Uniqueness Of A Solution Of The Cauchy Problem For One-Dimensional Compressible Viscous Micropolar Fluid Model^{*}

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Abstract

The Cauchy problem for one-dimensional flow of a compressible viscous heatconducting micropolar fluid is considered. It is assumed that the fluid is thermodynamically perfect and polytropic. This problem has a strong solution on $\mathbf{R} \times]0, T[$ for each T > 0. We prove that the solution of the Cauchy problem is unique.

1 Statement of the problem and the main result

In this paper we consider nonstationary 1-D flow of a compressible and heat-conducting micropolar fluid. The equations of motion for this fluid are derived from the integral form of conservation laws for polar fluids, under a number of supplementary assumtions such as politropy, Fourier's law, Boyle's law and selection of constitutive equations (see [7] and [6]). The corresponding Cauchy problem has a strong solution on $\Pi = \mathbf{R} \times [0, T[$, for each T > 0 ([8]). We prove the uniqueness of the solution of this problem.

Let ρ, v, ω and θ denote, respectively, the mass density, velocity, microrotation velocity and temperature of the fluid in the Lagrangean description. Then the problem which we consider has the formulation as follows ([7]):

$$\frac{\partial \rho}{\partial t} + \rho^2 \frac{\partial v}{\partial x} = 0 , \qquad (1)$$

$$\frac{\partial v}{\partial t} = \frac{\partial}{\partial x} \left(\rho \frac{\partial v}{\partial x} \right) - K \frac{\partial}{\partial x} \left(\rho \theta \right) , \qquad (2)$$

$$\rho \frac{\partial \omega}{\partial t} = A \left[\rho \frac{\partial}{\partial x} \left(\rho \frac{\partial \omega}{\partial x} \right) - \omega \right] , \qquad (3)$$

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$$\rho \frac{\partial \theta}{\partial t} = -K\rho^2 \theta \frac{\partial v}{\partial x} + \rho^2 \left(\frac{\partial v}{\partial x}\right)^2 + \rho^2 \left(\frac{\partial \omega}{\partial x}\right)^2 + \omega^2 + D\rho \frac{\partial}{\partial x} \left(\rho \frac{\partial \theta}{\partial x}\right) \tag{4}$$

in $\mathbf{R} \times \mathbf{R}^+$, where K, A and D are positive constants. The equations (1)-(4) are, respectively, local forms of the conservation laws for the mass, momentum, momentum moment and energy. We take the following non-homogeneous initial conditions :

$$\rho(x,0) = \rho_0(x) , \qquad (5)$$

$$v(x,0) = v_0(x)$$
, (6)

$$\omega(x,0) = \omega_0(x) , \qquad (7)$$

$$\theta(x,0) = \theta_0(x) \tag{8}$$

for $x \in \mathbf{R}$. We assume that there exist $m, M \in \mathbf{R}^+$, such that

$$0 < m \le \rho_0(x) \le M, \quad m \le \theta_0(x) \le M, \quad x \in \mathbf{R} .$$
(9)

If the initial functions satisfy conditions (9) and

$$\rho_0 - 1, v_0, \omega_0, \theta_0 - 1 \in H^1(R) \tag{10}$$

then for each $T\in {\bf R}^+$ there exists a state function

$$S(x,t) = (\rho, v, \omega, \theta)(x,t) \quad (x,t) \in \Pi = \mathbf{R} \times]0, T[, \qquad (11)$$

with the properties

$$\rho - 1 \in L^{\infty}(0, T; H^1(R)) \cap H^1(\Pi), \quad \inf_{\Pi} \rho \ge c > 0, \ c \in \mathbf{R}^+,$$
(12)

$$v, \omega, \theta - 1 \in L^{\infty}(0, T; H^1(R)) \cap H^1(\Pi) \cap L^2(0, T; H^2(R))$$
 (13)

which satisfies equations (1)-(4) in the sense of distributions in Π and conditions (5)-(8) in the sense of traces (see Theorem 1.1 in [8]).

We denote by $B^k(R), k \in \mathbf{N}_0$, the Banach space

$$B^{k}(R) = \{ u \in C^{k}(R) : \lim_{|x| \to \infty} |D^{n}u(x)| = 0, \ 0 \le n \le k \},$$
(14)

where D^n is *n*-th derivative; the norm is defined by

$$||u||_{B^k(R)} = \sup_{n \le k} \{\sup_{x \in R} |D^n u(x)|\}.$$
(15)

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REMARK 1. From Sobolev's embedding theorem ([3, 5, 2]) and theory of vectorvalued distributions ([4]) one can conclude that from (12) and (13) it follows:

$$\rho - 1 \in L^{\infty}(0, T; B^0(R)) \cap C([0, T]; L^2(R)),$$
(16)

$$v, \omega, \theta - 1 \in L^2(0, T; B^1(R)) \cap C([0, T]; H^1(R)) \cap L^\infty(0, T; B^0(R))$$
 (17)

and hence

$$v, \omega \in C([0, T]; B^0(R)), \quad \rho, \theta \in L^{\infty}(\Pi).$$

$$(18)$$

The state function S and its distributional derivatives that occur in (1)-(4) are locally integrable functions in Π and the system (1)-(4) is satisfied a. e. in Π . In other words, state function (11) is a strong solution of the system (1)-(4).

The aim of this paper is to prove the following result.

THEOREM 1. For each T > 0, the problem (1)-(10) has in Π at most one solution $S = (\rho, v, \omega, \theta)$ with properties (12)-(13).

2 Proof of Theorem 1.

The proof is very similar to that of Theorem 2.1 in [7] and in [1, Chapter 2].

Let $S_1 = (\rho_1, v_1, \omega_1, \theta_1)$ and $S_2 = (\rho_2, v_2, \omega_2, \theta_2)$ be two distinct solutions of (1)-(10) with properties (12)-(13). We can easily show that for all $\varphi \in L^2(R)$ the function $(\rho, v, \omega, \theta) = (\rho_1 - \rho_2, v_1 - v_2, \omega_1 - \omega_2, \theta_1 - \theta_2)$ satisfies the following system:

$$\int_{R} \left[\frac{\partial \rho}{\partial t} + \rho_{1}^{2} \frac{\partial v}{\partial x} + \rho(\rho_{1} + \rho_{2}) \frac{\partial v_{2}}{\partial x}\right] \varphi dx = 0 , \qquad (19)$$

$$\int_{R} \left[\frac{\partial v}{\partial t} - \frac{\partial}{\partial x} \left(\rho_1 \frac{\partial v}{\partial x} + \rho \frac{\partial v_2}{\partial x}\right) + K \frac{\partial}{\partial x} (\rho_1 \theta + \rho \theta_2)\right] \varphi dx = 0 , \qquad (20)$$

$$\int_{R} \left[\frac{\partial\omega}{\partial t} - A\left(\frac{\partial}{\partial x}\left(\rho_{1}\frac{\partial\omega}{\partial x} + \rho\frac{\partial\omega_{2}}{\partial x}\right) - \frac{\omega}{\rho_{1}} + \omega_{2}\frac{\rho}{\rho_{1}\rho_{2}}\right)\right]\varphi dx = 0, \qquad (21)$$

$$\int_{R} \left[\frac{\partial \theta}{\partial t} - D \frac{\partial}{\partial x} \left(\rho_{1} \frac{\partial \theta}{\partial x} + \rho \frac{\partial \theta_{2}}{\partial x} \right) + K \left(\rho_{1} \theta \frac{\partial v_{1}}{\partial x} + \theta_{2} \rho \frac{\partial v_{1}}{\partial x} + \rho_{2} \theta_{2} \frac{\partial v}{\partial x} \right) - \rho_{1} \frac{\partial v}{\partial x} \left(\frac{\partial v_{1}}{\partial x} + \frac{\partial v_{2}}{\partial x} \right) - \rho \left(\frac{\partial v_{2}}{\partial x} \right)^{2} - \frac{\omega}{\rho_{1}} (\omega_{1} + \omega_{2}) + \omega_{2}^{2} \frac{\rho}{\rho_{1} \rho_{2}} - \rho_{1} \frac{\partial \omega}{\partial x} \left(\frac{\partial \omega_{1}}{\partial x} + \frac{\partial \omega_{2}}{\partial x} \right) - \rho \left(\frac{\partial \omega_{2}}{\partial x} \right)^{2} \right] \varphi dx = 0$$
(22)

in]0, T[. From (12)-(13) it follows

$$\rho \in L^{\infty}(0,T; H^{1}(R)) \cap H^{1}(\Pi),$$
(23)

$$v, \omega, \theta \in L^{\infty}(0, T; H^1(R)) \cap H^1(\Pi) \cap L^2(0, T; H^2(R)).$$
 (24)

Evidently, we have

$$\rho(x,0) = v(x,0) = \omega(x,0) = \theta(x,0) = 0, \ x \in \mathbf{R}.$$
(25)

From (16) and (17) we conclude that

$$\lim_{|x|\to\infty}\rho(x,t) = \lim_{|x|\to\infty}v(x,t) = \lim_{|x|\to\infty}\omega(x,t) = \lim_{|x|\to\infty}\theta(x,t) = 0,$$
 (26)

$$\lim_{|x|\to\infty}\frac{\partial v}{\partial x}(x,t) = \lim_{|x|\to\infty}\frac{\partial \omega}{\partial x}(x,t) = \lim_{|x|\to\infty}\frac{\partial \theta}{\partial x}(x,t) = 0, \ t\in]0,T[.$$
 (27)

By C > 0 we denote a generic constant, having possibly different value at different places. We also use the notation

$$||f|| = ||f||_{L^2(R)}.$$

First we replace φ by $\rho(t)$ in (19). Taking into account (18) and applying Young's inequality we get

$$\frac{d}{dt}\|\rho(t)\|^2 \le C[1+\sup_R |\frac{\partial v_2}{\partial x}|^2(\tau)]\|\rho(t)\|^2 + \|\frac{\partial v}{\partial x}(t)\|^2.$$
(28)

Integrating over $]0, t[(t \in]0, T[))$, using (25) and (17), after application of the Gronwall inequality we obtain

$$\|\rho(t)\|^2 \le C \int_0^t \|\frac{\partial v}{\partial x}(\tau)\|^2 d\tau.$$
(29)

For $\varphi = v(t)$ from (20) it follows

$$\frac{1}{2}\frac{d}{dt}\|v(t)\|^2 + \int_R \rho_1(\frac{\partial v}{\partial x})^2 dx = -\int_R \rho \frac{\partial v_1}{\partial x} \frac{\partial v}{\partial x} dx + K \int_R (\rho_1 \theta + \rho \theta_2) \frac{\partial v}{\partial x} dx.$$
(30)

Integrating again over]0, t[and using (12), (18), (25) and Hölder's inequality, we have

$$\|v(t)\|^{2} + \int_{R} \|\frac{\partial v}{\partial x}(\tau)\|^{2} d\tau \leq C \int_{0}^{t} \left[(1 + \sup_{R} |\frac{\partial v_{2}}{\partial x}|(\tau)) \|\rho(\tau)\| \|\frac{\partial v}{\partial x}(\tau)\| + \|\theta(\tau)\| \|\frac{\partial v}{\partial x}(\tau)\| \right] d\tau$$
(31)

or applying (29) and Young's inequality with a parameter $\varepsilon_i > 0$ (i = 1, 2), we find that

$$\|v(t)\|^{2} + \int_{0}^{t} \|\frac{\partial v}{\partial x}(\tau)\|^{2} d\tau \leq (\varepsilon_{1} + \varepsilon_{2}) \int_{0}^{t} \|\frac{\partial v}{\partial x}(\tau)\|^{2} d\tau$$
$$+ C \int_{0}^{t} [(1 + \sup_{R} |\frac{\partial v_{1}}{\partial x}|(\tau))^{2} (\|v(\tau)\|^{2} + \int_{0}^{\tau} \|\frac{\partial v}{\partial x}(s)\|^{2} ds) + \|\theta(\tau)\|^{2}] d\tau.$$
(32)

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Taking into account ε_i (i = 1, 2) sufficiently small and using Gronwall's inequality, from (32) we obtain

$$\|v(t)\|^2 + \int_0^t \|\frac{\partial v}{\partial x}(\tau)\|^2 d\tau \le C \int_0^t \|\theta(\tau)\|^2 d\tau$$
(33)

Now we replace φ in (21) and (22), respectively, by $\omega(t)$ and $\theta(t)$ and integrate by parts over **R**. With the help of (12), (18), (25) and the Young inequality we get

$$\|\omega(t)\|^{2} + \int_{0}^{t} \|\frac{\partial\omega}{\partial x}(\tau)\|^{2} d\tau \leq C \int_{0}^{t} [\|\omega(\tau)\|^{2} + \int_{0}^{\tau} \|\frac{\partial\omega}{\partial x}(s)\|^{2} ds + (1 + (\sup_{R} |\frac{\partial\omega_{2}}{\partial x}|)^{2}(\tau))\|\rho(\tau)\|^{2}] d\tau + \varepsilon_{1} \int_{0}^{t} \|\frac{\partial\omega}{\partial x}(\tau)\|^{2} d\tau$$
(34)

and

$$\|\theta(t)\|^{2} + \int_{0}^{t} \|\frac{\partial\theta}{\partial x}(\tau)\|^{2} d\tau \leq \int_{0}^{t} A(\tau) [\|\theta(\tau)\|^{2} + \int_{0}^{\tau} \|\frac{\partial\theta}{\partial x}(s)\|^{2} ds] d\tau + \int_{0}^{t} B(\tau) \|\rho(\tau)\|^{2} d\tau + \varepsilon_{2} \int_{0}^{t} \|\frac{\partial\theta}{\partial x}(\tau)\|^{2} d\tau + C \int_{0}^{t} [\|\frac{\partial v}{\partial x}(\tau)\|^{2} + \|\omega(\tau)\|^{2} + \|\frac{\partial\omega}{\partial x}(\tau)\|^{2}] d\tau$$
(35)

where

$$A(\tau) = C[1 + (\sup_{R} |\frac{\partial v_1}{\partial x}|)^2 + (\sup_{R} |\frac{\partial v_2}{\partial x}|)^2 + (\sup_{R} |\frac{\partial \omega_2}{\partial x}|)^2 + (\sup_{R} |\frac{\partial \omega_1}{\partial x} + \frac{\partial \omega_2}{\partial x}|)^2],$$
(36)

$$B(\tau) = C[1 + (\sup_{R} |\frac{\partial \theta_2}{\partial x}|)^2 + (\sup_{R} |\frac{\partial v_2}{\partial x}|)^2 + (\sup_{R} |\frac{\partial v_1}{\partial x}|)^2 + (\sup_{R} |\frac{\partial \omega_2}{\partial x}|)^2].$$
(37)

Taking into account (17), (29), (33) and $\varepsilon_i (i = 1, 2)$ sufficiently small, with the help of the Gronwall inequality from (34) and (35) we obtain

$$\|\omega(t)\|^2 + \int_0^t \|\frac{\partial\omega}{\partial x}(\tau)\|^2 d\tau \le C \int_0^t \|\theta(\tau)\|^2 d\tau,$$
(38)

$$\begin{aligned} \|\theta(t)\|^{2} + \int_{0}^{t} \|\frac{\partial\theta}{\partial x}(\tau)\|^{2} d\tau &\leq C \int_{0}^{t} [\|\frac{\partial v}{\partial x}(\tau)\|^{2} d\tau + \|\omega(\tau)\|^{2} + \|\frac{\partial\omega}{\partial x}(\tau)\|^{2}] d\tau \\ &\leq C \int_{0}^{t} [\|\theta(\tau)\|^{2} + \int_{0}^{\tau} \|\frac{\partial\theta}{\partial x}(s)\|^{2} ds] d\tau. \end{aligned}$$
(39)

Using again Gronwall's inequality from (39) we find that $\theta = 0$ and from (38), (33) and (29) we get immediately

$$\rho = v = \omega = 0. \tag{40}$$

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