# Common Domain Of Asymptotic Stability Of A Family Of Difference Equations<sup>\*†</sup>

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#### Abstract

A necessary and sufficient condition is obtained for a family of difference equations to be asymptotically stable.

# 1. Introduction and Results

The following difference equation (see e.g. [1, 2] for its importance)

$$u_n = a u_{n-\tau} + b u_{n-\sigma}, \ n = 0, 1, 2, \dots$$
(1.1)

where a, b are real numbers and  $\tau, \sigma$  are positive integers, is said to be (globally) asymptotically stable if each of its solutions tends to zero.

When the delays  $\tau$  and  $\sigma$  are given (fixed), whether the corresponding equation (1.1) is asymptotically stable clearly depends on the coefficients a and b. For this reason, we denote the set of all pairs (x, y) such that the equation

$$u_n = x u_{n-\tau} + y u_{n-\sigma}, \ n = 0, 1, 2, \dots$$
(1.2)

is asymptotically stable by  $\Omega(x, y | \tau, \sigma)$ .

It is well known that equation (1.1) is asymptotically stable if, and only if, all the (complex) roots of its characteristic equation

$$\mathbf{l} = a\lambda^{-\tau} + b\lambda^{-\sigma},\tag{1.3}$$

are inside the open unit disk. In other words, the set  $\Omega(x, y | \tau, \sigma)$  is also the set of pairs (x, y) such that all the (complex) roots of

$$1 = x\lambda^{-\tau} + y\lambda^{-\sigma} \tag{1.4}$$

has magnitude less than one.

By means of commercial software such as the MATLAB, it is not difficult to generate domains  $\Omega(x, y|\tau, \sigma)$ in the x, y-plane for different values of the delays  $\tau$  and  $\sigma$ . It is interesting to observe that the set

$$\{(x,y)|\,|x|+|y|<1\}$$

is included in all of these computer generated domains. This motivates the following theorem.

**Theorem 1.** Let  $\Omega(x, y | \tau, \sigma)$  be the set of all pairs of the form (x, y) such that equation (1.2) is asymptotically stable. Then we have

$$\bigcap_{\tau,\sigma\in N} \Omega(x,y|\tau,\sigma) = \{(x,y)| |x| + |y| < 1\},\$$

where N is the set of all positive integers.

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One part of the proof is easy. Let  $\mu$  be a nonzero root of equation (1.3). If |a| + |b| < 1, then since

$$|a| + |b| < 1 \le |a| |\mu|^{-\tau} + |b| |\mu|^{-\sigma}$$

we see that

$$|a| < |a| |\mu|^{-\tau}$$

 $|b| < |b| |\mu|^{-\sigma}$ .

or

But then  $|\mu|^{\tau} < 1$  or  $|\mu|^{\sigma} < 1$ . In other words,  $|\mu| < 1$ .

In order to complete our proof, we need the following preparatory lemma.

**Lemma 2 (cf. [4, Lemma 2.1]).** Suppose *a*, *b* are real numbers such that  $|a| + |b| \neq 0$ , and  $\tau$  and  $\sigma$  are two positive integers. Then the equation

$$|a| x^{-\tau} + |b| x^{-\sigma} = 1, x > 0$$

has a unique solution in  $(0, \infty)$ .

**Proof.** Consider the function 
$$f(x) = |a| x^{-\tau} + |b| x^{-\sigma}, x > 0.$$

Since f is continuous on  $(0, \infty)$ ,  $\lim_{x\to 0^+} f(x) = \infty$ ,  $\lim_{x\to\infty} f(x) = 0$  and

$$f'(x) = -\left(|a|\,\tau x^{-\tau-1} + |b|\,\sigma x^{-\sigma-1}\right) < 0, \ x > 0,$$

thus our proof follows from the intermediate value theorem.  $\blacksquare$ 

## 2. Proof of Main Result

Now if (a, b) belongs to  $\cap_{\tau, \sigma \in N} \Omega(x, y | \tau, \sigma)$ , then for each pair  $(\tau, \sigma)$  of integers, each root  $\mu$  of equation (1.3) satisfies  $|\mu| < 1$ . Let us write  $\mu = re^{\theta}$  and write (1.3) in the form

$$ar^{-\tau}\cos\tau\theta + br^{-\sigma}\cos\sigma\theta = 1,\tag{2.1}$$

$$ar^{-\tau}\sin\tau\theta + br^{-\tau}\sin\sigma\theta = 0. \tag{2.2}$$

There are several cases to consider: (i) a = 0 or b = 0; (ii) a > 0, b > 0; (iii) a < 0, b < 0; (iv) a < 0, b > 0; and (v) a > 0, b < 0. The first case is easily dealt with. In the second case, since the equation

$$ax^{-\tau} + bx^{-\sigma} = 1$$

has a unique positive root  $\rho_1$  by Lemma 1,  $(r, \theta) = (\rho_1, 0)$  is a solution of equations (2.1)-(2.2). This implies that  $\rho_1 = r = |\mu| < 1$ . But then

$$1 = a\rho_1^{-\tau} + b\rho_1^{-\sigma} > a + b = |a| + |b|.$$

In the third case, since the equation

$$-ax^{-\tau} - bx^{-\sigma} = 1$$

has a unique positive root  $\rho_2$  by Lemma 1, it we pick  $\tau = 1$  and  $\sigma = 3$ , then  $(r, \theta) = (\rho_2, \pi)$  is a solution of equations (2.1)–(2.2). This implies  $\rho_2 = |\mu| < 1$ . But then

$$1 = -a\rho_2^{-\tau} - b\rho_2^{-\sigma} > -a - b = |a| + |b|.$$

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In the fourth case, since the equation

$$-ax^{-\tau} + bx^{-\sigma} = 1$$

has a unique positive root  $\rho_3$  by Lemma 1, if we pick  $\tau = 1$  and  $\sigma = 2$ , then  $(r, \theta) = (\rho_3, \pi)$  is a solution of equations (2.1)–(2.2). This implies  $\rho_3 = |\mu| < 1$ . But then

$$1 = -a\rho_3^{-\tau} + b\rho_3^{-\sigma} > -a + b = |a| + |b|.$$

In the final case, since the equation

 $ax^{-\tau} - bx^{-\sigma} = 1$ 

has a positive root  $\rho_4$ , if we pick  $\tau = 2$  and  $\sigma = 3$ , then  $(r, \theta) = (\rho_4, \pi)$  is a solution of equations (2.1)–(2.2). This implies  $\rho_4 < 1$  and consequently

$$1 \ge a\rho_4^{-\tau} - b\rho_4^{-\sigma} > a - b = |a| + |b|.$$

The proof is complete.

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