

Analyzing The Existence Theorem: Implications For Weakly Singular Integral Equations*

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Abstract

This article discusses the solvability of a weakly singular integral equation with a logarithm kernel. These equations are defined within the function space $C[0, \ell]$, which consists of real-valued functions. The primary methodological framework employed in our proofs is the concept of a measure of noncompactness in conjunction with the theorem of Petryshyn. Furthermore, we illustrate the practical significance of our findings by presenting a series of applications related to nonlinear singular integral equations. These examples serve to demonstrate the efficacy and applicability of our theoretical results, thereby contributing to the broader understanding of such integral equations in mathematical analysis.

Keywords: Measure of noncompactness; weakly singular integral equation; condensing map; existence results; Petryshyn's theorem.

1 Introduction

Functional integral equations (FIEs) are powerful tools used in a range of fields, such as mathematics [20, 27, 31], engineering [4, 20], bio-engineering [24, 33, 39], and applied sciences [15, 37]. The IEs are increasingly popular because they can accurately model complex phenomena. In recent years, there has been significant interest in both applied and pure analysis in FIEs, including ordinary and partial equations [1, 10, 19, 35].

In 2002, Butzer et al. [6] presented a novel approach to differentiation and integration on $(0, \infty)$ of the form

$$J_{0+;c}^\sigma v(r) = \int_0^r \left(\frac{\tau}{r}\right)^c \left(\log \frac{r}{\tau}\right)^{\sigma-1} \frac{v(\tau)}{\tau\gamma(\sigma)} d\tau, \quad \sigma > 0, \quad c \in \mathbb{R},$$

in terms of classical Mellin transform $(T_M)\mathcal{M}$ of function $v : \mathbb{R}^{>0} \rightarrow \mathbb{C}$ given by

$$T_M(v(r)) = \int_0^\infty \tau^{r-1} v(\tau) d\tau, \quad r = c + it, \quad c, t \in \mathbb{R},$$

which was a generalization of Hadamard's article [14], for more instances, see [18, 34]. Das et al. studied the existence of solution of generalized IEs of fractional order with two variables and proved a new fixed point theorem applying the measure of noncompactness (M.N.C) and a new contraction operator which generalized the Darbo's fixed point theorem (D-theorem) [10]. Paul et al. investigated the existence, uniqueness, stabilities of Hyers-Ulam-Rassias and Hyers-Ulam, and local stability of the solutions of the following nonlinear Volterra-Fredholm IE involving the Erdélyi-Kober fractional integral operator, for $r \in \mathbb{R}^{>0}$,

$$v(r) = w(r) + y_1(r) \int_0^r \frac{\mu^\gamma(r^\rho - \tau^\rho)}{\gamma(\delta)} f_1(r, \mu, v(\tau)) d\tau + y_2(r) \int_0^s \frac{\mu^\gamma(r^\rho - \tau^\rho)}{\gamma(\delta)} f_2(r, \mu, v(\tau)) d\tau,$$

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with $s \in \mathbb{R}^{>0}$, the function $w, y_1, y_2 : \mathbb{R}^{>0} \rightarrow \mathbb{R}$, where $r, \mu, \rho, \delta \in \mathbb{R}^{>0}$ and $\mathbb{f}_i \in C(\mathbb{R}^{>0} \times \mathbb{R}^{>0} \times \mathbb{R})$ [28]. They established the existence and uniqueness, and analyzed stabilities of Hyers-Ulam-Rassias and Hyers-Ulam of the solution for the nonlinear I \mathbb{E} in the case of the Riemann-Liouville fractional operator of the form

$$v(r) = w(r) + y(r) \int_0^r \frac{(r-\tau)^\sigma}{\gamma(\sigma)} \eta(\tau) \mathbb{f}(v(\tau)) d\tau, \quad r \in \Delta_\ell := [0, \ell],$$

where $\sigma \in \mathbb{R}^{>0}$ with the continuous functions $\mathbb{f} : C(\Delta_\ell) \rightarrow \mathbb{R}$ and $w, y, \eta : \Delta_\ell \rightarrow \mathbb{R}$, based on the Leray-Schauder alternative and Banach's fixed point theorem [29]. Researchers have focused on studying the existence of solutions for F $\mathbb{I}\mathbb{E}$ s, particularly those involving weakly singular I \mathbb{E} s (WSI \mathbb{E} s). One of the most commonly used methods is the concept of M.N.C. The root of this concept goes back to the famous work of Kuratowski [21]. This method plays a vital role in the publications of research [3].

In 1955, Darbo [8] established a ground-breaking theorem that proves the existence of fixed points for condensing operators using the concept of M.N.C. This theorem has found wide application in various scientific fields, particularly in finding solutions for both F $\mathbb{I}\mathbb{E}$ s and differential equations (D \mathbb{E} s) [5, 7, 22, 36, 38, 40]. Bhat et al. discussed the numerical solutions and studied the existence of the unique solutions of weakly singular Volterra and Fredholm I \mathbb{E} s, which were used to demonstrate the problems like heat conduction in engineering and the electrostatic potential theory, based on the modified Lagrange polynomial interpolation technique combined with the biconjugate gradient stabilized method [5]. Authors [12] obtained results to existence of solutions for the following nonlinear F $\mathbb{I}\mathbb{E}$ s,

$$\begin{aligned} v(r) &= \left[y_1(r, v(r)) + \mathbb{G}_1 \left(r, \int_0^r \mathbb{f}_1(r, \tau, v(\tau)) d\tau, \int_0^r \mathbb{h}_1(r, \tau, v(\tau)), v(\tau) \right) \right] \\ &\quad \times \left[y_2(r, v(r)) + \mathbb{G}_2 \left(r, \int_0^r \mathbb{f}_2(r, \tau, v(\tau)) d\tau, \int_0^r \mathbb{h}_2(r, \tau, v(\tau)), v(\tau) \right) \right], \end{aligned}$$

for $r \in \Delta_\ell$ where $y_i \in C(\Delta_\ell \times \mathbb{R}^2)$, $\mathbb{G}_i \in C(\Delta_\ell \times \mathbb{R}^3)$, $i = 1, 2$. Metwali and Mishra in [23], proved a new compactness criterion in the Lebesgue spaces $L_p(\mathbb{R}^{>0})$, $1 \leq p < \infty$ and used such criteria to construct a M.N.C in the mentioned spaces and applied such M.N.C with a modified version of D-theorem in proving the existence of monotonic integrable solutions for a product of n -Hammerstein I \mathbb{E} s, $n \geq 2$, is given by,

$$v(r) = y(r, v(r)) + \prod_{i=1}^n \left(\mathbb{f}_i(r, v(r)) + \mathbb{h}_i(r, v(r)) \cdot |v(r)|^{p/q_i} \int_0^\infty \mathbb{K}_i(r, \tau) \mathbb{u}_i(\tau, v(\tau)) d\tau \right),$$

where $p < q_i < \infty$. Nashine et al. investigated the solutions of a system of F $\mathbb{I}\mathbb{E}$ is expressed by,

$$\begin{cases} v(r) = \mathbb{G} \left(r, v(r), q(r), \int_0^r \mathbb{f}(r, \tau, v(\tau), q(\tau)) d\tau \right), \\ q(r) = \mathbb{G} \left(r, q(r), v(r), \int_0^r \mathbb{f}(r, \tau, q(\tau), v(\tau)) d\tau \right), \end{cases}$$

in the setting of M.N.C on real-valued bounded and continuous Banach space by using Darbo type fixed and coupled fixed point results for μ -set (ω, ϑ) -contraction operator and arbitrary M.N.C in this spaces, where $\mathbb{G} \in C(\mathbb{R}^{>0} \times \mathbb{R}^3)$ along with the some conditions [25]. The D-theorem offers a significant advantage over Schauder's theorem by relaxing the requirement of compactness for the operator's domain [2]. This flexibility makes it suitable for studying solvability in different types of equations, including implicit D \mathbb{E} s, I-D \mathbb{E} s, and equations arising in controllability problems for dynamical systems [9, 11].

Although D-theorem is highly effective in this field, the method is still criticized for its tendency to impose many conditions on the problem, which is seen as a significant weakness. In 2016, by the assistance of M.N.C and fixed point theorem of Petryshyn (P-theorem), Kazemi et al. established that the sub-linear conditions in D-theorem is an additional condition [16, 32].

This article analyzes the existence result for the following WSI \mathbb{E} ,

$$v(r) = \mathbb{g} \left(r, \sum_{i=1}^s v(\beta_i(r)) \right) + \mathbb{f} \left(r, \sum_{j=1}^m v(\alpha_j(r)) \right) \int_0^r \ln |\tau - r| \mathbb{u} \left(r, \tau, \sum_{k=1}^n v(\gamma_k(r)) \right) d\tau, \quad (1)$$

for $r, \tau \in \Delta_\ell$, with $\mathcal{U}_{p=1}^q v(\hat{\eta}_p(\cdot)) := (v(\hat{\eta}_1(\cdot)), v(\hat{\eta}_2(\cdot)), \dots, v(\hat{\eta}_q(\cdot)))$, where

W1) functions β_i , α_j and $\gamma_k \in C(\Delta_\ell)$ with $1 \leq i \leq s$, $1 \leq j \leq m$ and $1 \leq k \leq n$.

In the following, we consider the outline of the paper. In Section 2, we collect some definitions, lemmas and theorems, which are essential to prove our main results. In Section 3, we establish and prove a new existence theorem by utilizing the P-theorem for WSE (1). In Section 4, we also give few examples to support our main theorem. Finally, In Section 5, concludes the paper.

2 Auxiliary Facts and Notations

In this section, we will review several definitions and theorems, providing additional facts to enhance understanding.

Definition 1 ([13, 21]) *Let B be a bounded subset of a Banach space \mathbb{F} . The M.N.C types of Kuratowski and Hausdroff are expressed by,*

$$\begin{aligned} \mathfrak{m}_K(B) &= \inf \left\{ \varepsilon > 0 : A \text{ may be covered by finitely multiple sets of diameter } \leq \varepsilon \right\}, \\ \mathfrak{m}_H(B) &= \inf \left\{ \varepsilon > 0 : \text{there is a finite } \varepsilon\text{-net for } B \in \mathbb{F} \right\}. \end{aligned} \quad (2)$$

Theorem 1 ([30]) *Let $B, \tilde{B} \in \mathbb{F}$ and $\lambda \in \mathbb{R}$. Then*

- i) $\mathfrak{m}_H(B) = 0$ iff B is relatively-compact;
- ii) $B \subseteq \tilde{B} \implies \mathfrak{m}_H \leq \mathfrak{m}_H(\tilde{B})$;
- iii) $\mathfrak{m}_H(\bar{B}) = \mathfrak{m}_H(\text{conv } B) = \mathfrak{m}_H(B)$;
- iv) $\mathfrak{m}_H(B \cup \tilde{B}) = \max \{ \mathfrak{m}_H(B), \mathfrak{m}_H(\tilde{B}) \}$;
- v) $\mathfrak{m}_H(\lambda B) = |\lambda| \mathfrak{m}_H(B)$;
- vi) $\mathfrak{m}_H(B + \tilde{B}) \leq \mathfrak{m}_H(B) + \mathfrak{m}_H(\tilde{B})$.

In the following, we will operate in the space $C(\Delta_\ell)$ endowed with the norm $\|v\| = \sup\{|v(r)| : r \in \Delta_\ell\}$. Recall that the modulus of continuity of a function $v \in C(\Delta_\ell)$ is defined as,

$$\omega(v, \varepsilon) = \sup \left\{ |v(r) - v(\tilde{r})| : |r - \tilde{r}| \leq \varepsilon \right\}.$$

Theorem 2 ([17]) *For all bounded sets $B \subset C(\Delta_\ell)$, the M.N.C (2) is equivalent to,*

$$\mathfrak{m}_H(B) = \lim_{\varepsilon \rightarrow 0} \sup_{v \in B} \omega(v, \varepsilon).$$

Definition 2 ([26]) *Assume that $\mathfrak{W} : \mathbb{F} \rightarrow \mathbb{F}$ be a continuous mapping of \mathbb{F} . \mathfrak{W} is called a k -set contraction if for all bounded subset $B \subset \mathbb{F}$, $\mathfrak{W}(B)$ is bounded and $\mathfrak{m}_K(\mathfrak{W}(B)) \leq k \mathfrak{m}_K(B)$, $0 < k < 1$. If $\mathfrak{m}_K(\mathfrak{W}(B)) < \mathfrak{m}_K(B)$, for each $\mathfrak{m}_K(H) > 0$, then \mathfrak{W} is called densifying (or condensing) map.*

Theorem 3 (P-theorem [30]) *Assume that $\mathfrak{W} : \bar{B}_{r_0} \rightarrow \mathbb{F}$ be a condensing mapping which satisfies the boundary condition, $\mathfrak{W}(v) = kv$, for some v in ∂B_{r_0} with $k \leq 1$, then the set of fixed points of \mathfrak{W} in \bar{B}_{r_0} is non-empty, where \bar{B}_{r_0} and $\partial \bar{B}_{r_0}$ are closed ball at center 0 and sphere in \mathbb{F} around 0, respectively with radius $r_0 > 0$.*

3 An Existence Theorem Based on P-theorem

We consider the essential assumptions to verify the existence of a solution for FWSIE (1):

M1) $\mathbf{g} \in C(\Delta_\ell \times \mathbb{R}^s)$ and $\mathbf{f} \in C(\Delta_\ell \times \mathbb{R}^m)$ and there exist q_i, λ_j for $1 \leq i \leq s, 1 \leq j \leq m$ such that

$$\begin{aligned} |\mathbf{g}(r, v_1, v_2, \dots, v_s) - \mathbf{g}(r, \tilde{v}_1, \tilde{v}_2, \dots, \tilde{v}_s)| &\leq \sum_{i=1}^s q_i |v_i - \tilde{v}_i| \\ |\mathbf{f}(r, v_1, v_2, \dots, v_m) - \mathbf{f}(r, \tilde{v}_1, \tilde{v}_2, \dots, \tilde{v}_m)| &\leq \sum_{j=1}^m \lambda_j |v_j - \tilde{v}_j|, \end{aligned}$$

M2) There exists $r_\circ > 0$ such that

$$\sup \left| \mathbf{g} \left(r, \sum_{i=1}^s v_i(\beta_i(r)) \right) + \mathbf{f} \left(r, \sum_{j=1}^m v_j(\alpha_j(r)) \right) \int_0^r \ln |\tau - r| \mathbf{u} \left(r, \tau, \sum_{k=1}^n v_k(\gamma_k(r)) \right) d\tau \right| \leq r_\circ,$$

with $\sum_{i=1}^s q_i + \Omega \sum_{j=1}^m \lambda_j < 1$, where

$$\Omega = \sup \left\{ |\mathbf{u}(r, \tau, v_1, v_2, \dots, v_n)| : r, \tau \in \Delta_\ell, v_i \in [-r_\circ, r_\circ], 1 \leq i \leq n \right\}.$$

Theorem 4 Assume that (M1) and (M2) hold. Then FWSIE (1) has at least one solution in $C(\Delta_\ell)$.

Proof. Define the operator $\mathfrak{D} : B_{r_\circ} \rightarrow C(\Delta_\ell)$ as follows

$$(\mathfrak{D}v)(r) = \mathbf{g} \left(r, \sum_{i=1}^s v_i(\beta_i(r)) \right) + \mathbf{f} \left(r, \sum_{j=1}^m v_j(\alpha_j(r)) \right) \int_0^r \ln |\tau - r| \mathbf{u} \left(r, \tau, \sum_{k=1}^n v_k(\gamma_k(r)) \right) d\tau,$$

where $B_{r_\circ} = \{v \in C(\Delta_\ell) : \|v\| \leq r_\circ\}$. We divide the proof into several steps.

Step 1. Consider arbitrary $v, \tilde{v} \in B_{r_\circ}$ and $\varepsilon > 0$ such that $\|v - \tilde{v}\| < \varepsilon$. Then,

$$\begin{aligned} &|(\mathfrak{D}v)(r) - (\mathfrak{D}\tilde{v})(r)| \\ &= \left| \mathbf{g} \left(r, \sum_{i=1}^s v_i(\beta_i(r)) \right) + \mathbf{f} \left(r, \sum_{j=1}^m v_j(\alpha_j(r)) \right) \int_0^r \ln |\tau - r| \mathbf{u} \left(r, \tau, \sum_{k=1}^n v_k(\gamma_k(r)) \right) d\tau \right. \\ &\quad \left. - \mathbf{g} \left(r, \sum_{i=1}^s \tilde{v}_i(\beta_i(r)) \right) - \mathbf{f} \left(r, \sum_{j=1}^m \tilde{v}_j(\alpha_j(r)) \right) \int_0^r \ln |\tau - r| \mathbf{u} \left(r, \tau, \sum_{k=1}^n \tilde{v}_k(\gamma_k(r)) \right) d\tau \right| \\ &\leq \left| \mathbf{g} \left(r, \sum_{i=1}^s v_i(\beta_i(r)) \right) - \mathbf{g} \left(r, \sum_{i=1}^s \tilde{v}_i(\beta_i(r)) \right) \right| \\ &\quad + \left| \left[\mathbf{f} \left(r, \sum_{j=1}^m v_j(\alpha_j(r)) \right) - \mathbf{f} \left(r, \sum_{j=1}^m \tilde{v}_j(\alpha_j(r)) \right) \right] \int_0^r \ln |\tau - r| \mathbf{u} \left(r, \tau, \sum_{k=1}^n \tilde{v}_k(\gamma_k(r)) \right) d\tau \right| \\ &\quad + \left| \mathbf{f} \left(r, \sum_{j=1}^m v_j(\alpha_j(r)) \right) \int_0^r \ln |\tau - r| \left[\mathbf{u} \left(r, \tau, \sum_{k=1}^n v_k(\gamma_k(r)) \right) - \mathbf{u} \left(r, \tau, \sum_{k=1}^n \tilde{v}_k(\gamma_k(r)) \right) \right] d\tau \right| \\ &\leq \left| \mathbf{g} \left(r, \sum_{i=1}^s v_i(\beta_i(r)) \right) - \mathbf{g} \left(r, \sum_{i=1}^s \tilde{v}_i(\beta_i(r)) \right) \right| \\ &\quad + \left| \mathbf{f} \left(r, \sum_{j=1}^m v_j(\alpha_j(r)) \right) - \mathbf{f} \left(r, \sum_{j=1}^m \tilde{v}_j(\alpha_j(r)) \right) \right| \int_0^r \ln |\tau - r| \left| \mathbf{u} \left(r, \tau, \sum_{k=1}^n \tilde{v}_k(\gamma_k(r)) \right) \right| d\tau \\ &\quad + \left| \mathbf{f} \left(r, \sum_{j=1}^m v_j(\alpha_j(r)) \right) \right| \int_0^r \ln |\tau - r| \left| \mathbf{u} \left(r, \tau, \sum_{k=1}^n v_k(\gamma_k(r)) \right) - \mathbf{u} \left(r, \tau, \sum_{k=1}^n \tilde{v}_k(\gamma_k(r)) \right) \right| d\tau \\ &\leq \sum_{i=1}^s q_i |v_i(\beta_i(r)) - \tilde{v}_i(\beta_i(r))| + \sum_{j=1}^m \lambda_j |v_j(\alpha_j(r)) - \tilde{v}_j(\alpha_j(r))| \Omega |\ell(\ln \ell - 1)| + \sup(\mathbf{f}) |\ell(\ln \ell - 1)| \omega(v, \varepsilon) \end{aligned}$$

$$\leq \left[\sum_{i=1}^s q_i + \Omega |\ell(\ln \ell - 1)| \sum_{j=1}^m \lambda_j \right] \|v - \tilde{v}\| + \sup(\mathbb{F}) |\ell(\ln \ell - 1)| \omega(v, \varepsilon),$$

where

$$\sup(\mathbb{F}) = \left\{ |\mathbb{F}(r, v_1, v_2, \dots, v_m)| : r \in \Delta_\ell, v_i \in [-r_\circ, r_\circ], 1 \leq i \leq n \right\}$$

and

$$\begin{aligned} \omega(v, \varepsilon) &= \sup \left\{ |\mathbb{U}(r, \tau, v_1, v_2, \dots, v_n) - \mathbb{U}(r, \tau, \tilde{v}_1, \tilde{v}_2, \dots, \tilde{v}_n)| : r, \tau \in \Delta_\ell, \right. \\ &\quad \left. v_i, \tilde{v}_i \in [-r_\circ, r_\circ], 1 \leq i \leq n, \|v - \tilde{v}\| \leq \varepsilon \right\}. \end{aligned}$$

The uniform continuity of $\widehat{\mathbb{U}} = \mathbb{U}(r, \tau, v_1, v_2, \dots, v_n)$ on $\Delta_\ell^2 \times [-r_\circ, r_\circ]^n$ yields $\omega(v, \varepsilon) \rightarrow 0$ as $\varepsilon \rightarrow 0$. Then, the operator \mathfrak{D} is continuous on B_{r_\circ} .

Step 2. We show that the operator \mathfrak{D} is a condensing map in view of measure \mathfrak{m}_H . For arbitrary $\varepsilon > 0$, v in bounded subset $\Psi \subset \mathbb{F}$, and $r_1, r_2 \in \Delta_\ell$ with $|r_2 - r_1| \leq \varepsilon$, we obtain

$$\begin{aligned} &|(\mathfrak{D}v)(r_2) - (\mathfrak{D}v)(r_1)| \\ &= \left| \mathfrak{g} \left(r_2, \sum_{i=1}^s v(\beta_i(r_2)) \right) \right. \\ &\quad \left. + \mathbb{f} \left(r_2, \sum_{j=1}^m v(\alpha_j(r_2)) \right) \int_0^{r_2} \ln |\tau - r_2| \mathbb{u} \left(r_2, \tau, \sum_{k=1}^n v(\gamma_k(\tau)) \right) d\tau - \mathfrak{g} \left(r_1, \sum_{i=1}^s v(\beta_i(r_1)) \right) \right. \\ &\quad \left. - \mathbb{f} \left(r_1, \sum_{j=1}^m v(\alpha_j(r_1)) \right) \int_0^{r_1} \ln |\tau - r_1| \mathbb{u} \left(r_1, \tau, \sum_{k=1}^n v(\gamma_k(\tau)) \right) d\tau \right| \\ &\leq \left| \mathfrak{g} \left(r_2, \sum_{i=1}^s v(\beta_i(r_2)) \right) - \mathfrak{g} \left(r_2, \sum_{i=1}^s v(\beta_i(r_1)) \right) \right| \\ &\quad + \left| \mathfrak{g} \left(r_2, \sum_{i=1}^s v(\beta_i(r_1)) \right) - \mathfrak{g} \left(r_1, \sum_{i=1}^s v(\beta_i(r_1)) \right) \right| \\ &\quad + \left| \mathbb{f} \left(r_2, \sum_{j=1}^m v(\alpha_j(r_2)) \right) \int_0^{r_2} \ln |\tau - r_2| \mathbb{u} \left(r_2, \tau, \sum_{k=1}^n v(\gamma_k(\tau)) \right) d\tau \right. \\ &\quad \left. - \mathbb{f} \left(r_1, \sum_{j=1}^m v(\alpha_j(r_1)) \right) \int_0^{r_1} \ln |\tau - r_1| \mathbb{u} \left(r_1, \tau, \sum_{k=1}^n v(\gamma_k(\tau)) \right) d\tau \right| \\ &\leq \left| \mathfrak{g} \left(r_2, \sum_{i=1}^s v(\beta_i(r_2)) \right) - \mathfrak{g} \left(r_2, \sum_{i=1}^s v(\beta_i(r_1)) \right) \right| \\ &\quad + \left| \mathfrak{g} \left(r_2, \sum_{i=1}^s v(\beta_i(r_1)) \right) - \mathfrak{g} \left(r_1, \sum_{i=1}^s v(\beta_i(r_1)) \right) \right| \\ &\quad + \left\{ \left| \mathbb{f} \left(r_2, \sum_{j=1}^m v(\alpha_j(r_2)) \right) - \mathbb{f} \left(r_2, \sum_{j=1}^m v(\alpha_j(r_1)) \right) \right| \right. \\ &\quad \left. + \left| \mathbb{f} \left(r_2, \sum_{j=1}^m v(\alpha_j(r_1)) \right) - \mathbb{f} \left(r_1, \sum_{j=1}^m v(\alpha_j(r_1)) \right) \right| \right\} \int_0^{r_2} \ln |\tau - r_2| \mathbb{u} \left(r_2, \tau, \sum_{k=1}^n v(\gamma_k(\tau)) \right) d\tau \\ &\quad + \left| \mathbb{f} \left(r_1, \sum_{j=1}^m v(\alpha_j(r_1)) \right) \int_0^{r_2} \ln |\tau - r_2| \left[\mathbb{u} \left(r_2, \tau, \sum_{k=1}^n v(\gamma_k(\tau)) \right) \right. \right. \\ &\quad \left. \left. - \mathbb{u} \left(r_1, \tau, \sum_{k=1}^n v(\gamma_k(\tau)) \right) \right] d\tau \right| \\ &\quad + \left| \mathbb{f} \left(r_1, \sum_{j=1}^m v(\alpha_j(r_1)) \right) \int_0^{r_2} \mathbb{u} \left(r_1, \tau, \sum_{k=1}^n v(\gamma_k(\tau)) \right) (\ln(\tau - r_2) - \ln(\tau - r_1)) d\tau \right| \\ &\quad + \left| \mathbb{f} \left(r_1, \sum_{j=1}^m v(\alpha_j(r_1)) \right) \int_{r_1}^{r_2} \ln |\tau - r_1| \mathbb{u} \left(r_1, \tau, \sum_{k=1}^n v(\gamma_k(\tau)) \right) d\tau \right| \end{aligned}$$

$$\leq \sum_{i=1}^s q_i |v(\beta_i(r_2)) - v(\beta_i(r_1))| + \omega_g(\varepsilon) + \left[\sum_{j=1}^m \lambda_j |v(\alpha_j(r_2)) - v(\alpha_j(r_1))| + \omega_f(\varepsilon) \right] |\ell(\ln \ell - 1)| \Omega \\ + \sup(f) |r_2(\ln r_2 - 1)| \omega_u(\varepsilon) + 2 \sup(f) \Omega |\ell(\ln \ell - 1)| + \sup(f) \Omega |r_2 - r_1|,$$

where for $r_2, r_1 \in \Delta_\ell$, $v_i \in [-r_o, r_o]$, $1 \leq i \leq m$, $|r_2 - r_1| \leq \varepsilon$,

$$\begin{cases} \omega_g(\varepsilon) = \sup \left| g(r_2, v_1, v_2, \dots, v_m) - g(r_1, v_1, v_2, \dots, v_m) \right|, \\ \omega_f(\varepsilon) = \sup \left| f(r_2, v_1, v_2, \dots, v_m) - f(r_1, v_1, v_2, \dots, v_m) \right|, \\ \omega_u(\varepsilon) = \sup \left| u(r_2, v_1, v_2, \dots, v_m) - u(r_1, v_1, v_2, \dots, v_m) \right|. \end{cases} \quad (3)$$

From Ineqs. (3), we obtain

$$\omega(\mathfrak{D}v, \varepsilon) \leq \sum_{i=1}^s q_i \omega(v, \omega(\beta_j, \varepsilon)) + \omega_g(\varepsilon) + \left[\sum_{j=1}^m \lambda_j \omega(v, \omega(\alpha_i, \varepsilon)) + \omega_f(\varepsilon) \right] |\ell(\ln \ell - 1)| \Omega \\ + \sup(f) |r_2(\ln r_2 - 1)| \omega_u(\varepsilon) + 2 \sup(f) \Omega |\ell(\ln \ell - 1)| + \sup(f) \Omega \varepsilon.$$

By taking the supremum over Ψ and $\varepsilon \rightarrow 0$, we

$$\mathfrak{m}_H(\mathfrak{D}\Psi) \leq \left[\sum_{i=1}^s q_i + \Omega \sum_{j=1}^m \lambda_j \right] \mathfrak{m}_H(\Psi).$$

Assumption (M2) together with Definition 2 imply that \mathfrak{D} is a condensing map.

Step 3. Suppose that $v \in \partial B_{r_o} = \{v \in C(\Delta_\ell) : \|v\| = r_o\}$ and $\mathfrak{D}v = \zeta v$. Then we get $\|\mathfrak{D}v\| = \zeta \|v\| = \zeta r_o$. Thus, (W3) implies that,

$$|(\mathfrak{D}v)(r)| = \left| g\left(r, \sum_{i=1}^s v(\beta_i(r))\right) + f\left(r, \sum_{j=1}^m v(\alpha_j(r))\right) \int_0^r \ln |\tau - r| u\left(r, \tau, \sum_{k=1}^n v(\gamma_k(r))\right) d\tau \right| \leq r_o, \quad (4)$$

and so, $\|\mathfrak{D}v\| \leq r_o$ which implies that $\zeta \leq 1$. Hence, under the assumptions (M1) and (M2), the FWSIE (1) has at least one solution $C(\Delta_\ell)$. ■

Corollary 1 *Under the control conditions as follows:*

M3) Let $g, f \in C(\Delta_\ell \times \mathbb{R})$ and there exists $q, \lambda \in \mathbb{R}^{>0}$ such that,

$$|g(r, v) - g(r, \tilde{v})| \leq q|v - \tilde{v}|, \quad |f(r, v) - f(r, \tilde{v})| \leq \lambda|v - \tilde{v}|.$$

M4) There exists $r_o > 0$ such that

$$\sup \left| g(r, v(r)) + f(r, v(r)) \int_0^r \ln |\tau - r| u(r, \tau, v(r)) d\tau \right| \leq r_o,$$

with $q + \Omega \lambda < 1$ where

$$\Omega = \sup \left\{ |u(r, \tau, v)| : v, \tau \in \Delta_\ell, v \in [-r_o, r_o] \right\},$$

Then the FWSIE,

$$v(r) = g(r, v(r)) + f(r, v(r)) \int_0^r \ln |\tau - r| u(r, \tau, v(r)) d\tau,$$

has at least one solution in $C(\Delta_\ell)$.

Proof. The proof is relevant to Theorem 4, so we can exclude the irrelevant parts. ■

4 Applications with Numerical Examples

In this part, we give some examples of **FWSIE** to explain the advantage of our results.

Example 1 Consider the following **FWSIE** in $C(\Delta_\ell)$, $\ell = 1$,

$$v(r) = \frac{r^4}{3(1+r^4)} (v(\sqrt{r}) + v(r^2)) + \frac{r^2+v(\sqrt{\sin r})}{12(1+r)} \int_0^1 \ln |\tau - r| \left(\sqrt[3]{v(\tau)} + \ln(1 + |v(\tau^2)|) \right) d\tau. \quad (5)$$

Clearly,

- $\beta_1(r) = \sqrt{r}$, $\beta_2(r) = r^2$, $\alpha_1(r) = \sqrt{\sin r}$, $\gamma_1(r) = r$, $\gamma_2(r) = r^2$,
- $\mathfrak{g}(r, v_1, v_2) = \frac{r^4}{3(1+r^4)} v_1 + \frac{r^4}{3(1+r^4)} v_2$, $\mathfrak{f}(r, v_1) = \frac{r^2+v_1}{12(1+r)}$,
- $\mathfrak{u}(r, \tau, v_1, v_2) = \sqrt[3]{v_1} + \ln(1 + |v_2|)$.

By taking these data, we have

$$\begin{aligned} |\mathfrak{g}(r, v_1, v_2) - \mathfrak{g}(r, \tilde{v}_1, \tilde{v}_2)| &= \left| \frac{r^4}{3(1+r^4)} v_1 + \frac{r^4}{3(1+r^4)} v_2 - \frac{r^4}{3(1+r^4)} \tilde{v}_1 - \frac{r^4}{3(1+r^4)} \tilde{v}_2 \right| \\ &\leq \frac{1}{3} |v_1 - \tilde{v}_1| + \frac{1}{3} |v_2 - \tilde{v}_2|, \end{aligned} \quad (6)$$

and

$$|\mathfrak{f}(r, v) - \mathfrak{f}(r, \tilde{v})| = \left| \frac{r^2+\tilde{v}}{12(1+r)} - \frac{r^2+\tilde{v}}{12(1+r)} \right| \leq \frac{1}{12} |v - \tilde{v}|. \quad (7)$$

Based on Ineqs. (6) and (7), the assumption (M1) holds when $q_1 = \frac{1}{3}$, $q_2 = \frac{1}{3}$ and $\lambda_1 = \frac{1}{12}$. In order to verify assumption (M2) observe that the inequality appearing in this assumption has the form,

$$\frac{2}{3} r_\circ + \frac{r_\circ + 1}{12} \left(\sqrt[3]{r_\circ} + \ln(1 + |r_\circ|) \right) \leq r_\circ. \quad (8)$$

It is easy to verify that the number $r_\circ \in [0.3103, 4.01835]$ satisfies Ineq. (8). Further, for $r_\circ = 1$, we have $\Omega = 1 + \ln 2 \approx 1.6931$ and $q_1 + q_2 + \Omega \lambda_1 = 0.8077583 < 1$. Therefore, all conditions of Theorem 4 are satisfied. This implies that the **FWSIE** (5) has at least one solution in $C(\Delta_\ell)$.

Example 2 Consider **FWSIE** as form,

$$v(r) = \frac{r^2}{2(1+r^2)} + \frac{v(\sqrt{r})}{10} + \frac{v(\sin r)}{15} + \frac{\sqrt[3]{r}+v(\cos r^2)}{10} \int_0^1 \ln |\tau - r| \left(\sqrt{v(\tau)} + \frac{\tau^3}{8} + \frac{v^2(\tau)}{6} \right) d\tau, \quad (9)$$

in $C(\Delta_\ell)$, $\ell = 1$. It can be seen that $\beta_1(r) = \sqrt{r}$, $\beta_2(r) = \sin r$, $\alpha_1(r) = \cos r$, $\gamma_1(r) = \gamma_2(r) = \tau$, $\alpha_1 = \cos r$, $\mathfrak{g}(r, v_1, v_2) = \frac{r^2}{2(1+r^2)} + \frac{v_1}{10} + \frac{v_2}{15}$, $\mathfrak{f}(r, v_1) = \frac{\sqrt[3]{r}+v_1}{10}$ and $\mathfrak{u}(r, \tau, v_1, v_2) = \sqrt{v_1} + \frac{r^3}{8} + \frac{r_2^2}{6}$. It is evident that

$$|\mathfrak{g}(r, v_1, v_2) - \mathfrak{g}(r, \tilde{v}_1, \tilde{v}_2)| = \left| \frac{v_1}{10} + \frac{v_2}{15} - \frac{\tilde{v}_1}{10} - \frac{\tilde{v}_2}{15} \right| \leq \frac{1}{10} |v_1 - \tilde{v}_1| + \frac{1}{15} |v_2 - \tilde{v}_2|, \quad (10)$$

and

$$|\mathfrak{f}(r, v) - \mathfrak{f}(r, \tilde{v})| = \left| \frac{\sqrt[3]{r}+v}{10} - \frac{\sqrt[3]{r}+\tilde{v}}{10} \right| \leq \frac{1}{10} |v - \tilde{v}|. \quad (11)$$

Thus, Ineqs. (10) and (11) confirm the assumption (M1) in Theorem 4 satisfies when $q_1 = \frac{1}{10}$, $q_2 = \frac{1}{15}$ and $\lambda_1 = \frac{1}{10}$. In order to verify assumption (M2) observe that the inequality appearing in this assumption has the form,

$$\frac{1}{2} + \frac{r_\circ}{10} + \frac{1}{15} + \frac{r_\circ + 1}{10} \left(\sqrt{r_\circ} + \frac{1}{8} + \frac{r_\circ^2}{6} \right) \leq r_\circ.$$

It is easy to verify that the number $r_\circ \in [0.87808, 5.01871]$ satisfies the last inequality inequality. Also, for $r_\circ = 2.114$, we have $\Omega = \sqrt{2} + \frac{1}{8} + \frac{2}{3} \approx 2.20588$ and $q_1 + q_2 + \Omega \lambda_1 = 0.38725 < 1$. Therefore, all conditions of Theorem 4 are satisfied. This implies that the **FWSIE** (5) has at least one solution in $C(\Delta_\ell)$.

5 Conclusion

The central aim in the theory of integral equations revolves around the existence and uniqueness of solutions. Therefore, several researchers have shared their findings and methodologies in this field. In alignment with this, the authors of this paper present a new approach using M.N.C and P-theorem for a nonlinear FWSIE. This method offers several advantages over similar techniques, including fewer conditions and no need to confirm the operator's mapping of a closed convex subset onto itself. The outcomes of this research are diverse and noteworthy, making it intriguing and deserving of further investigation in subsequent studies.

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