^{2t} \\ 2\sin t \\ -8e^t \cos 2t \end{cases}.$$

$$(1) y'' - 3y' - 4y = 3e^{2t}$$

$$2 \neq r_1, r_2$$

$$(e^{2t})'' - 3(e^{2t})' - 4(e^{2t}) = 4e^{2t} - 6e^{2t} - 4e^{2t} \neq 0$$

$$\text{Try } y = Ae^{2t}$$

$$\Rightarrow 4Ae^{2t} - 6Ae^{2t} - 4Ae^{2t} = 3e^{2t}$$

$$-6A = 3 \Rightarrow A = -1/2$$

$$\Rightarrow y(t) = -1/2e^{2t}$$

$$(2) y'' - 3y' - 4y = 2 \sin t = 2 \operatorname{Im} e^{it}$$

Try $y = A \cos t + B \sin t$ (Equivalent to try $(C + Di)e^{it}$) as follow :

$$y'' - 3y' - 4y$$

$$= -B \sin t - A \cos t + 3A \sin t - 3B \cos t - 4A \cos t - 4B \sin t$$

$$= 2 \sin t$$

$$\begin{cases} -B + 3A - 4B = 2 \\ -A - 3B - 4A = 0 \end{cases} \Rightarrow \begin{cases} 3A - 5B = 2 \\ 5A + 3B = 0 \end{cases} \Rightarrow \begin{cases} A = \frac{6}{34} \\ B = \frac{-10}{34} \end{cases}$$

$$\begin{pmatrix} -A \\ -B \end{pmatrix} - 3 \begin{pmatrix} B \\ -A \end{pmatrix} - 4 \begin{pmatrix} A \\ B \end{pmatrix} = \begin{pmatrix} 0 \\ 2 \end{pmatrix}$$

$$(C + Di)(e^{it})'' - 3(e^{it})' - 4(e^{it})$$

$$= (C + Di)(-5 - 3i)e^{it}$$

$$= (-5C - 3Ci - 5Di + 3D)e^{it}$$

$$= (-5C + 3D + i(-3i - 5D))e^{it}$$

$$= 2 \operatorname{Im} e^{it}$$

$$\Rightarrow \begin{cases} -5C + 3D = 2 \\ -3C - 5D = 0 \end{cases} \Rightarrow \begin{cases} C = -\frac{10}{34} = -\frac{5}{17} \\ D = \frac{6}{34} = \frac{3}{17} \end{cases}$$

$$(3) \ y'' - 3y' - 4y = -8e^t \cos 2t = -8\operatorname{Re} e^{(1+2i)t}$$

$$\lambda \left((e^{(1+2i)t})'' - 3(e^{(1+2i)t})' - 4(e^{(1+2i)t}) \right)$$

$$= \lambda (-2i - 10) e^{(1+2i)t} = -8e^{(1+2i)t}$$

$$\Rightarrow \lambda = \frac{-8}{-2i-10}$$

$$\Rightarrow \text{take } y = \operatorname{Re} (\lambda e^{(1+2i)t})$$

Example : To find a particular solution of $y'' + 4y = 3 \cos(2t)$, ($= 3 \operatorname{Re} e^{2it}$).

First we solve $r^2 + 4 = 0$, and obtain $r = \pm 2i$.

Next, try $\lambda t e^{2it}$ as follow :

Take $\operatorname{Re} (\lambda t e^{2it})$

$$y'' - 4y' + 4y = e^{2t}$$

Try $A t^2 e^{2t}$

Consider :

$$\begin{cases} ay'' + by' + cy = ke^{qt} \\ aq^2 + bq + c = 0 \end{cases}$$

Try $p(t)e^{qt}$

$$2aq + b \neq 0 \Leftrightarrow q = r_1 \neq r_2$$

$$2aq + b = 0 \Leftrightarrow r_1 = r_2$$

$$(p(t)e^{qt})'' + (p(t)e^{qt})' + (p(t)e^{qt})$$

$$a \begin{pmatrix} p'' \\ +2p'q \\ +pq^2 \end{pmatrix} e^{qt} + b \begin{pmatrix} p' \\ pq \end{pmatrix} e^{qt} + c(p) e^{qt}$$

$$\begin{aligned}
&= p''ae^{qt} + p'(2aq + b)e^{qt} + p(aq^2 + bq + c)e^{qt} \\
&= ke^{qt}
\end{aligned}$$

There are two possibility :

1. If $2aq + b = 0$, then we let $p'' = k/a$.
2. If $2aq + b \neq 0$, then we let $p'' = 0$ and $p' = k/(2aq + b)$.

Example : To solve the differential equation $y'' + 3y' + 2y = t^k$, we may try the

polynomial $y(t) = a_k t^k + a_{k-1} t^{k-1} + \dots + a_0$. Then

$$\begin{aligned}
&a_k k(k-1)t^{k-2} + a_{k-1}(k-1)(k-2)t^{k-3} + \dots \\
&+ 3\left(a_k k t^{k-1} + a_{k-1}(k-1)t^{k-2} + a_{k-2}(k-2)t^{k-3} + \dots\right) \\
&+ 2\left(a_k t^k + a_{k-1} t^{k-1} + a_{k-2} t^{k-2} + \dots\right) = t^k.
\end{aligned}$$

Therefore,

$$\begin{aligned}
2a_k &= 1 \\
3a_k k + 2a_{k-1} &= 0 \\
a_k k(k-1) + 3a_{k-1}(k-1) + 2a_{k-2} &= 0 \\
&\vdots
\end{aligned}$$

Question : What can we do in the case of $y'' + 3y' = t^k + \dots$?

Answer : Try the polynomial $y(t) = a_{k+1} t^{k+1} + a_k t^k + \dots$.

Remark : To solve $y'' = t^k + \dots$, we integrate on both sides directly.

Undamped Oscillations

Consider the second order differential equation

$$mu'' + ku = 0,$$

for some positive constants m, k .

$$(F = ma)$$

$$u'' + \frac{k}{m}u = 0$$

$$u = A \cos\left(\sqrt{\frac{k}{m}}t\right) + B \sin\left(\sqrt{\frac{k}{m}}t\right) = \sqrt{A^2 + B^2} \cos\left(\sqrt{\frac{k}{m}}t + \delta_0\right).$$

$$T = \frac{2\pi}{\sqrt{k/m}}$$

Damped Oscillations

$$mu'' + \nu u' + ku = 0, \quad \nu > 0 \text{ (fixed)}$$

The solution are given by $c_1 e^{r_1 t} + c_2 e^{r_2 t}$

$$r_1, r_2 : mr^2 + \nu r + k = 0$$

$$r_1, r_2 = \frac{-\nu \pm \sqrt{\nu^2 - 4mk}}{2m}$$

There are 3 cases to be discussed :

1. If $\nu^2 - 4mk > 0$, then $r_1 < 0, r_2 < 0$, and $r_1 \neq r_2$.
2. If $\nu^2 - 4mk = 0$, then $r_1 = r_2 = \frac{-\nu}{2m} < 0$.
3. If $\nu^2 - 4mk < 0$, then $\text{Re } r_1 = \text{Re } r_2 = \frac{-\nu}{2m} < 0$.

Since $u(t) = c_1 e^{r_1 t} + c_2 e^{r_2 t}$, i.e.

$$u = e^{-\nu t/2m} \left(c_1 \cos\left(\frac{\sqrt{4mk - \nu^2}}{2m}t\right) + c_2 \sin\left(\frac{\sqrt{4mk - \nu^2}}{2m}t\right) \right),$$

we have $\lim_{t \rightarrow \infty} u(t) = 0$ for any initial data $u(0)$, $u'(0)$.

REMARK :

1. In the case of $r_1 \neq r_2 < 0$, say $r_1 < r_2 < 0$, we have $u = c_1 e^{r_1 t} + c_2 e^{r_2 t}$.

$$c_1, c_2 = ?$$

$$\begin{cases} u(0) = c_1 + c_2 \\ u'(0) = r_1 c_1 + r_2 c_2 \end{cases}$$

$$\text{Therefore, } c_1 = \frac{u'(0) - r_2 u(0)}{r_1 - r_2}, \text{ and } c_2 = \frac{u'(0) - r_1 u(0)}{r_2 - r_1}.$$

2. In the case of $r_1 = r_2 < 0$, we have $u(t) = c_1 e^{rt} + c_2 t e^{rt}$.

Undamped Oscillations

$$mu'' + ku = F_0 \cos \omega t$$

$$\text{Let } \omega_0 = \sqrt{k/m}$$

$$u(t) = c_1 \cos \omega_0 t + c_2 \sin \omega_0 t + \frac{F_0}{k - m\omega^2} \cos \omega t \quad (\omega^2 \neq \omega_0^2 \Rightarrow k - m\omega^2 \neq 0)$$

$$c_1, c_2 = ?$$

$$\begin{cases} c_1 + \frac{F_0}{k - m\omega^2} = u(0) \\ \omega_0 c_2 = u'(0) \end{cases}$$

$$u = \sqrt{c_1^2 + c_2^2} \cos(\omega_0 t + \delta) + \frac{F_0}{k - m\omega^2} \cos \omega t$$

$$\text{As } \omega \sim \omega_0$$

$$\begin{cases} \omega_0 = \frac{\omega + \omega_0}{2} - \frac{\omega - \omega_0}{2} \\ \omega = \frac{\omega + \omega_0}{2} + \frac{\omega - \omega_0}{2} \end{cases} \text{ implies } \begin{cases} \frac{\omega + \omega_0}{2} \sim \omega_0 \\ \frac{\omega - \omega_0}{2} \sim 0 \end{cases}$$

For simplicity, suppose $u'(0) = 0$ ($c_2 = 0$) $\Rightarrow \delta = 0$

$$u = c_1 \cos \omega_0 t + \frac{F_0}{k - m\omega^2} \cos \omega t$$

$$\text{Let } A = \frac{\omega + \omega_0}{2} t, \quad \text{and } B = \frac{\omega - \omega_0}{2} t$$

$$\Rightarrow u = c_1(\cos A \cos B + \sin A \sin B) + \frac{F_0}{k-m\omega^2}(\cos A \cos B - \sin A \sin B)$$

$$= \begin{cases} \frac{2F_0}{k-m\omega^2} \cos\left(\frac{\omega+\omega_0}{2}t\right) \cos\left(\frac{\omega-\omega_0}{2}t\right) & c_1 = \frac{F_0}{k-m\omega^2} \\ \frac{-2F_0}{k-m\omega^2} \sin\left(\frac{\omega+\omega_0}{2}t\right) \sin\left(\frac{\omega-\omega_0}{2}t\right) & c_1 = \frac{-F_0}{k-m\omega^2} \end{cases}$$

$$\text{Recall : } mu'' + ku = F_0 \cos \omega t$$

$$u(t) = c_1 \cos \omega_0 t + c_2 \sin \omega_0 t + \frac{F_0}{m(\omega_0^2 - \omega^2)} \cos \omega t$$

$$\omega_0^2 = \frac{k}{m}$$

$$\text{If } u(0) = u'(0) = 0, c_2 = 0, c_1 = \frac{-F_0}{m(\omega_0^2 - \omega^2)}$$

then

$$\begin{aligned} u(t) &= \frac{F_0}{m(\omega_0^2 - \omega^2)} (\cos \omega t - \cos \omega_0 t) \\ &= \frac{-2F_0}{m(\omega_0^2 - \omega^2)} \cdot \sin\left(\frac{\omega+\omega_0}{2}t\right) \cdot \sin\left(\frac{\omega-\omega_0}{2}t\right). \end{aligned}$$

In general,

$$\begin{aligned} u(t) &= A \cos(\omega_0 t + \delta) + B \cos(\omega t) \\ &= A(\cos \alpha \cos \beta + \sin \alpha \sin \beta) + B(\cos \alpha \cos \beta - \sin \alpha \sin \beta) \\ &= (A + B) \cos \alpha \cos \beta + (A - B) \sin \alpha \sin \beta \\ &= C \cos(\beta + \varepsilon). \end{aligned}$$

Homework : What is C and ε ?

Resonance ($\omega = \omega_0$)

$$mu'' + ku = F_0 \cos \omega_0 t$$

$$u = c_1 \cos \omega_0 t + c_2 \sin \omega_0 t + \text{Re}\left(\frac{F_0}{2mi\omega_0} t e^{i\omega_0 t}\right) = c_1 \cos \omega_0 t + c_2 \sin \omega_0 t + c_3 t \sin \omega_0 t$$

$$\text{Try } u_p = p(t)e^{i\omega_0 t} \text{ s.t. } mu_p'' + ku_p = F_0 e^{i\omega_0 t}$$

Take $\text{Re}(u_p)$

$$mu_p'' = m(p'' + 2p'i\omega_0 - \omega_0^2 p)e^{i\omega_0 t} + kp e^{i\omega_0 t} = F_0 e^{i\omega_0 t}$$

$$\text{Hence } mp'' + 2mp'i\omega_0 = F_0$$

and we get $p = \frac{F_0}{2mi\omega_0}t$

Take $\text{Re}(u_p) = \frac{F_0}{2m\omega_0}t \cdot \sin(\omega_0 t)$,

$$G(t, s) = \frac{\sin(\omega_0(t-s))}{\omega_0}$$

$$u_p(t) = \int_0^t \frac{1}{\omega_0} \sin(\omega_0(t-s)) \frac{F_0}{m} \cos(\omega_0 s) ds$$

$$mu'' + ru' + ku = F_0 \cos \omega_0 t$$

$$u(t) = c_1 e^{r_1 t} + c_2 e^{r_2 t} + c_3 \cos(\omega_0 t + \delta) \quad (\omega_0 \neq r_1, r_2)$$

$$\begin{cases} \text{Re } r_1 < 0 \\ \text{Re } r_2 < 0 \end{cases} \quad \lim_{t \rightarrow \infty} (c_1 e^{r_1 t} + c_2 e^{r_2 t}) = 0$$

HW : 3.7, 15, 17

HW : (1) $u'' - 3u' + 2u = \cos t$, find a particular solution.

(2) $u'' - 2u' + u = \cos t$, find a particular solution.