

Unique Periodic Solution Of ES-S Model*

Jin-guo Lian and Hong-kun Zhang[†]

Received 14 November 2006

Abstract

In this paper, coincidence degree method is employed to prove existence of T -periodic solutions in \mathcal{D} for a non-autonomous system which is called ES-S model, where \mathcal{D} is a strictly positively invariant region of ES-S model. Furthermore, Floquet theory is provided to analyze uniqueness of a T -periodic solution of ES-S model.

1 Introduction

Schnakeberg model [7] is

$$\begin{cases} u_t(r, t) = d_1 \Delta u(r, t) + a - u(r, t) + u^2(r, t)v(r, t), & r \in \Lambda, \\ v_t(r, t) = d_2 \Delta v(r, t) + b - u^2(r, t)v(r, t), & r \in \Lambda \end{cases}$$

with boundary conditions

$$n(r) \cdot \nabla u(r, t) = n(r) \cdot \nabla v(r, t) = 0$$

for $r \in \partial\Lambda$, where $n(r)$ is the unit outward normal vector field along the boundary of $0\Lambda = [0, l] \times [0, l]$ ($l > 0$) and a, b, d_1, d_2 are positive constants. If we consider the case when reactants are well stirred, then the diffusion terms disappear. In this case, we get the simplified Schnakeberg (S-S) model [5, p. 156]

$$\begin{cases} \dot{u} = a - u + u^2v \\ \dot{v} = b - u^2v. \end{cases}$$

If in S-S model, we allow the coefficients a and b to be positive continuous T -periodic functions of t with period $T > 0$, then the corresponding model is called ES-S model. Similarly, Schnakeberg model will be called ES model, if we replace constants a and b by positive continuous T -periodic functions.

Our goal is to concentrate on the study of periodic patterns of ES model. This is a job different from the study of pattern formation of Schnakeberg model by using Turing's Instability [5, p.380]. In order to study the pattern formation of ES model, we need to find a T -periodic solution (a source of the T -periodic pattern) for ES-S model in a certain patch.

*Mathematics Subject Classifications: 92C15, 34A34.

[†]Dept. Maths & Physics, North China Electric Power University, Baoding, Hebei, 071003, P. R. China.

2 Main Results

$$x(t) = \begin{pmatrix} u(t) \\ v(t) \end{pmatrix} \quad \text{and} \quad F(t, x(t)) = \begin{pmatrix} a - u + u^2v \\ b - u^2v \end{pmatrix}.$$

Then ES-S model is defined by

$$\dot{x}(t) = F(t, x(t)) \tag{1}$$

with conditions

$$1.1 < a(t) < 1.6, \quad 0.04 < b(t) < 0.1. \tag{2}$$

LEMMA 1. There exists a strictly positively invariant region

$$\mathcal{D} = \{(u, v) \in \mathbb{R}^2 : 1 \leq u \leq 2, 0.01 \leq v \leq 0.1\}$$

for ES-S model given by (1) with conditions (2).

Linearize the system (1) with respect to its a T -periodic solution $x(t) = (u(t), v(t))^T \in \mathcal{D}$ for any $t \in \mathbb{R}$ (if such a T -periodic solution exists), then we get

$$\dot{W}(t) = A(t)W(t), \tag{3}$$

where

$$A(t) = F'_{x(t)} = \begin{pmatrix} -1 + 2u(t)v(t) & u^2(t) \\ -2u(t)v(t) & -u^2(t) \end{pmatrix}.$$

$$W(t) = \begin{pmatrix} w_1(t) \\ w_2(t) \end{pmatrix}$$

is a variation vector field along the trajectory $x(t)$.

PROPOSITION 2. Linear system (3) satisfies $\text{tr}(A(t)) < 0$ and $\det(A(t)) > 0$ for any $t \in \mathbb{R}$.

The similar proofs of Lemma 1 and Proposition 2 are in [3]. Now, let us state the main result:

THEOREM 3. For ES-S model with conditions (2), there exists only one T -periodic solution $x_0(t)$ in \mathcal{D} .

3 Preliminaries

Let $\mathcal{X} = \{x \in C([0, T]) \mid x(0) = x(T)\}$. Clearly \mathcal{X} is a Banach space with the supremum norm. Define $Lx(t) = \dot{x}(t)$ with domain

$$\text{Dom}(L) = \{x \in C^1([0, T]) \mid x(0) = x(T)\}.$$

It is easy to verify that $\text{Dom}(L)$ is contained in \mathcal{X} , the range of L is $\text{Im}(L) = \{z(t) \in \mathcal{X} \mid \int_0^T z(t)dt = 0\}$ and L is a Fredholm mapping of index 0. Let

$$\Theta = \{x \in \text{Dom}(L) \mid x(t) \in \mathcal{D}, \quad \forall t \in [0, T]\}. \tag{4}$$

Define $\mathcal{F}_1 : \Theta \rightarrow \mathcal{X}$ by $\mathcal{F}_1(x) = F(\cdot, x(\cdot))$ and $H_1(x(t)) = \mathcal{F}_1(x(t)) - Lx(t)$.

Now, construct a homotopy family

$$H_\lambda : (Dom(L) \cap \Theta) \times [0, 1] \rightarrow \mathcal{X}$$

to be of the form

$$H_\lambda(x(t)) = \mathcal{F}_\lambda(x(t)) - Lx(t), \quad (5)$$

where $\mathcal{F}_\lambda : \Theta \times [0, 1] \rightarrow \mathcal{X}$ with

$$\mathcal{F}_\lambda(x(t)) = \begin{pmatrix} \tilde{a}(t) - u(t) + u^2(t)v(t) \\ \tilde{b}(t) - u^2(t)v(t) \end{pmatrix}. \quad (6)$$

Here $\tilde{a}(t) = (1 - \lambda)1.4 + \lambda a(t)$, and $\tilde{b}(t) = 0.05(1 - \lambda) + \lambda b(t)$ with $\lambda \in [0, 1]$. It is easy to verify that $\mathcal{F}_\lambda : \Theta \times [0, 1] \rightarrow \mathcal{X}$ is L -compact. For more details of degree theory, see [4, Ch. I-IV].

LEMMA 4. Given $\lambda \in [0, 1]$, if $x(t) \in \Theta$ is a T -periodic solution of the system

$$\dot{x}(t) = \mathcal{F}_\lambda(x(t)), \quad (7)$$

then $\partial\mathcal{D}$ is an a priori bound of $x(t)$.

PROOF. Clearly, \tilde{a} and \tilde{b} satisfy conditions (2). System (7) is an ES-S model. By Lemma 1, \mathcal{D} is still a strictly positively invariant region of system (7). None of T -periodic solutions of (7) in Θ can touch the boundary of \mathcal{D} .

COROLLARY 5. $0 \notin H_\lambda((Dom(L) \cap \partial\mathcal{D}) \times [0, 1])$.

LEMMA 6. $D_L(H_0(x(t)), \Theta) = D_B(H_0(x(t)), \mathcal{D}) = 1$, where D_L denote Leray-Schauder degree and D_B denote Brouwer degree.

For a similar proof, see [2].

LEMMA 7. For system (3) with conditions (2), zero is the only T -periodic solution.

PROOF. Suppose (3) has a non-trivial T -periodic solution called $W_1(t)$. By Proposition 2 and Floquet theory [1, p. 93-105], its orbit Γ is an orbitally asymptotically stable. For $s \in \mathbb{R}$, $sW_1(t)$ is also a T -periodic solution of (3). Then orbit of $sW_1(t)$ can not be attracted to Γ for any $s \in \mathbb{R}$. This leads a contradiction to the orbital asymptotic stability of Γ .

REMARK 8. For the linear system (3), if $tr(A(t))$ does not change sign in some simply connected region $E \subset \mathbb{R}^2$, then (3) has no non-trivial periodic solution in E ; since the system (3) is a linearization of an non-autonomous system, Bendixson's Criteria [6, p. 264] cannot be used to prove Lemma 7.

4 Proof of Theorem 3

PROOF. (**Existence**) Combine Lemma 4, Corollary 5 and Lemma 6, by a general existence theorem of the Leray-Schauder type, we get

$$D_L(H_1(x(t)), \Theta) = D_L(H_0(x(t)), \Theta) = D_B(\mathcal{F}_0(x(t)), \mathcal{D}) = 1,$$

which implies that there at least exists one T -periodic solution $x_0(t) = (u_0(t), v_0(t))^T$ of ES-S model in \mathcal{D} . If a and b are constants, it is easy to show that there is only one trivial T -periodic solution $x_0 \in \text{int}(\mathcal{D})$, otherwise, we can easily verify that $x_0(t)$ is a nontrivial T -periodic solution of ES-S model in \mathcal{D} by substituting $x_0(t)$ into ES-S model.

(Uniqueness) Define $C_T = \{x(t) \in \Theta \mid x(t) \text{ satisfies (1) with conditions (2)}\}$. Since $x_0(t) \in C_T$, C_T is not an empty set. If a and b are constants, there is only one constant solution in C_T .

If one of $a(t)$ and $b(t)$ is a non-trivial T -periodic function, then $x_0(t) \in C_T$ is a non-trivial T -periodic solution. Assume C_T is not a singleton; we pick

$$x_1(t) = \begin{pmatrix} u_1(t) \\ v_1(t) \end{pmatrix}, \quad x_2(t) = \begin{pmatrix} u_2(t) \\ v_2(t) \end{pmatrix}$$

in C_T and substitute them into (1) to get

$$\dot{x}_i(t) = F(t, x_i(t)), \quad i = 1, 2. \quad (8)$$

Define $z(t) = x_1(t) - x_2(t)$. By the mean value theorem, we get

$$\dot{z}(t) = z(t) \int_0^1 F'_x[t, x_2(t) + \theta(x_1(t) - x_2(t))]d\theta \quad (9)$$

and

$$\int_0^1 F'_x[t, x_2(t) + \theta(x_1(t) - x_2(t))]d\theta = \begin{pmatrix} -1 + 2n(t) & m(t) \\ -2n(t) & -m(t) \end{pmatrix},$$

where

$$m(t) = \int_0^1 [v_2(t) + \theta(v_1(t) - v_2(t))]^2 d\theta,$$

$$n(t) = \int_0^1 [u_2(t) + \theta(u_1(t) - u_2(t))][v_2(t) + \theta(v_1(t) - v_2(t))]d\theta.$$

Since

$$n(t) = \frac{1}{2}(v_2(t)u_1(t) + u_2(t)v_1(t)) + \frac{1}{3}(u_1(t) - u_2(t))(v_1(t) - v_2(t))$$

and

$$m(t) = \frac{1}{3}(v_1(t) - v_2(t))^2 + v_2(t)v_1(t),$$

$$\begin{aligned} \text{tr} \left(\int_0^1 F'_x[t, x_2(t) + \theta(x_1(t) - x_2(t))]d\theta \right) &= -1 - m(t) + 2n(t) \\ &= -1 - \frac{1}{3}v_1(t)^2 - \frac{1}{3}v_2(t)^2 - \frac{1}{3}v_1(t)v_2(t) \\ &\quad + \frac{1}{3}v_2(t)u_1(t) + \frac{1}{3}v_1(t)u_2(t) + \frac{2}{3}v_1(t)u_1(t) + \frac{2}{3}v_2(t)u_2(t). \end{aligned}$$

Notice the following facts:

$$\frac{1}{3}v_2(t)u_1(t) + \frac{2}{3}v_2(t)u_2(t) \leq \frac{v_2(t)}{3}(u_1(t) + 2u_2(t)) \leq 2v_2(t) \leq 0.2,$$

$$\frac{1}{3}v_1(t)u_2(t) + \frac{2}{3}v_1(t)u_1(t) \leq \frac{v_1(t)}{3}(u_2(t) + 2u_1(t)) \leq 2v_1(t) \leq 0.2.$$

It follows that

$$\text{tr} \left(\int_0^1 F'_x[t, x_2(t) + \theta(x_1(t) - x_2(t))]d\theta \right) < 0. \quad (10)$$

This implies that the zero solution is the only one T -periodic solution for (9) by Remark 8. Hence, $x_1(t) = x_2(t)$. C_T is a singleton.

5 Future Works

In this paper, we proved the existence and uniqueness of the periodic solution $x_0(t)$ of ES-S model. This establishes a foundation for further studying patterns of ES model. Of course, the problem mentioned here is still open, the investigation of this question is currently underway.

Acknowledgment. This work was supported by Research Fund of North China Electric Power University (93509001).

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