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On A Second-Order Differential Inclusion With Constraints^{*}

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Abstract

We prove the existence of viable solutions to the Cauchy problem $x'' \in F(x,x') + f(t,x,x'), x(0) = x_0, x'(0) = y_0, x(t) \in K$, where $K \subset \mathbb{R}^n$ is a closed set, F is a set-valued map contained in the Fréchet subdifferential of a ϕ - convex function of order two and f is a Carathéodory map.

1 Introduction

In this note we consider the second order differential inclusions of the form

$$x'' \in F(x, x') + f(t, x, x'), \quad x(0) = x_0, x'(0) = y_0, \tag{1}$$

where $F(.,.): D \subset \mathbb{R}^n \times \mathbb{R}^n \to \mathcal{P}(\mathbb{R}^n)$ is a given set-valued map, $f(.,.,.): D_1 \subset \mathbb{R} \times \mathbb{R}^n \times \mathbb{R}^n \to \mathcal{P}(\mathbb{R}^n)$ is a given function and $x_0, y_0 \in \mathbb{R}^n$.

Existence of solutions of problem (1.1) that satisfy a constraint of the form $x(t) \in K$, $\forall t$, well known as viable solutions, has been studied by many authors, mainly in the case when the multifunction is convex valued and $f \equiv 0$ ([2], [6], [8], [10] etc.).

Recently in [1], the situation when the multifunction is not convex valued is considered. More exactly, in [1] it is proved the existence of viable solutions of the problem (1) when F(.,.) is an upper semicontinuous, compact valued multifunction contained in the subdifferential of a proper convex function. The result in [1] extends the result in [9] obtained for problems without constraints (i.e., $K = R^n$).

The aim of this note is to prove existence of viable solutions of the problem (1) in the case when the set-valued map F(.,.) is upper semicontinuous compact valued and contained in the Fréchet subdifferential of a ϕ - convex function of order two.

On one hand, since the class of proper convex functions is strictly contained into the class of ϕ - convex functions of order two, our result generalizes the result in [1]. On the other hand, our result may be considered as an extension of our previous viability result for second-order nonconvex differential inclusions in [5] obtained for a problem without perturbations (i.e., $f \equiv 0$).

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The proof of our result follows the general ideas in [1] and [5]. We note that in the proof we pointed out only the differences that appeared with respect to the other approaches.

The paper is organized as follows: in Section 2 we recall some preliminary facts that we need in the sequel and in Section 3 we prove our main result.

2 Preliminaries

We denote by $\mathcal{P}(\mathbb{R}^n)$ the set of all subsets of \mathbb{R}^n and by \mathbb{R}_+ the set of all positive real numbers. For $\epsilon > 0$ we put $B(x, \epsilon) = \{y \in \mathbb{R}^n; ||y - x|| < \epsilon\}$ and $\overline{B}(x, \epsilon) = \{y \in \mathbb{R}^n; ||y - x|| \le \epsilon\}$. With B we denote the unit ball in \mathbb{R}^n . By cl(A) we denote the closure of the set $A \subset \mathbb{R}^n$, by co(A) we denote the convex hull of A and we put $||A|| = \sup\{||a||; a \in A\}$.

Let $\Omega \subset \mathbb{R}^n$ be an open set and let $V : \Omega \to \mathbb{R} \cup \{+\infty\}$ be a function with domain $D(V) = \{x \in \mathbb{R}^n; V(x) < +\infty\}.$

DEFINITION 2.1. The multifunction $\partial_F V : \Omega \to \mathcal{P}(\mathbb{R}^n)$, defined as:

$$\partial_F V(x) = \{ \alpha \in \mathbb{R}^n, \liminf_{y \to x} \frac{V(y) - V(x) - \langle \alpha, y - x \rangle}{||y - x||} \ge 0 \} \text{ if } V(x) < +\infty$$

and $\partial_F V(x) = \emptyset$ if $V(x) = +\infty$ is called the *Fréchet subdifferential* of V.

According to [4] the values of $\partial_F V$ are closed and convex.

DEFINITION 2.2. Let $V : \Omega \to R \cup \{+\infty\}$ be a lower semicontinuous function. We say that V is a ϕ -convex of order 2 if there exists a continuous map $\phi_V : (D(V))^2 \times R^2 \to R_+$ such that for every $x, y \in D(\partial_F V)$ and every $\alpha \in \partial_F V(x)$ we have

$$V(y) \ge V(x) + \langle \alpha, x - y \rangle - \phi_V(x, y, V(x), V(y))(1 + ||\alpha||^2)||x - y||^2.$$
(2)

In [4], [7] there are several examples and properties of such maps. For example, according to [4], if $M \subset \mathbb{R}^2$ is a closed and bounded domain, whose boundary is a \mathbb{C}^2 regular Jordan curve, the indicator function of M

$$V(x) = I_M(x) = \begin{cases} 0, & \text{if } x \in M \\ +\infty, & \text{otherwise} \end{cases}$$

is ϕ - convex of order 2.

In what follows we assume the next assumptions.

HYPOTHESIS 2.3. i) $\Omega = K \times 0$, where $K \subset \mathbb{R}^n$ is a closed set and $O \subset \mathbb{R}^n$ is a nonempty open set.

ii) $F(.,.): \Omega \to \mathcal{P}(\mathbb{R}^n)$ is upper semicontinuous (i.e., $\forall z \in \Omega, \forall \epsilon > 0$ there exists $\delta > 0$ such that $||z - z'|| < \delta$ implies $F(z') \subset F(z) + \epsilon B$) with compact values.

iii) $f(.,.,.): R \times \Omega \to R^n$ is a Carathèodory function, i.e., $\forall (x, y) \in \Omega, t \to f(t, x, y)$ is measurable, for all $t \in R$ f(t,.) is continuous and there exists $m(.) \in L^2(R, R_+)$ such that $||f(t, x, y)|| \le m(t) \ \forall (t, x, y) \in R \times \Omega$.

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iv) For all $(t, x, v) \in \mathbb{R} \times \Omega$, there exists $w \in F(x, v)$ such that

$$\liminf_{h \to 0} \frac{1}{h^2} d(x + hv + \frac{h^2}{2}w + \int_t^{t+h} f(s, x, v) ds, K) = 0.$$

v) There exists a proper lower semicontinuous ϕ - convex function of order two $V: \mathbb{R}^n \to \mathbb{R} \cup \{+\infty\}$ such that

$$F(x,y) \subset \partial_F V(y), \quad \forall (x,y) \in \Omega.$$

3 The Mmain Result

In order to prove our result we need the following lemmas.

LEMMA 3.1 ([1]). Assume that Hypotheses 2.3 i)-iv) are satisfied. Consider $(x_0, y_0) \in \Omega, r > 0$ such that $B(x_0, r) \subset O, M := \sup\{||F(t, x)||; (t, x) \in \Omega_0 := [K \times \overline{B}(y_0, r)] \cap \overline{B}((x_0, y_0), r)\}, T_1 > 0$ such that $\int_0^{T_1} (m(s) + M + 1) < \frac{r}{3}, T_2 = \min\{\frac{r}{3(M+1)}, \frac{2r}{3(||y_0||+r)}\}$ and $T \in (0, \min\{T_1, T_2\})$. Then for every $\epsilon > 0$ there exists $\eta \in (0, \epsilon)$ and $p \geq 1$ such that for all i = 1, ..., p - 1 there exists $(h_i, (x_i, y_i), w_i) \in [\eta, \epsilon] \times \Omega_0 \times \mathbb{R}^n$ with the following properties

$$x_{i} = x_{i-1} + h_{i-1}y_{i-1} + \frac{h_{i-1}^{2}}{2}w_{i-1} + \int_{h_{i-2}}^{h_{i-2} + h_{i-1}} f(s, x_{i-1}, y_{i-1})ds \in K,$$

$$y_{i} = y_{i-1} + h_{i-1}w_{i-1}, \quad w_{i} \in F(x_{i}, y_{i}) + \frac{\epsilon}{T}B,$$

and

$$(x_i, y_i) \in \Omega_0, \quad \sum_{i=0}^{p-1} h_i < T \le \sum_{i=0}^p h_i.$$

Moreover, for $\epsilon > 0$ sufficiently small we have $\sum_{i=0}^{p-1} \frac{h_i^2}{2} \le \sum_{i=0}^{p-1} h_i < T$.

For $k \ge 1$ and q = 1, ..., p denote by h_q^k the real number associated to $\epsilon = \frac{1}{k}$ and $(t, x, y) = (h_{q-1}^k, x_q, y_q)$ given by Lemma 3.1. Define $t_k^0 = 0, t_k^p = T, t_p^q = h_0^k + ... + h_{q-1}^k$ and consider the sequence $x_k(.) : [t_k^{q-1}, t_k^q] \to R^n, k \ge 1$ defined by

 $x_k(0) = x_0,$

$$x_k(t) = x_{q-1} + (t - t_k^{q-1})y_{q-1} + \frac{1}{2}(t - t_k^{q-1})^2 w_{q-1} + \int_{t_k^{q-1}}^t (t - s)f(s, x_{q-1}, y_{q-1})ds.$$

LEMMA 3.2 ([1]). Assume that Hypotheses 2.3 i)-iv) are satisfied and consider $x_k(.)$ the sequence constructed above. Then there exists a subsequence, still denoted by $x_k(.)$ and an absolutely continuous function $x(.): [0,T] \to \mathbb{R}^n$ such that

- i) $x_k(.)$ converges uniformly to x(.),
- ii) $x'_k(.)$ converges uniformly to x'(.),
- iii) $x_k''(.)$ converges weakly in $L^2([0,T], \mathbb{R}^n)$ to x''(.),

iv) The sequence $\left(\sum_{q=1}^p \int_{t_k^{q-1}}^{t_k^q} \langle x_k''(s), f(s, x_k(t_k^{q-1}), x_k'(t_k^{q-1})) \rangle ds\right)_k$ converges to $\int_0^T \langle x''(s), f(s, x(s), x'(s)) \rangle ds,$ v) For every $t \in (0, T)$ there exists $q \in \{1, ..., p\}$ such that

$$\lim_{k \to \infty} d((x_k(t), x'_k(t), x''_k(t) - f(t, x_k(t_k^{q-1}), x'_k(t_k^{q-1}))), graph(F)) = 0,$$

vi) x(.) is a solution of the convexified problem

$$x'' \in coF(x, x') + f(t, x, x'), \quad x(0) = x_0, x'(0) = v_0.$$

We are now able to prove our result.

THEOREM 3.3. Assume that Hypothesis 2.3 is satisfied. Then, for every $(x_0, y_0) \in$ Ω there exist T > 0 and $x(.) : [0,T] \to \mathbb{R}^n$ a solution of problem (1) that satisfies $x(t) \in K \ \forall t \in [0, T].$

PROOF. Let $(x_0, y_0) \in \Omega$ and consider r > 0, T > 0 as in Lemma 3.1 and $x_k(.)$: $[0,T] \to \mathbb{R}^n, x(.): [0,T] \to \mathbb{R}^n$ as in Lemma 3.2. Let ϕ_V the continuous function appearing in Definition 2.2. Since V(.) is continuous on D(V) (e.g. [7]), by possibly decreasing r one can assume that for all $y \in B(y_0, r) \cap D(V)$

$$|V(y) - V(y_0)| \le 1.$$

Set

$$S := \sup\{\phi_v(y_1, y_2, z_1, z_2); y_i \in \overline{B}(y_0, r), z_i \in [V(y_0) - 1, V(y_0) + 1], i = 1, 2\}.$$

From the statement vi) in Lemma 3.2 and Hypothesis 2.3 v it follows that for almost all $t \in [0, T]$,

$$x''(t) - f(t, x(t), x'(t)) \in \partial_F V(x'(t)).$$
(3)

Since the mapping x(.) is absolutely continuous, from (3) and Theorem 2.2 in [4] we deduce that there exists $T_3 > 0$ such that the mapping $t \to V(x'(t))$ is absolutely continuous on $[0, \min\{T, T_3\}]$ and

$$(V(x'(t)))' = \langle x''(t), x''(t) - f(t, x(t), x'(t)) \rangle \quad a.e. \ [0, \min\{T, T_3\}].$$
(4)

Without loss of generality we may assume that $T = \min\{T, T_3\}$. From (4) we have

$$V(x'(T)) - V(y_0) = \int_0^T ||x''(s)||^2 ds - \int_0^T \langle x''(s), f(s, x(s), x'(s)) \rangle ds.$$
(5)

On the other hand, for q = 1, ..., p and $t \in [t_k^{q-1}, t_k^q)$

$$x_k''(t) - f(t, x_k(t_k^{q-1}), x_k'(t_k^{q-1})) \in F(x_k(t_k^{q-1}), x_k'(t_k^{q-1})) + \frac{1}{kT}B$$

and therefore

$$x_k''(t) - f(t, x_k(t_k^{q-1}), x_k'(t_k^{q-1})) \in \partial_F V(x_k'(t_k^{q-1})) + \frac{1}{kT}B.$$

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We deduce the existence of $b_k^q \in B$ such that

$$x_k''(t) - f(t, x_k(t_k^{q-1}), x_k'(t_k^{q-1})) - \frac{b_k^q}{kT} \in \partial_F V(x_k'(t_k^{q-1})).$$

Taking into account Definition 2.2 we obtain

$$V(x'_{k}(t^{q}_{k})) - V(x'_{k}(t^{q-1}_{k})) \geq \left\langle x''_{k}(t) - f(t, x_{k}(t^{q-1}_{k}), x'_{k}(t^{q-1}_{k})) - \frac{b^{q}_{k}}{kT}, \int_{t^{q-1}_{k}}^{t^{q}_{k}} x''_{k}(s) ds \right\rangle$$
$$-\phi_{V} \left(x'_{k}(t^{q}_{k}), x'_{k}(t^{q-1}_{k}), V(x'_{k}(t^{q}_{k})), V(x'_{k}(t^{q-1}_{k})) \right)$$
$$\times \left(1 + \left\| x''_{k}(t) - f(t, x_{k}(t^{q-1}_{k}), x'_{k}(t^{q-1}_{k})) - \frac{b^{q}_{k}}{kT} \right\|^{2} \right)$$
$$\times \left\| x'_{k}(t^{q}_{k}) - x'_{k}(t^{q-1}_{k}) \right\|^{2}.$$

Using the fact that $x_k^{\prime\prime}(.)$ is constant on $[t_k^{q-1},t_k^q]$ one may write

$$\begin{split} V(x'_{k}(t^{q}_{k})) - V(x'_{k}(t^{q-1}_{k})) & \geq \int_{t^{q-1}_{k}}^{t^{q}_{k}} \langle x''_{k}(s), x''_{k}(s) \rangle \, ds - \int_{t^{q-1}_{k}}^{t^{q}_{k}} \left\langle x''_{k}(s), \frac{b^{q}_{k}}{kT} \right\rangle ds \\ & - \int_{t^{q-1}_{k}}^{t^{q}_{k}} \left\langle x''_{k}(s), f(s, x_{k}(t^{q-1}_{k}), x'_{k}(t^{q-1}_{k})) \right\rangle ds \\ & - \phi_{V} \left(x'_{k}(t^{q}_{k}), x'_{k}(t^{q-1}_{k}), V(x'_{k}(t^{q}_{k})), V(x'_{k}(t^{q-1}_{k})) \right) \\ & \times \left(1 + \left\| x''_{k}(t) - f(t, x_{k}(t^{q-1}_{k}), x'_{k}(t^{q-1}_{k})) - \frac{b^{q}_{k}}{kT} \right\|^{2} \right) \\ & \times \left\| x'_{k}(t^{q}_{k}) - x'_{k}(t^{q-1}_{k}) \right\|^{2}. \end{split}$$

By adding on q the last inequalities we get

$$V(x'_{k}(T)) - V(y_{0}) \geq \int_{0}^{T} ||x''_{k}(s)||^{2} ds + a(k) + b(k) - \sum_{q=1}^{p} \int_{t_{k}^{q-1}}^{t_{k}^{q}} \left\langle x''_{k}(s), f(s, x_{k}(t_{k}^{q-1}), x'_{k}(t_{k}^{q-1})) \right\rangle ds, \quad (6)$$

where

$$a(k) = -\sum_{q=1}^{p} \frac{1}{kT} \int_{t_{k}^{q-1}}^{t_{k}^{q}} \langle x_{k}''(s), b_{k}^{q} \rangle \, ds,$$

$$b(k) = -\sum_{q=1}^{p} \phi_{V} \left(x_{k}'(t_{k}^{q}), x_{k}'(t_{k}^{q-1}), V(x_{k}'(t_{k}^{q}))), V(x_{k}'(t_{k}^{q-1})) \right) \\ \times \left(1 + \left\| x_{k}''(t) - f(t, x_{k}(t_{k}^{q-1}), x_{k}'(t_{k}^{q-1})) - \frac{b_{k}^{q}}{kT} \right\|^{2} \right) \left\| x_{k}'(t_{k}^{q}) - x_{k}'(t_{k}^{q-1}) \right\|^{2}.$$

On the other hand, one has

$$\begin{aligned} |a(k)| &\leq \frac{1}{kT} \sum_{q=1}^{p} ||b_{k}^{q}|| \int_{t_{k}^{q-1}}^{t_{k}^{q}} ||x_{k}''(s)|| ds \\ &\leq \frac{1}{kT} \int_{0}^{T} ||x_{k}''(s)|| ds \leq \frac{1}{kT} \int_{0}^{T} [M + \frac{1}{T} + m(s)] ds \end{aligned}$$

and

$$\begin{split} |b(k)| &\leq \sum_{q=1}^{p} S(1+M^{2}) || \int_{t_{k}^{q-1}}^{t_{k}^{p}} x_{k}''(s) ds ||^{2} \\ &\leq S(1+M^{2}) \sum_{q=1}^{p} \frac{1}{k} \int_{t_{k}^{p-1}}^{t_{k}^{p}} ||x_{k}''(s)||^{2} ds \leq S(1+M^{2}) \frac{1}{k} \int_{0}^{T} ||x_{k}''(s)||^{2} ds \\ &\leq \frac{1}{k} S(1+M^{2}) \int_{0}^{T} [M + \frac{1}{T} + m(s)]^{2} ds. \end{split}$$

We infer that

$$\lim_{k \to \infty} a(k) = \lim_{k \to \infty} b(k) = 0.$$

Hence using also statement iv) in Lemma 3.2 and the continuity of the function V(.) by passing to the limit as $k \to \infty$ in (6) we obtain

$$V(x'(T)) - V(y_0) \ge \limsup_{k \to \infty} \int_0^T ||x_k''(s)||^2 ds - \int_0^T \left\langle x''(s), f(s, x_0), x'(s) \right\rangle ds.$$
(7)

Using (4) we infer that

$$\limsup_{k \to \infty} \int_0^T ||x'_k(t)||^2 dt \le \int_0^T ||x''(t)||^2 dt$$

and, since $x_k''(.)$ converges weakly in $L^2([0,T], \mathbb{R}^n)$ to x''(.), by the lower semicontinuity of the norm in $L^2([0,T], \mathbb{R}^n)$ (e.g. Prop. III.30 in [3]) we obtain that

$$\lim_{k \to \infty} \int_0^T ||x_k''(t)||^2 dt = \int_0^T ||x''(t)||^2 dt$$

i.e., $x_k''(.)$ converges strongly in $L^2([0,T], \mathbb{R}^n)$. Hence, there exists a subsequence (still denoted) $x_k''(.)$ that converges pointwise to x''(.). From the statement v) in Lemma 3.2 it follows that

$$d((x(t), x'(t), x''(t) - f(t, x(t), x'(t))), graph(F)) = 0 \quad a.e. \ [0, T].$$

and since by Hypothesis 2.4 graph(F) is closed we obtain

$$x''(t) \in F(x(t), x'(t)) + f(t, x(t), x'(t))$$
 a.e. $[0, T]$.

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In order to prove the viability constraint satisfied by x(.) fix $t \in [0, T]$. There exists a sequence $(t_k^q)_k$ such that $t = \lim_{k \to \infty} t_k^q$. But $\lim_{k \to \infty} ||x(t) - x_k(t_k^q)|| = 0$ and $x_k(t_k^q) \in K$. So the fact that K is closed gives $x(t) \in K$ and the proof is complete.

REMARK 3.4. If $V(.): \mathbb{R}^n \to \mathbb{R}$ is a proper lower semicontinuous convex function then (e.g. [7]) $\partial_F V(x) = \partial V(x)$, where $\partial V(.)$ is the subdifferential in the sense of convex analysis of V(.), and Theorem 3.3 yields the result in [1]. At the same time if in Theorem 3.3 $f \equiv 0$ then Theorem 3.3 yields the result in [5].

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