## Hermite Interpolation

Given n+1 data points  $x_0 < x_1 < \cdots < x_n$ , and

for some function  $f \in C^m[a,b]$ , where  $m = \max\{m_0, m_1, \ldots, m_n\}$ .



ullet Determine a polynomial P of degree at most N, where

$$N = \left(\sum_{i=0}^{n} m_i\right) + n,\tag{5}$$

to satisfy the following interpolation conditions:

$$P^{(k)}(x_i) = y_i^{(k)}, \qquad k = 0, 1, \dots, m_i, \quad i = 0, 1, \dots, n.$$
 (6)

- If n = 0, then P is the  $m_0$ th Taylor polynomial for f at  $x_0$ .
- If  $m_i = 0$  for each i, then P is the nth Lagrange polynomial interpolating f on  $x_0, \ldots, x_n$ .
- If  $m_i = 1$  for each i, then P is called the Hermite polynomial.



## **Theorem**

If  $f \in C^1[a,b]$  and  $x_0, \ldots, x_n \in [a,b]$  are distinct, then the polynomial of least degree agreeing with f and f' at  $x_0, \ldots, x_n$  is unique and is given by

$$H_{2n+1}(x) = \sum_{j=0}^{n} f(x_j) H_{n,j}(x) + \sum_{j=0}^{n} f'(x_j) \widehat{H}_{n,j}(x),$$

where

$$H_{n,j}(x) = [1 - 2(x - x_j)L'_{n,j}(x_j)]L^2_{n,j}(x), \quad \widehat{H}_{n,j}(x) = (x - x_j)L^2_{n,j}(x),$$

and

$$L_{n,j}(x) = \frac{(x-x_0)\cdots(x-x_{j-1})(x-x_{j+1})\cdots(x-x_n)}{(x_j-x_0)\cdots(x_j-x_{j-1})(x_j-x_{j+1})\cdots(x_j-x_n)}.$$

Moreover, if  $f \in C^{2n+2}[a,b]$ , then  $\exists \xi(x) \in [a,b]$  s.t.

$$f(x) = H_{2n+1}(x) + \frac{(x-x_0)^2 \cdots (x-x_n)^2}{(2n+2)!} f^{(2n+2)}(\xi(x)).$$

Proof: The representation

$$H_{2n+1}(x) = \sum_{j=0}^{n} f(x_j) H_{n,j}(x) + \sum_{j=0}^{n} f'(x_j) \widehat{H}_{n,j}(x),$$

suggests that it suffices to construct  $H_{n,j}(x)$  and  $\hat{H}_{n,j}(x)$  with

$$\begin{cases} H_{n,j}(x_j) = 1 \\ H'_{n,j}(x_j) = 0 \end{cases}, \quad H_{n,j}(x_i) = H'_{n,j}(x_i) = 0 \quad \text{if } i \neq j,$$

and

$$\begin{cases} \hat{H}_{n,j}(x_j) = 0 \\ \hat{H}'_{n,j}(x_j) = 1 \end{cases}, \quad \hat{H}_{n,j}(x_i) = \hat{H}'_{n,j}(x_i) = 0 \quad \text{if } i \neq j,$$

It is easy to see that  $\deg H_{n,j} \leq 2n+1$  and  $\deg H_{n,j} \leq 2n+1$ . Since  $\deg L_{n,j}^2 = 2n$  and

$$L_{n,j}^2(x_i) = (L_{n,j}^2)'(x_i) = 0$$
, for  $i \neq j$ 

We can simply seek for  $H_{n,j}(x)$  and  $\hat{H}_{n,j}(x)$  of the form

$$H_{n,j}(x) = (a(x-x_j)+b)L_{n,j}^2(x), \quad \hat{H}_{n,j}(x) = (\hat{a}(x-x_j)+\hat{b})L_{n,j}^2(x)$$

The coefficients a, b and  $\hat{a}$ ,  $\hat{b}$  can be easily solved from the conditions

$$H_{n,j}(x_i) = 1, \quad H'_{n,j}(x_i) = 0,$$

and

$$\hat{H}_{n,j}(x_i) = 0, \quad \hat{H}'_{n,j}(x_i) = 1,$$

respectively.

## **Proof of uniqueness:**

• Since  $deg(P) \leq 2n + 1$ , write

$$P(x) = a_0 + a_1 x + \dots + a_{2n+1} x^{2n+1}.$$

• 2n+2 coefficients,  $a_0, a_1, \ldots, a_{2n+1}$ , to be determined and 2n+2 conditions given

$$P(x_i) = f(x_i), \quad P'(x_i) = f'(x_i), \text{ for } i = 0, ..., n.$$

 $\Rightarrow 2n+2$  linear equations in 2n+2 unknowns to solve

 $\Rightarrow$  show that the coefficient matrix A of this system is nonsingular.

- To prove A is nonsingular, it suffices to prove that Au = 0 has only the trivial solution u = 0.
- Au = 0 iff

$$P(x_i) = 0, \quad P'(x_i) = 0, \text{ for } i = 0, \dots, n.$$

 $\Rightarrow P$  is a multiple of the polynomial given by

$$q(x) = \prod_{i=0}^{n} (x - x_i)^2$$
.

- However, deg(q) = 2n + 2 whereas P has degree at most N.
- Therefore, P(x) = 0, i.e. u = 0.
- That is, A is nonsingular, and the Hermite interpolation problem has a unique solution.

## Divided Difference Method for Hermite Interpolation

Given the 2n + 2 condition pairs

$$(x_0, f(x_0)), (x_0, f'(x_0)), (x_1, f(x_1)), (x_1, f'(x_1)), \cdots, (x_n, f(x_n)), (x_n, f'(x_n))$$

Rename the x-coordinates as  $z_0, z_1, \dots, z_{2n+1}$ , where

$$z_0 = z_1 = x_0, z_2 = z_3 = x_1, \cdots, z_{2n+1} = z_{2n+2} = x_n.$$

Note that  $z_0 \le z_1 \le \cdots \le z_N$ . If  $z_j$  were distinct, then the unique Hermite interpolating polynomial in Newton's form is given by

$$H_{2n+1}(x) = f[z_0] + \sum_{k=1}^{2n+2} f[z_0, z_1, \dots, z_k](x-z_0)(x-z_1) \cdots (x-z_{k-1}).$$

When  $k \geq 2$ ,  $z_i \neq z_{i+k}$ , the k-th divided difference is well defined:

$$f[z_i, z_{i+1}, \dots, z_{i+k}] = \frac{f[z_{i+1}, z_{i+2}, \dots, z_{i+k}] - f[z_i, z_{i+1}, \dots, z_{i+k-1}]}{z_{i+k} - z_i}.$$

However the first divided-difference formula has to be modified since  $z_{2i} = z_{2i+1} = x_i$  for each i. Let

$$z_{2i} = x_i, \qquad z_{2i+1}^{\epsilon} = x_i + \epsilon.$$

and let  $\epsilon \to 0$ . Formally, it suffices to replace the first divided differences by

$$f[z_{2i}, z_{2i+1}] := \lim_{\epsilon \to 0} f[z_{2i}, z_{2i+1}^{\epsilon}] = f'(z_{2i}) = f'(x_i)$$



z	f(z)		
$z_0 = x_0$	$f[z_0] = f(x_0)$		
		$f[z_0, z_1^{\epsilon}] = \frac{f[z_1^{\epsilon}] - f[z_0]}{z_1^{\epsilon} - z_0}$	
$z_1^{\epsilon} = x_0 + \epsilon$	$f[z_1^{\epsilon}] = f(z_1^{\epsilon})$		$f[z_0, z_1^{\epsilon}, z_2] = \frac{f[z_1^{\epsilon}, z_2] - f[z_0, z_1^{\epsilon}]}{z_2 - z_0}$
		$f[z_1^{\epsilon}, z_2] = \frac{f[z_2] - f[z_1^{\epsilon}]}{z_2 - z_1^{\epsilon}}$	
$z_2 = x_1$	$f[z_2] = f(x_1)$	<u>-</u>	$f[z_1^{\epsilon}, z_2, z_3^{\epsilon}] = \frac{f[z_2, z_3^{\epsilon}] - f[z_1^{\epsilon}, z_2]}{z_3^{\epsilon} - z_1^{\epsilon}}$
		$f[z_2, z_3^{\epsilon}] = \frac{f[z_3^{\epsilon}] - f[z_2]}{z_2^{\epsilon} - z_2}$	*3 *1
$z_3^{\epsilon} = x_1 + \epsilon$	$f[z_3^{\epsilon}] = f(z_3^{\epsilon})$	$z_3$ $z_2$	$f[z_2, z_3^{\epsilon}, z_4] = \frac{f[z_3^{\epsilon}, z_4] - f[z_2, z_3^{\epsilon}]}{z_4 - z_2}$
3 1	a [ 3] a ( 3)	$f[z_3^{\epsilon}, z_4] = \frac{f[z_4] - f[z_3^{\epsilon}]}{z_4 - z_2^{\epsilon}}$	$z_4-z_2$
$z_4 = x_2$	$f[z_4] = f(x_2)$	$z_4-z_3$	$f[z_3^{\epsilon}, z_4, z_5^{\epsilon}] = \frac{f[z_4, z_5^{\epsilon}] - f[z_3^{\epsilon}, z_4]}{z_5^{\epsilon} - z_5^{\epsilon}}$
$z_4 - x_2$	$J [\sim 4] - J (\sim 2)$	$f[z_5^{\epsilon}] - f[z_4]$	$J[\sim_3,\sim_4,\sim_5]$ $z_5^{\epsilon}-z_3^{\epsilon}$
	rr el (r/ e)	$f[z_4, z_5^{\epsilon}] = \frac{f[z_5^{\epsilon}] - f[z_4]}{z_5^{\epsilon} - z_4}$	
$z_5^{\epsilon} = x_2 + \epsilon$	$f[z_5^{\epsilon}] = f(z_5^{\epsilon})$		



As  $\epsilon \to 0$ ,  $z_1^{\epsilon} \to z_1 := x_0$ ,  $f[z_1^{\epsilon}] \to f(x_0)$ ,  $f[z_0, z_1^{\epsilon}] \to f[z_0, z_1] := f'(x_0)$ , etc.

$$z_{0} = x_{0} \quad f[z_{0}] = f(x_{0})$$

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$$f[z_{1}, z_{2}] = \frac{f[z_{2}] - f[z_{1}]}{z_{2} - z_{1}}$$

$$z_{2} = x_{1} \quad f[z_{2}] = f(x_{1})$$

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$$f[z_{2}, z_{3}] = \frac{f[z_{2}, z_{3}] - f[z_{2}, z_{3}]}{z_{4} - z_{2}}$$

$$f[z_{2}, z_{3}, z_{4}] = \frac{f[z_{3}, z_{4}] - f[z_{2}, z_{3}]}{z_{4} - z_{2}}$$

$$f[z_{3}, z_{4}] = \frac{f[z_{4}] - f[z_{3}]}{z_{4} - z_{3}}$$

$$f[z_{4}, z_{5}] = f'(x_{2})$$

$$z_{5} = x_{2} \quad f[z_{5}] = f(x_{2})$$

$$H_{2n+1}(x) = f[z_0] + \sum_{k=1}^{2n+2} f[z_0, z_1, \dots, z_k](x - z_0)(x - z_1) \cdots (x - z_{k-1}).$$